

CS062

DATA STRUCTURES AND ADVANCED PROGRAMMING

35–36: Directed Graphs



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LECTURES

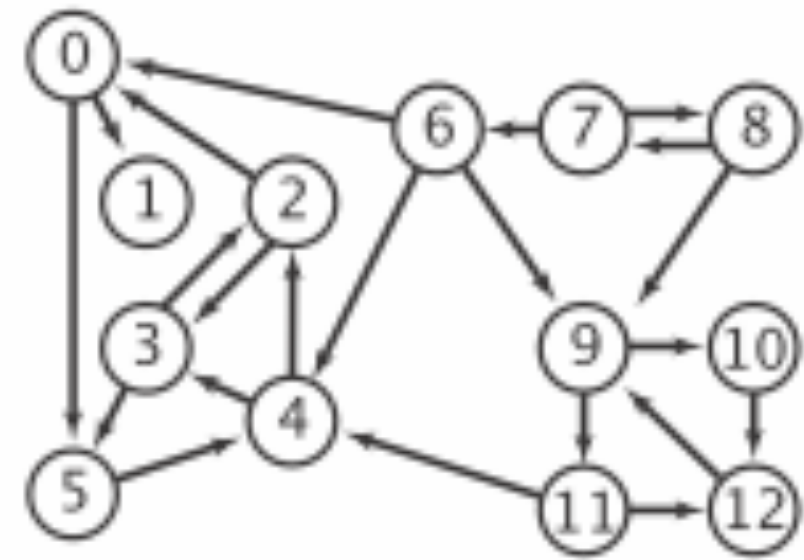


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Lecture 35-36: Directed Graphs

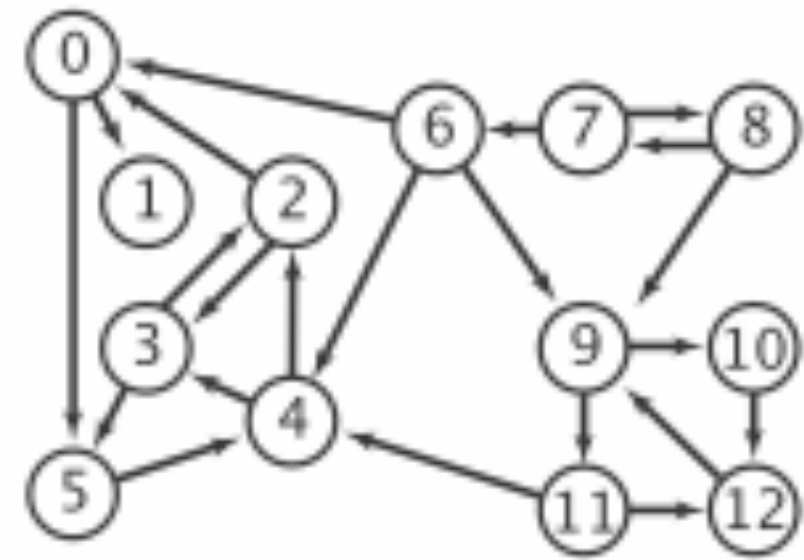
- ▶ Introduction to Directed Graphs
- ▶ Digraph API
- ▶ Depth-First Search
- ▶ Breadth-First Search
- ▶ Topological Sort
- ▶ Strongly Connected Components

