

Basic probability theory: terminology

An experiment has a set of potential outcomes, e.g., throw a die, "look at" another example $\$

The sample space of an experiment is the set of all possible outcomes, e.g., $\{1, 2, 3, 4, 5, 6\}$

For machine learning the sample spaces can be very large

Basic probability theory: terminology

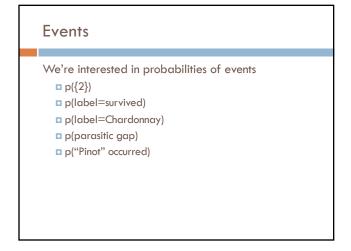
An event is a subset of the sample space

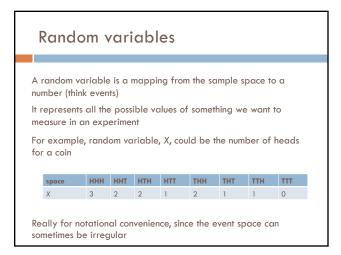
Dice rolls

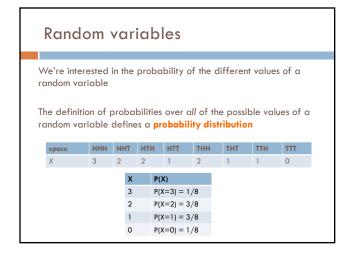
- {2}
- **□** {3, 6}
- □ even = {2, 4, 6}
- odd = $\{1, 3, 5\}$

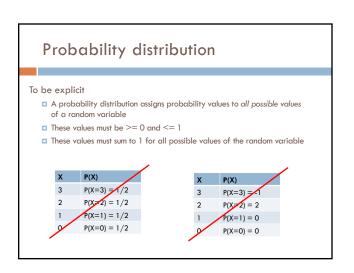
Machine learning

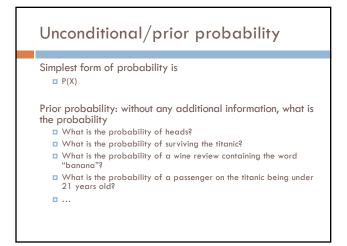
- A particular feature has particular values
- An example, i.e. a particular setting of feature values
- □ label = Chardonnay

