Lecture 21: Threads and Concurrency

CS 105

Spring 2024

Why Concurrent Programs?



Program Structure: expressing logically concurrent programs



Responsiveness: managing I/O devices



Responsiveness: shifting work to run in the background



Traditional View of a Process

Process = process context + (virtual) memory state

Process Control Block

Program context: Data registers Stack pointer (rsp) Condition codes Program counter (rip) Kernel context: VM structures

File table

brk pointer

 $rsp \rightarrow \qquad Stack$ $rsp \rightarrow \qquad Heap$ $brk \rightarrow \qquad Heap$ Data $rip \rightarrow \qquad Code$

Virtual Memory

Alternate View of a Process

Process = thread + other state



A Process With Multiple Threads

- Multiple threads can be associated with a process
 - Each thread has its own logical control flow
 - Each thread has its own stack for local variables
 - Each thread has its own thread id (TID)
 - Each thread shares the same code, data, and kernel context



Threads vs. Processes

- How threads and processes are similar
 - Each has its own logical control flow
 - Each can run concurrently with others (possibly on different cores)
 - Each is scheduled and context switched
- How threads and processes are different
 - Threads share all code and data (except local stacks)
 - Processes (typically) do not
 - Threads are somewhat less expensive than processes
 - Thread control (creating and reaping) is half as expensive as process control
 - ~20K cycles to create and reap a process
 - ~10K cycles (or less) to create and reap a thread
 - Thread context switches are less expensive (e.g., don't flush TLB)

Logical View of Threads

- Threads associated with process form a pool of peers
 - · Unlike processes which form a tree hierarchy



Posix Threads Interface

C (Pthreads)

- Creating and reaping threads
 - pthread_create()
 - pthread_join()
- Determining your thread ID
 - pthread_self()
- Terminating threads
 - pthread_cancel()
 - pthread_exit()
 - exit() [terminates all threads]
 - RET [terminates current thread]

Python (threading)

- Creating and reaping threads
 - Thread()
 - thread.join()
- Determining your thread ID
 - thread.get_ident()
- Terminating threads
 - thread.exit()
 - RET [terminates current thread]

The Pthreads "hello, world" Program



Example: Sharing with Threads

sharing.c

}

```
char** ptr; /* global var */
int main() {
    pthread t tid;
    char * msgs[2] = {
        "Hello from foo",
        "Hello from bar"
    };
    ptr = msqs;
    for (int i = 0; i < 2; i++) {</pre>
        pthread create(&tid, NULL,
             f1, (void*) i);
```

```
long myid = (long) vargp;
static int cnt = 0;
printf("[%d]: %s (cnt=%d)\n",
```

void* f1(void* vargp) {

```
myid, ptr[myid], ++cnt);
return NULL; /
```

Peer threads reference main thread's stack indirectly through global ptr variable

```
pthread_exit(NULL);
```

Mapping Variable Instances to Memory

- Global variables
 - Def: Variable declared outside of a function
 - Virtual memory contains exactly one instance of any global variable
- Local variables
 - Def: Variable declared inside function without static attribute
 - Each thread stack contains one instance of each local variable
- Local static variables
 - Def: Variable declared inside function with the static attribute
 - Virtual memory contains exactly one instance of any local static variable.

Mapping Variable Instances to Memory



Exercise 1: Shared Variables

```
char **ptr; /* global var */
int main() {
    pthread_t tid;
    char *msgs[2] = {"Hello from foo",
                      "Hello from bar"};
    ptr = msgs;
    for (int i = 0; i < 2; i++)
        Pthread_create(&tid, NULL,
                      thread, (void *)i);
    Pthread_exit(NULL);
}</pre>
```

```
void *thread(void *vargp) {
  long myid = (long)vargp;
  static int cnt = 0;
  printf("[%d]: %s (cnt=%d) \n",
      myid, ptr[myid], ++cnt);
  return NULL;
```

Which variables are shared?

- ptr
- cnt
- i
- msgs
- myid

Exercise 1: Shared Variables

- Which variables are shared?
 - A variable ${\bf x}$ is shared iff multiple threads reference at least one instance of ${\bf x}.$

Variable	Referenced by	Referenced by	Referenced by
instance	main thread?	peer thread 0?	peer thread 1?
ptr			
cnt			
i.main			
msgs.main			
myid.thread0			
myid.thread1			

Why not Concurrent Programs?

```
/* Global shared variable */
volatile long cnt = 0; /* Counter */
int main(int argc, char** argv) {
    long niters;
    pthread t tid1, tid2;
    niters = atoi(argv[1]);
    pthread create (&tid1, NULL,
        count func, &niters);
    pthread create (&tid2, NULL,
        count func, &niters);
    pthread join(tid1, NULL);
    pthread join(tid2, NULL);
    /* Check result */
    if (cnt != (2 * niters))
        printf("BOOM! cnt=%ld\n", cnt);
```

```
else
```

```
printf("OK cnt=%ld\n", cnt);
exit(0);
```

}

```
/* Thread routine */
void* count_func(void* vargp){
  long i, niters;
  niters = *((long*) vargp);
  for (i = 0; i < niters; i++){
    cnt++;
  }
  return NULL;
}</pre>
```

```
linux> ./badcnt 10000
OK cnt=20000
linux> ./badcnt 10000
BOOM! cnt=13051
linux>
```