Directed Graph Terminology

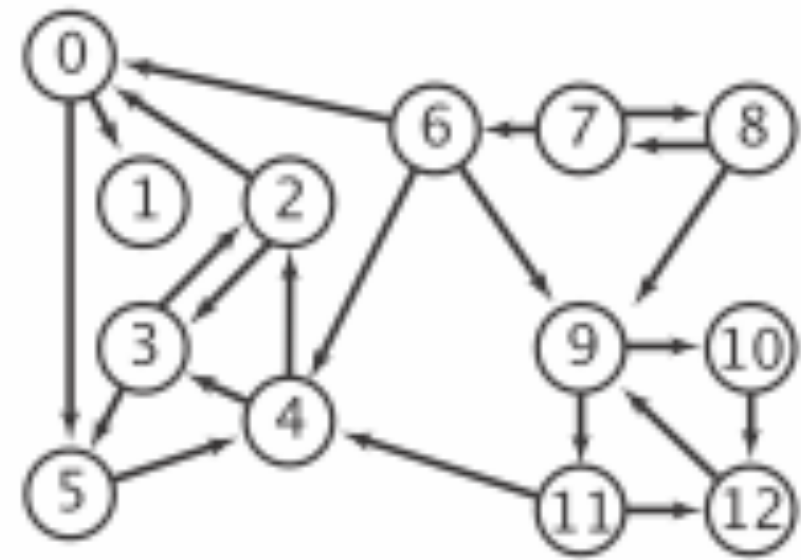


- ▶ **Directed Graph (or digraph)** : set of **vertices** V connected pairwise by a set of **directed edges** E .
 - ▶ E.g., $V = \{0,1,2,3,4,5,6,7,8,9,10,11,12\}$,
 $E = \{\{0,1\}, \{0,5\}, \{2,0\}, \{2,3\}, \{3,2\}, \{3,5\}, \{4,2\}, \{4,3\}, \{5,4\}, \{6,0\}, \{6,4\}, \{6,9\}, \{7,6\}, \{7,8\}, \{8,7\}, \{8,9\}, \{9,10\}, \{9,11\}, \{10,12\}, \{11,4\}, \{11,12\}, \{12,9\}\}$.
- ▶ **Directed path**: a sequence of vertices in which there is a directed edge pointing from each vertex in the sequence to its successor in the sequence, with no repeated edges.
 - ▶ A **simple directed path** is a directed path with no repeated vertices.
- ▶ **Directed cycle**: Directed path with at least one edge whose first and last vertices are the same.
 - ▶ A **simple directed cycle** is a directed cycle with no repeated vertices (other than the first and last).
- ▶ The **length** of a cycle or a path is its number of edges.

