Lecture 22: Semaphores and Conditional Variables

CS 105

Problems with Locks

- Problem 1: Correct Synchronization with Locks is Hard
- Problem 2: Locks are Slow
 - threads that fail to acquire a lock on the first attempt must "spin", which wastes CPU cycles
 - replace no-op with yield()
 - threads get scheduled and de-scheduled while the lock is still locked
 - need a better synchronization primitive

Semaphores

- A semaphore s is a stateful synchronization primitive comprised of:
 - a value n (non-negative integer)
 - a lock
 - a queue
- Interface:
 - init(sem_t * s, unsigned int val)
 - P(sem_t * s): If s is nonzero, the P decrements s and returns immediately. If s is zero, then adds the thread to queue(s); after restarting, the P operation decrements s and returns.
 - V(sem_t * s): Increments s by 1. If there are any threads in queue(s), then V restarts exactly one of these threads, which then completes the P operation.

Semantics of P and V

- P(sem_t * s)
 - block (suspend thread) until value n > 0
 - when n > 0, decrement n by one

- V(sem_t * s)
 - increment value n b 1
 - resume a thread waiting on s (if any)

Why P and V?

- Edsger Dijkstra was from the Netherlands
 - P comes from the Dutch word proberen (to test)
 - V comes from the Dutch word verhogen (to increment)
- Better names than the alternatives
 - decrement_or_if_value_is_zero_block_then_decrement_after_waking
 - increment_and_wake_a_waiting_process_if_any

Binary Semaphore (aka mutex)

- A binary semaphore is a semaphore whose value is always 0 or 1
- Used for mutual exclusion---it's a more efficient lock!



Example: Shared counter



Example: Shared counter



Exercise 1: Semaphores

• What would be the value in the semaphore at the four bad points?



Example: Synchronization Barrier

- With data parallel programming, a computation proceeds in parallel, with each thread operating on a different section of the data. Once all threads have completed, they can safely use each others results.
 - MapReduce is an example of this!
- To do this safely, we need a way to check whether all n threads have completed.

```
volatile int results = 0;
volatile int done_count = 0;
sem_t count_mutex;
sem_init(&count_mutex, 1)
sem_t barrier;
sem_init(&barrier, 0)
```

```
void *thread(void *args) {
    parallel_computation(args);
```

```
P(&count_mutex);
done_count++;
V(&count_mutex);
if(done count == n){
```

```
V(&barrier);
}
P(&barrier);
V(&barrier);
use_results();
```

Counting Semaphores

- A semaphore with a value that goes above 1 is called a counting semaphore
- Provide a more flexible primitive for mediating access to shared resources

Example: Bounded Buffers



finite capacity (e.g. 20 loaves) implemented as a queue



Threads A: produce loaves of bread and put them in the queue



Threads B: consume loaves by taking them off the queue

Example: Bounded Buffers



finite capacity (e.g. 20 loaves) implemented as a queue

Separation of concerns:

1. How do you implement a bounded buffer?

2. How do you synchronize concurrent access to a bounded buffer?



Threads A: produce loaves of bread and put them in the queue



Threads B: consume loaves by taking them off the queue

```
Example: Bounded Buffers
         1
              2
                  3 \quad 4 \quad 5 \quad (n=6)
       ()
                  2
                          1
  b
       3
                      4
                                       Values wrap around!!
                 front
         rear
typedef struct {
    int *b; // ptr to buffer containing the queue
    int n; // length of array (max # slots)
    int front; // index of first element, 0 <= front < n</pre>
    int rear; // (index of last elem)+1 % n, 0 <= rear < n</pre>
} bbuf t
void init(bbuf t * ptr, int n){
                                    void put(bbuf t * ptr, int val){
                                      ptr->b[ptr->rear]= val;
  ptr->b = malloc(n*sizeof(int));
 ptr->n = n;
                                      ptr->rear= ((ptr->rear)+1)%(ptr->n);
  ptr->front = 0;
                                    }
  ptr - rear = 0;
                                    int get(bbuf_t * ptr){
}
                                      int val= ptr->b[ptr->front];
                                      ptr->front= ((ptr->front)+1)%(ptr->n);
                                      return val;
                  Exercise 2: What can go wrong?
```

Example: Bounded Buffers 3 2 4 5 (n=6)() 3 b 2 1 4 front rear void put(bbuf_t * ptr, int val){ typedef struct { P(&(ptr->slots)) int *b; P(&(ptr->mutex)) int n; ptr->b[ptr->rear]= val; int front; ptr->rear= ((ptr->rear)+1)%(ptr->n); int rear; V(&(ptr->mutex)) sem t mutex; V(&(ptr->items)) sem t slots; sem t items; } bbuf t void init(bbuf_t * ptr, int n){ int get(bbuf_t * ptr){ ptr->b = malloc(n*sizeof(int)); P(&(ptr->items)) P(&(ptr->mutex)) ptr->n = n;int val= ptr->b[ptr->front]; ptr->front = 0;ptr->front= ((ptr->front)+1)%(ptr->n); $ptr \rightarrow rear = 0;$ sem init(&mutex, 1); V(&(ptr->mutex)) sem_init(&slots, n); V(&(ptr->slots)) sem init(&items, 0); return val;