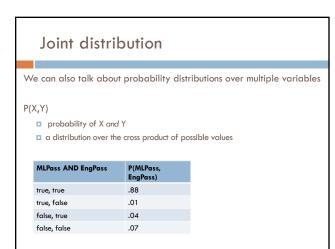


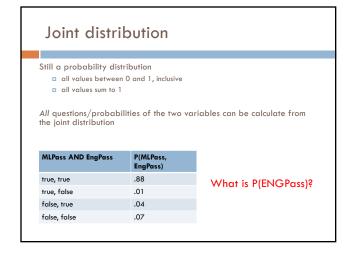


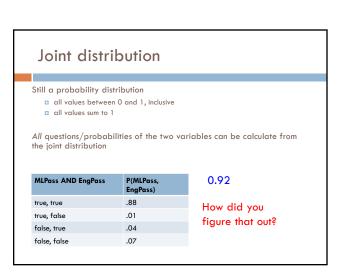


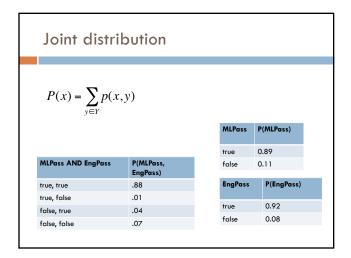


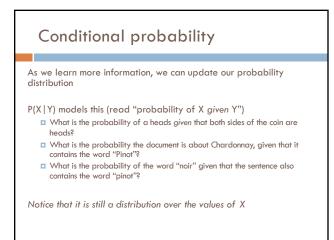


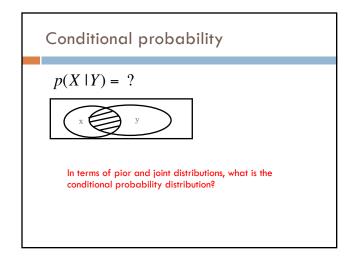


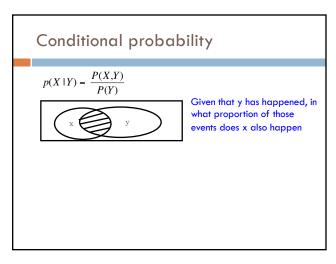


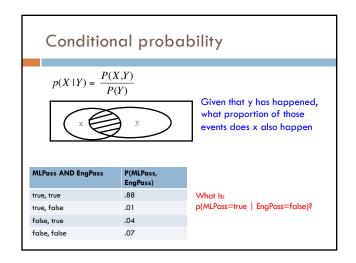


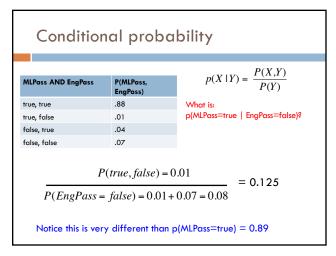


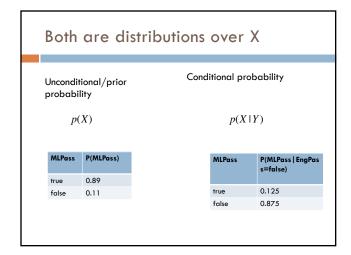


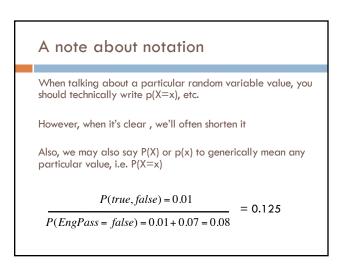






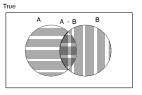






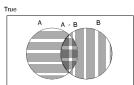
Properties of probabilities

P(A or B) = ?



Properties of probabilities

$$P(A \text{ or } B) = P(A) + P(B) - P(A,B)$$



Properties of probabilities

$$P(\neg E) = 1 - P(E)$$

More generally:

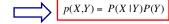
■ Given events $E = e_1, e_2, ..., e_n$

$$p(e_i) = 1 - \sum_{j=1:n, j \neq i} p(e_j)$$

 $P(E1, E2) \leq P(E1)$

Chain rule (aka product rule)

$$p(X \mid Y) = \frac{P(X,Y)}{P(Y)}$$



We can view calculating the probability of X AND Y occurring as two steps:

- 1. Y occurs with some probability P(Y)
- 2. Then, \boldsymbol{X} occurs, given that \boldsymbol{Y} has occurred

or you can just trust the math... \odot

Chain rule

 $p(X,Y,Z) = P(X \mid Y,Z)P(Y,Z)$

 $p(X,Y,Z) = P(X,Y \mid Z)P(Z)$

 $p(X,Y,Z) = P(X \mid Y,Z)P(Y \mid Z)P(Z)$

 $p(X,Y,Z) = P(Y,Z \mid X)P(X)$

$$p(X_1, X_2, ..., X_n) = ?$$

Applications of the chain rule

We saw that we could calculate the individual prior probabilities using the joint distribution

$$p(x) = \sum_{y \in Y} p(x, y)$$

What if we don't have the joint distribution, but do have conditional probability information:

■ P(Y)

■ P(X | Y)

$$p(x) = \sum_{y \in Y} p(y) p(x \mid y)$$

This is called "summing over" or "marginalizing out" a variable

Bayes' rule (theorem)

$$p(X \mid Y) = \frac{P(X,Y)}{P(Y)} \qquad \qquad p(X,Y) = P(X \mid Y)P(Y)$$

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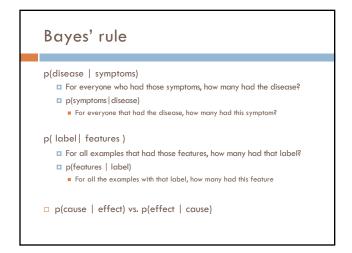
Bayes' rule