Directed Graph Terminology



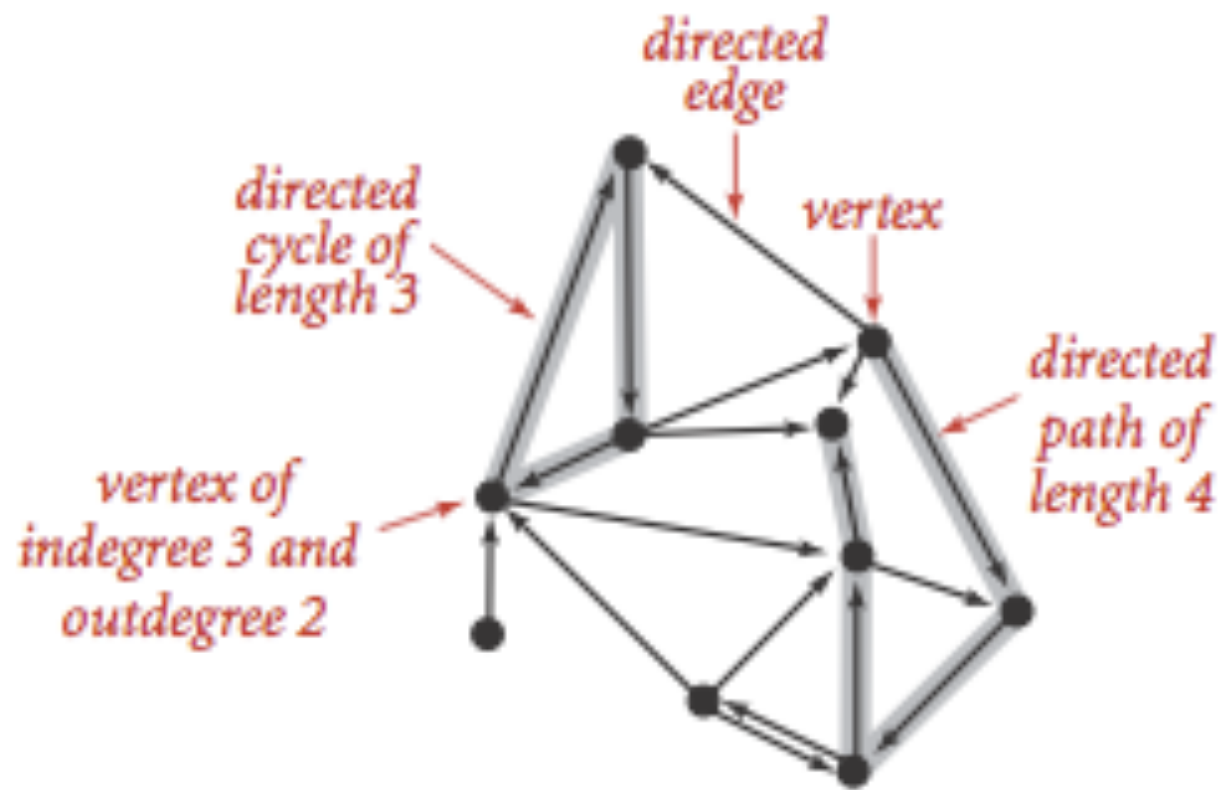
- ▶ **Self-loop**: an edge that connects a vertex to itself.
- ▶ Two edges are **parallel** if they connect the same pair of vertices.
- ▶ The **outdegree** of a vertex is the number of edges pointing from it.
- ▶ The **indegree** of a vertex is the number of edges pointing to it.
- ▶ A vertex w is **reachable** from a vertex v if there is a directed path from v to w .
- ▶ Two vertices v and w are **strongly connected** if they are mutually reachable.