Assembly Code for Counter Loop

C code for counter loop in thread i

```
for (i = 0; i < niters; i++) {
    cnt++;
}</pre>
```

Asm code for thread i

<pre>movq (%rdi), %rcx testq %rcx,%rcx jle .L2 movl \$0, %eax</pre>	H_i : Head
.L3: movq cnt(%rip),%rdx addq \$1, %rdx movq %rdx, cnt(%rip)	<pre> L_i: Load cnt U_i: Update cnt S_i: Store cnt</pre>
addq \$1, %rax cmpq %rcx, %rax jne .L3 .L2:	T_i : Tail

Race conditions

- A race condition is a timing-dependent error involving shared state
 - whether the error occurs depends on thread schedule
- program execution/schedule can be non-deterministic
- compilers and processors can re-order instructions

A concrete example...

- You and your roommate share a refrigerator. Being good roommates, you both try to make sure that the refrigerator is always stocked with milk.
- Liveness: if you are out of milk, someone buys milk
- Safety: you never have more than one quart of milk



Algorithm 1:

A problematic schedule

You

- 3:00 Look in fridge; out of milk
- 3:05 Leave for store
- 3:10 Arrive at store
- 3:15 Buy milk
- 3:20 Arrive home; put milk in fridge

Your Roommate

- 3:10 Look in fridge; out of milk
- 3:15 Leave for store
- 3:20 Arrive at store
- 3:25 Buy milk
- 3:30 Arrive home; put milk in fridge

Safety violation: You have too much milk and it spoils

Solution 1: Leave a note

 You and your roommate share a refrigerator. Being good roommates, you both try to make sure that the refrigerator is always stocked with milk.



Solution 2: Leave note before check note

 You and your roommate share a refrigerator. Being good roommates, you both try to make sure that the refrigerator is always stocked with milk.



Algorithm 3:

Solution 3: Keep checking for note

 You and your roommate share a refrigerator. Being good roommates, you both try to make sure that the refrigerator is always stocked with milk.



Algorithm 4:

Solution 4: Take turns

 You and your roommate share a refrigerator. Being good roommates, you both try to make sure that the refrigerator is always stocked with milk.



Algorithm 5:

Locks

- A lock (aka a mutex) is a synchronization primitive that provides mutual exclusion. When one thread holds a lock, no other thread can hold it.
 - a lock can be in one of two states: locked or unlocked
 - a lock is initially unlocked
 - function acquire(&lock) waits until the lock is unlocked, then atomically sets it to locked
 - function release(&lock) sets the lock to unlocked

Solution 5: use a lock

 You and your roommate share a refrigerator. Being good roommates, you both try to make sure that the refrigerator is always stocked with milk.



Atomic Operations

- Solution: hardware primitives to support synchronization
- A machine instruction that (atomically!) reads and updates a memory location
- Example: xchg *src, dest*
 - one instruction
 - semantics: TEMP ← DEST; DEST ← SRC; SRC ← TEMP;

Spinlocks

acquire:

- mov \$1, eax
 xchg eax, (rdi)
 test eax, eax
 jnz acquire
 ret
 - ; Set EAX to 1
 - ; Atomically swap EAX w/ lock val
 - ; check if EAX is 0 (lock unlocked)
 - ; if was locked, loop
 - ; lock has been acquired, return

release:

mov \$0, eax xchg eax, (rdi) ret

- ; Set EAX to 0 ; Atomically swap EAX w/ lock val
 - ; lock has been released, return

Programming with Locks

C (pthreads)

- Defines lock type pthread_mutex_t
- functions to create/destroy locks:
 - int pthread_mutex_init(&lock, attr);
 - int pthread_mutex_destroy(&lock);
- functions to acquire/release lock:
 - int pthread_mutex_lock(&lock);
 - int pthread_mutex_unlock(&lock);

Python (threading)

- Defines class Lock
- constructor to create locks:
 - Lock()
 - destroyed by garbage collector
- functions to aquire/release lock:
 - lock.acquire()
 - lock.release()

Exercise 2: Locks

```
/* Global shared variable */
volatile long cnt = 0; /* Counter */
```

```
int main(int argc, char **argv)
```

```
long niters;
pthread_t tid1, tid2;
```

```
niters = atoi(argv[1]);
Pthread_create(&tid1, NULL,
        thread, &niters);
Pthread_create(&tid2, NULL,
        thread, &niters);
Pthread_join(tid1, NULL);
Pthread_join(tid2, NULL);
```

```
/* Check result */
if (cnt != (2 * niters))
    printf("BOOM! cnt=%ld\n", cnt);
else
    printf("OK cnt=%ld\n", cnt);
exit(0);
```

• TODO: Modify this example to guarantee correctness

{

Problems with Locks

- 1. Locks are slow
 - threads that fail to acquire a lock on the first attempt must "spin", which wastes CPU cycles
 - threads get scheduled and de-scheduled while the lock is still locked
- 2. Using locks correctly is hard
 - hard to ensure all race conditions are eliminated
 - easy to introduce synchronization bugs (deadlock, livelock)

Better Synchronization Primitives

- Semaphores
 - stateful synchronization primitive
- Condition variables
 - event-based synchronization primitive