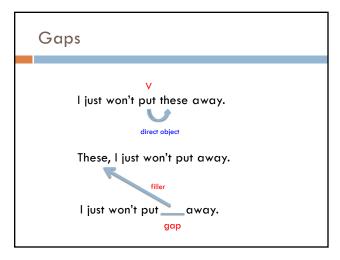
Allows us to talk about P(Y | X) rather than P(X | Y)

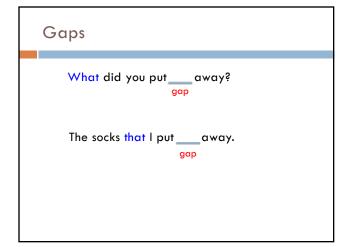
Sometimes this can be more intuitive

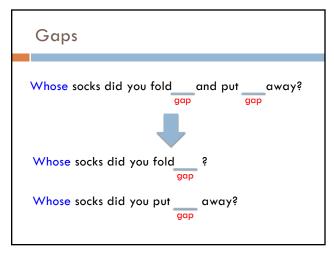
Why?

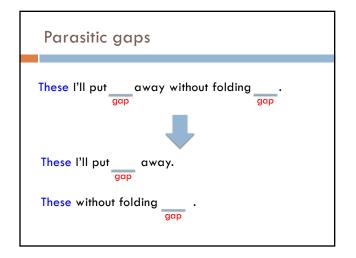
$$p(X \mid Y) = \frac{P(Y \mid X)P(X)}{P(Y)}$$













Parasitic gaps

http://literalminded.wordpress.com/2009/02/10/dougs-parasitic-gap/

Frequency of parasitic gaps

Parasitic gaps occur on average in 1/100,000 sentences

Problem:

Your friend has developed a machine learning approach to identify parasitic gaps. If a sentence has a parasitic gap, it correctly identifies it 95% of the time. If it doesn't, it will incorrectly say it does with probability 0.005. Suppose we run it on a sentence and the algorithm says it is a parasitic gap, what is the probability it actually is?

Prob of parasitic gaps

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G = gap T = test positive

What question do we want to ask?

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$$p(g \mid t) = ?$$

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G = gap T = test positive

$$p(g \mid t) = \frac{p(t \mid g)p(g)}{p(t)}$$

$$= \frac{p(t \mid g)p(g)}{\sum_{g \in G} p(g)p(t \mid g)} = \frac{p(t \mid g)p(g)}{p(g)p(t \mid g) + p(\overline{g})p(t \mid \overline{g})}$$

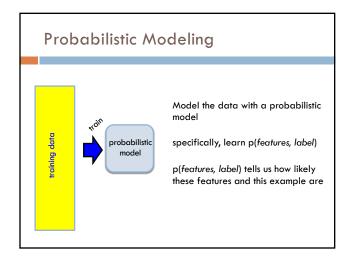
Prob of parasitic gaps

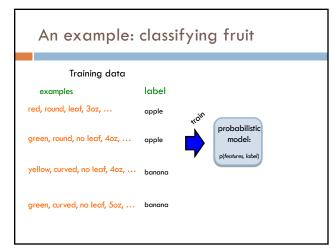
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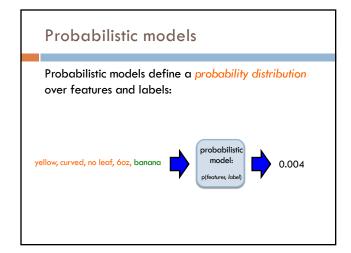
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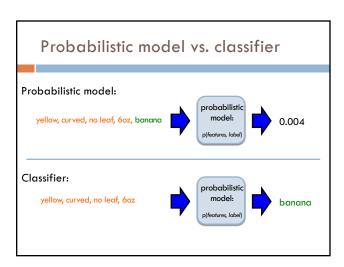
$$p(g \mid t) = \frac{p(t \mid g)p(g)}{p(g)p(t \mid g) + p(\overline{g})p(t \mid \overline{g})}$$

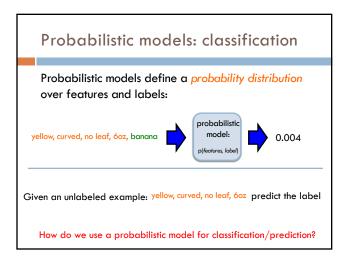
$$= \frac{0.95 * 0.00001}{0.00001 * 0.95 + 0.99999 * 0.005} \approx 0.002$$