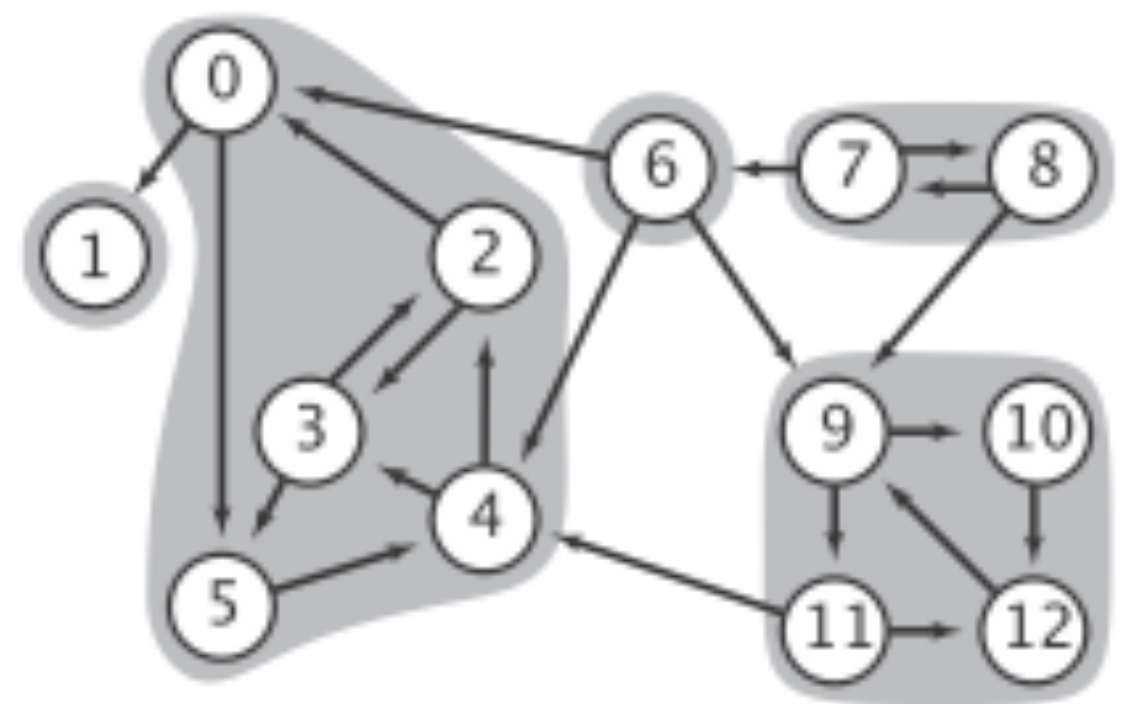
Directed Graph Terminology

- ▶ A digraph is **strongly connected** if there is a directed path from every vertex to every other vertex.
- ▶ A digraph that is not strongly connected consists of a set of strongly connected components, which are maximal strongly connected subgraphs.
- ▶ A **directed acyclic graph (DAG)** is a digraph is a graph with no directed cycles.

Anatomy of a digraph



Anatomy of a digraph



A digraph and its strong components

Digraph Applications

Digraph	Vertex	Edge
Web	Web page	Link
Cell phone	Person	Placed call
Financial	Bank	Transaction
Transportation	Intersection	One-way street
Game	Board	Legal move
Citation	Article	Citation
Infectious Diseases	Person	Infection
Food web	Species	Predator-prey relationship

Popular digraph problems

Problem	Description
$s \rightarrow t$ path	Is there a path from s to t ?
Shortest $s \rightarrow t$ path	What is the shortest path from s to t ?
Directed cycle	Is there a directed cycle in the digraph?
Topological sort	Can vertices be sorted so all edges point from earlier to later vertices?
Strong connectivity	Is there a directed path between every pair of vertices?

Lecture 35-36: Directed Graphs

- ▶ Introduction to Directed Graphs
- ▶ **Digraph API**
- ▶ Depth-First Search
- ▶ Breadth-First Search
- ▶ Topological Sort
- ▶ Strongly Connected Components