Exercise 3: Readers/Writers

- Consider a collection of concurrent threads that have access to a shared object
- Some threads are readers, some threads are writers
 - a unlimited number of readers can access the object at same time
 - a writer must have exclusive access to the object

```
// global variables
                                           void init(){
                                                sem init(&num lock, 1);
int num readers = 0;
sem t num lock;
                                                sem init(&ojb lock, 1);
sem t ojb lock;
                                           }
int reader(void *shared){
                                           void writer(void *shared, int val){
    P(&num lock);
                                               P(&ojb lock);
                                               write(shared, val);
    num readers++;
    if(num readers == 1)
                                               V(&ojb lock);
        P(&obj lock);
    V(&num lock);
    int x = read(shared);
    P(&num lock);
    num readers--;
    if(num readers == 0)
        V(&obj lock);
    V(&num lock);
    return x
}
                                           }
```

Programming with Semaphores

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- Semaphore type: sem_t
- Initialization:

```
sem_wait(sem_t * s)
```

• V

```
sem_post(sem_t * s)
```

Python

- Semaphore type: class Semaphore
- Initialization:
 - s = Semaphore(value)

- P
 - s.acquire()
- V
 - s.release()

Limitations of Semaphores

- semaphores are a very spartan mechanism
 - they are simple, and have few features
 - more designed for proofs than synchronization
- they lack many practical synchronization features
 - it is easy to deadlock with semaphores
 - one cannot check the lock without blocking
- strange interactions with OS scheduling (priority inheritance)

Condition Variables

- A condition variable cv is a stateless synchronization primitive that is used in combination with locks (mutexes)
 - condition variables allow threads to efficiently wait for a change to the shared state protected by the lock
 - a condition variable is comprised of a waitlist
- Interface:
 - wait(CV * cv, Lock * lock): Atomically releases the lock, suspends execution of the calling thread, and places that thread on cv's waitlist; after the thread is awoken, it re-acquires the lock before wait returns
 - signal(CV * cv): takes one thread off of cv's waitlist and marks it as eligible to run. (No-op if waitlist is empty.)
 - broadcast(CV * cv): takes all threads off cv's waitlist and marks them as eligible to run. (No-op if waitlist is empty.)

Using Condition Variables

- 1. Add a lock. Each shared value needs a lock to enforce mutually exclusive access to the shared value.
- 2. Add code to acquire and release the lock. All code access the shared value must hold the objects lock.
- Identify and add condition variables. A good rule of thumb is to add a condition variable for each situation in a function must wait for.
- 4. Add loops to wait. Threads might not be scheduled immediately after they are eligible to run. Even if a condition was true when signal/broadcast was called, it might not be true when a thread resumes execution.

Example: Synchronization Barrier

}

- With data parallel programming, a computation proceeds in parallel, with each thread operating on a different section of the data. Once all threads have completed, they can safely use each others results.
 - MapReduce is an example of this!
- To do this safely, we need a way to check whether all n threads have completed.

```
int done_count = 0;
Lock lock;
CV all done;
```

```
/* Thread routine */
void *thread(void *args)
{
    parallel_computation(args)
    acquire(&lock);
    done_count++;
    if(done_count < n){
        wait(&all_done, &lock);
    } else {
        broadcast(&all_done);
    }
    release(&lock);
    use_results();
}</pre>
```

Exercise 4: Readers/Writers

- Consider a collection of concurrent threads that have access to a shared object
- Some threads are readers, some threads are writers
 - a unlimited number of readers can access the object at same time
 - a writer must have exclusive access to the object

```
int num readers = 0;
                     int num writers = 0;
                     Lock lock;
                     CV readable;
int reader(void *sha CV writeable;
                                           void writer(void *shared, int val){
    acquire(&lock);
                                               acquire(&lock);
    while(num writers > 0)
                                               while(num readers > 0)
        wait(readable, &lock);
                                                   wait(writeable, &lock);
    num readers++;
                                               num writers=1;
    release(&lock);
                                               release(&lock);
    int x = read(shared);
                                               write(shared, val);
    acquire(&lock);
                                               acquire(&lock);
    num readers--;
                                               num writers=0;
    if(num readers == 0)
                                               signal(writeable);
        signal(writeable);
                                               broadcast(readable);
    release(&lock);
                                               release(&lock);
    return x
                                           }
```

Programming with CVs

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Initialization:

pthread_mutex_t lock =

PTHREAD_MUTEX_INITIALIZER; pthread_cond_t cv =

PTHREAD_COND_INITIALIZER;

Lock acquire/release:

pthread_mutex_lock(&lock);
pthread_mutex_unlock(&lock);

CV operations:

pthread_cond_wait(&cv, &lock);
pthread_cond_signal(&cv);
pthread_cond_broadcast(&cv);

Python

Initialization:

lock = Lock()
cv = Condition(lock)

• Lock acquire/release: lock.acquire() lock.release()

• V

```
cv.wait()
cv.notify()
cv.notify_all()
```

Exercise 5: Feedback

- 1. Rate how well you think this recorded lecture worked
 - 1. Better than an in-person class
 - 2. About as well as an in-person class
 - 3. Less well than an in-person class, but you still learned something
 - 4. Total waste of time, you didn't learn anything
- 2. How much time did you spend on this video (including exercises)?
- 3. Do you have any particular questions you'd like me to address in this week's problem session?
- 4. Do you have any other comments or feedback?