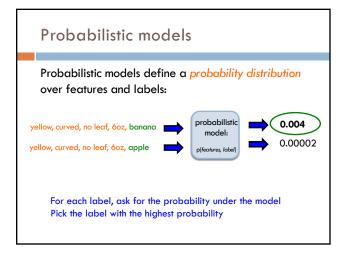


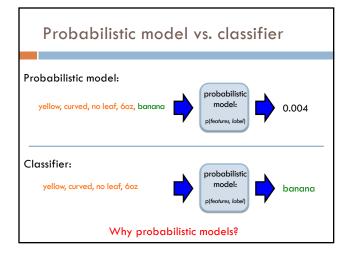


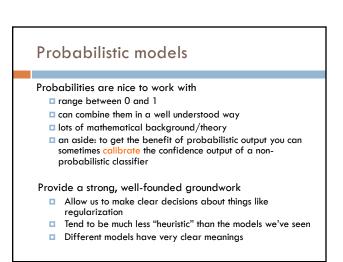












Probabilistic models: big questions

Which model do we use, i.e. how do we calculate p(feature, label)?

How do train the model, i.e. how to we we estimate the probabilities for the model?

How do we deal with overfitting?

Same problems we've been dealing with so far

Probabilistic models

Which model do we use, i.e. how do we calculate p(feature, label)?

How do train the model, i.e. how to we we estimate the probabilities for the model?

How do we deal with overfitting?

ML in general

Which model do we use (decision tree, linear model, non-parametric)

How do train the model?

How do we deal with overfitting?

Basic steps for probabilistic modeling

Step 1: pick a model

Step 2: figure out how to estimate the probabilities for the model

Step 3 (optional): deal with overfitting

Probabilistic models

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Basic steps for probabilistic modeling

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Step 2: figure out how to estimate the probabilities for the model

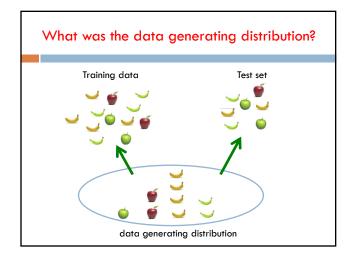
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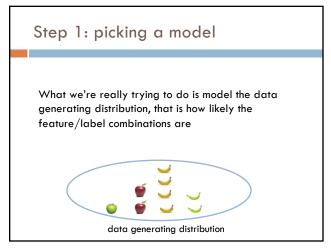
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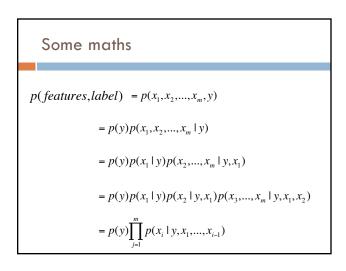
How do train the model, i.e. how to we we estimate the probabilities for the model?

How do we deal with overfitting?





Some maths $p(features, label) = p(x_1, x_2, ..., x_m, y)$ $= p(y)p(x_1, x_2, ..., x_m \mid y)$ What rule?



Step 1: pick a model

 $p(features, label) = p(y) \prod_{i=1}^{m} p(x_i | y, x_1, ..., x_{i-1})$

So, far we have made NO assumptions about the data

$$p(x_m | y, x_1, x_2, ..., x_{m-1})$$

How many entries would the probability distribution table have if we tried to represent all possible values (e.g. for the wine data set)?

Full distribution tables ... 0 0 0 0 0 0 0 0 0 0 0 ... 0 0 Wine problem: all possible combination of features ■ ~7000 binary features ■ Sample space size: $2^{7000} = ?$

27000

1421096755662202026466660854783770951911124303637432562359820841515270231627023529870802237879
4460004651996019099530984538625578925465132041070221102535646586474318852270765599373340842842
72242011228185782600729310826170431944842665920077784125099998860169430006650011209817579296787
8190255237700655579477526476555809293846027218604216108862200816907132974749043538784101108162
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Any problems with this?