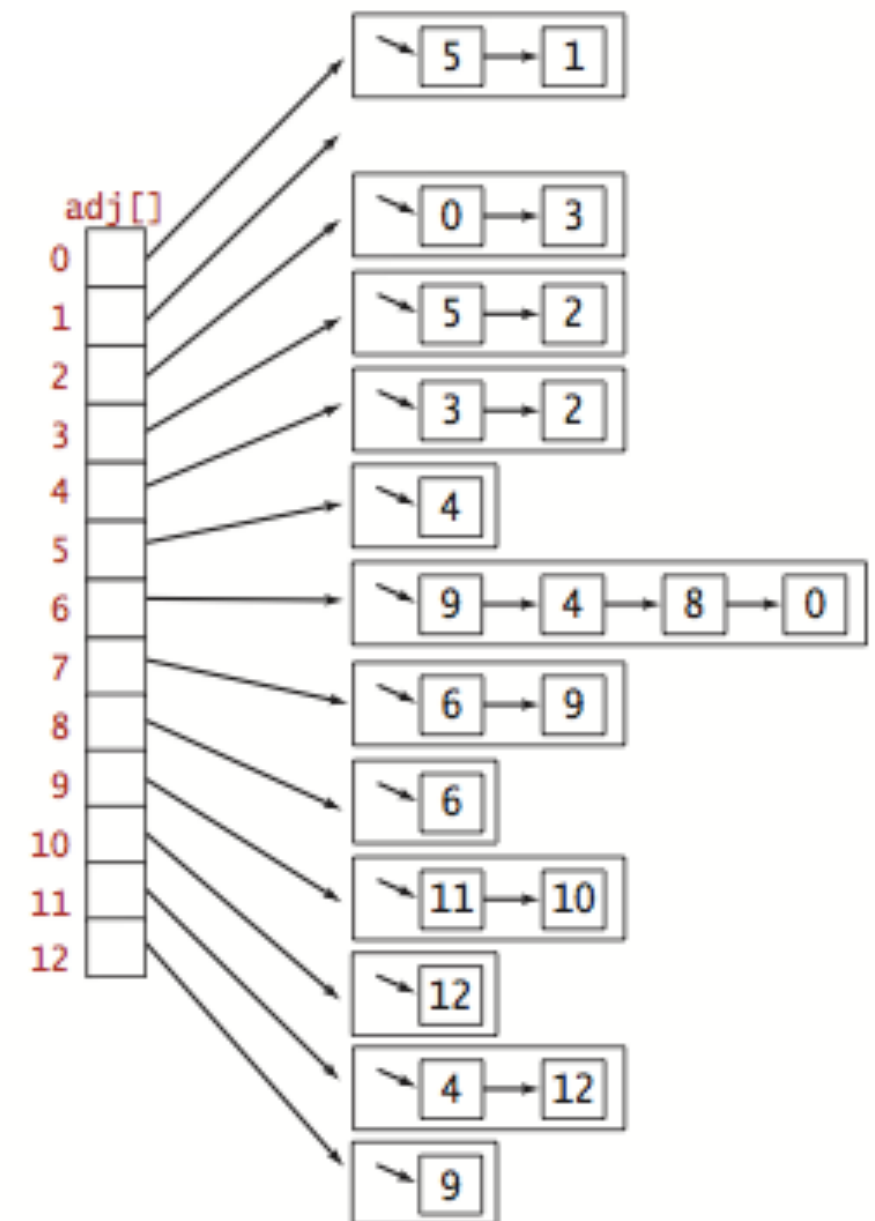
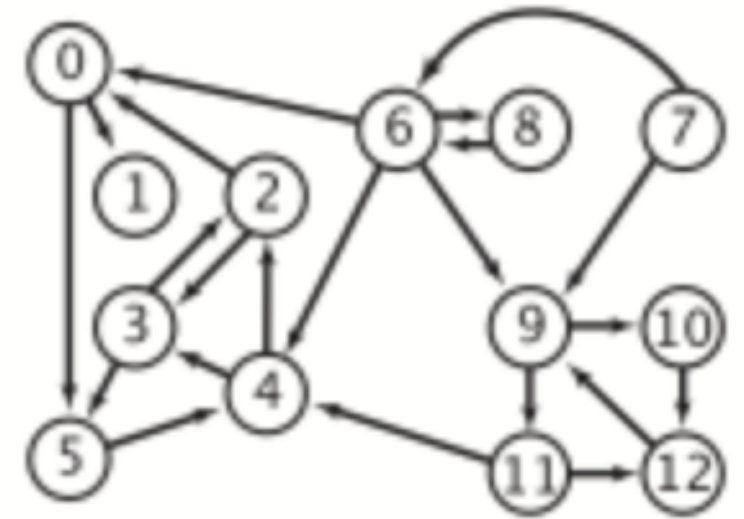
Basic Graph API

- ▶ `public class Digraph`
- ▶ `Digraph(int V)`: create an empty digraph with V vertices.
- ▶ `void addEdge(int v, int w)`: add an edge $v \rightarrow w$.
- ▶ `Iterable<Integer> adj(int v)`: return vertices adjacent from v .
- ▶ `int V()`: number of vertices.
- ▶ `int E()`: number of edges.
- ▶ `Digraph reverse()`: reverse edges of digraph.

DIRECTED GRAPHS

Digraph representation: adjacency list

- ▶ Maintain vertex-indexed array of lists.
- ▶ Good for sparse graphs (edges proportional to $|V|$) which are much more common in the real world.
- ▶ Algorithms based on iterating over vertices adjacent from v .
- ▶ Space efficient ($|E| + |V|$).
- ▶ Constant time for adding a directed edge.
- ▶ Lookup of a directed edge or iterating over vertices adjacent from v is $outdegree(v)$.



Adjacency-list digraph representation in Java

```
public class Digraph {

    private final int V;
    private int E;
    private Bag<Integer>[] adj;

    //Initializes an empty digraph with V vertices and 0 edges.
    public Digraph(int V) {
        this.V = V;
        this.E = 0;
        adj = (Bag<Integer>[]) new Bag[V];
        for (int v = 0; v < V; v++) {
            adj[v] = new Bag<Integer>();
        }
    }

    //Adds the directed edge v->w to this digraph.
    public void addEdge(int v, int w) {
        E++;
        adj[v].add(w);
    }

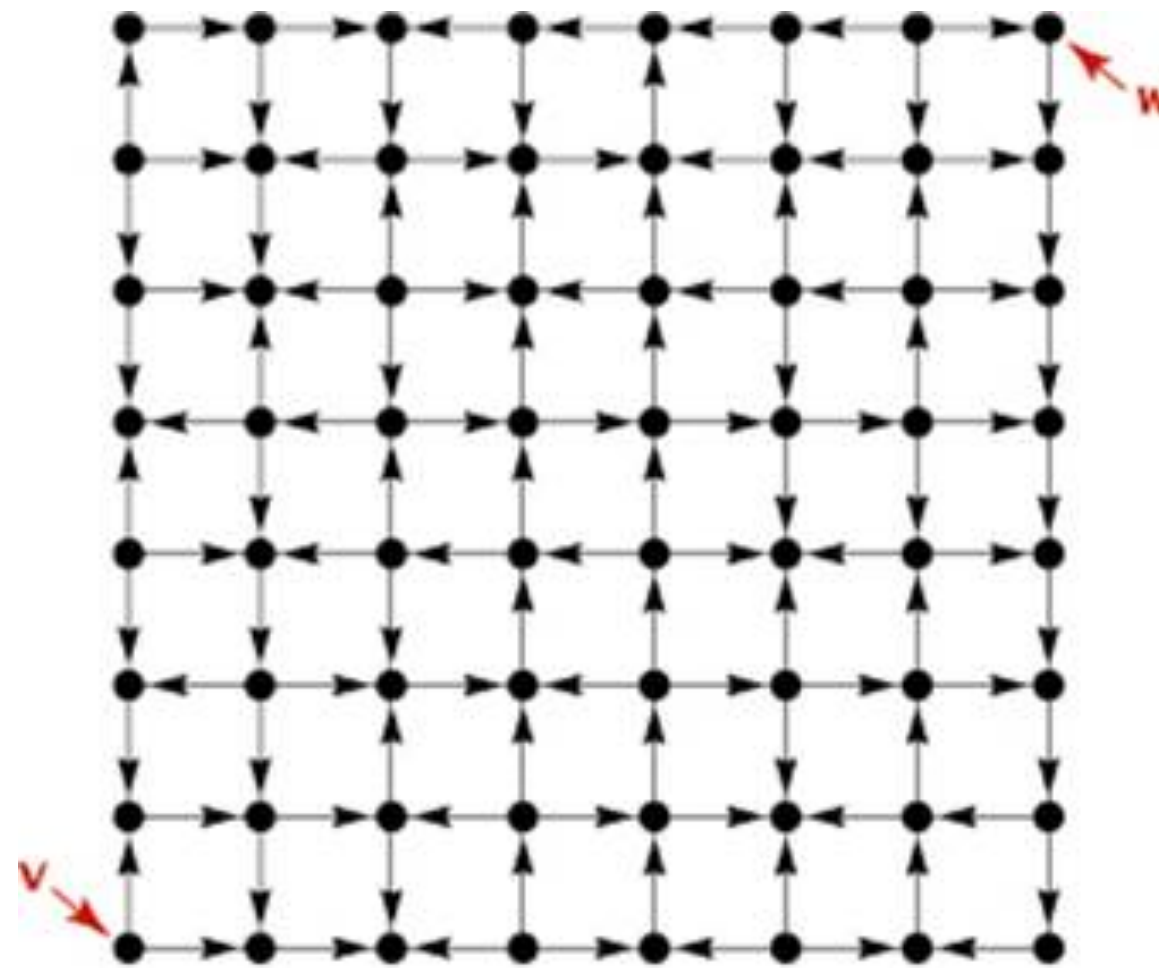
    //Returns the vertices adjacent from vertex v.
    public Iterable<Integer> adj(int v) {
        return adj[v];
    }
}
```

Lecture 35-36: Directed Graphs

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- ▶ **Depth-First Search**
- ▶ Breadth-First Search
- ▶ Topological Sort
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Reachability

- ▶ Find all vertices reachable from s along a directed path.



Is w reachable from v in this digraph?

Depth-first search in digraphs

- ▶ Same method as for undirected graphs.
 - ▶ Every undirected graph is a digraph with edges in both directions.
 - ▶ Maximum number of edges in a simple digraph is $n(n - 1)$.
- ▶ DFS (to visit a vertex v)
 - ▶ Mark vertex v .
 - ▶ Recursively visit all unmarked vertices w adjacent from v .
- ▶ Typical applications:
 - ▶ Find a directed path from source vertex S to a given target vertex V .
 - ▶ Topological sort.
 - ▶ Directed cycle detection.



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4.2 DIRECTED DFS DEMO

Directed depth-first search in Java

```
public class DirectedDFS {
    private boolean[] marked;    // marked[v] = is there an s->v path?

    public DirectedDFS(Digraph G, int s) {
        marked = new boolean[G.V()];
        dfs(G, s);
    }

    // directed depth first search from v
    private void dfs(Digraph G, int v) {
        marked[v] = true;
        for (int w : G.adj(v)) {
            if (!marked[w]) {
                dfs(G, w);
            }
        }
    }
}
```

Alternative iterative implementation with a stack

```
public class DirectedDFS {
    private boolean[] marked;    // marked[v] = is there an s->v path?

    public DirectedDFS(Digraph G, int s) {
        marked = new boolean[G.V()];
        dfs(G, s);
    }

    // iterative dfs that uses a stack
    private void dfs(Digraph G, int v) {
        Stack stack = new Stack();
        s.push(v);
        while (!stack.isEmpty()) {
            int vertex = stack.pop();
            if (!marked[vertex]) {
                marked[vertex] = true;
                while (int w : G.adj(vertex)) {
                    if (!marked[w])
                        stack.push(w);
                }
            }
        }
    }
}
```

Depth-first search Analysis

- ▶ DFS marks all vertices reachable from s in time proportional to $|V| + |E|$ in the worst case.
 - ▶ Initializing arrays marked takes time proportional to $|V|$.
 - ▶ Each adjacency-list entry is examined exactly once and there are E such edges.
- ▶ Once we run DFS, we can check if vertex v is reachable from s in constant time. We can also find the $s \rightarrow v$ path (if it exists) in time proportional to its length.

Lecture 35-36: Directed Graphs

- ▶ Introduction to Directed Graphs
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- ▶ Depth-First Search
- ▶ **Breadth-First Search**
- ▶ Topological Sort
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Breadth-first search

- ▶ Same method as for undirected graphs.
 - ▶ Every undirected graph is a digraph with edges in both directions.
- ▶ **BFS** (from source vertex s)
 - ▶ Put s on queue and mark s as visited.
 - ▶ Repeat until the queue is empty:
 - ▶ Dequeue vertex v .
 - ▶ Enqueue all unmarked vertices adjacent from v , and mark them.
- ▶ **Typical applications:**
 - ▶ Find the shortest (in terms of number of edges) directed path between two vertices in time proportional to $|E| + |V|$.



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4.2 DIRECTED BFS DEMO

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Depth-first orders

- ▶ If we save the vertex given as argument to recursive dfs in a data structure, we have three possible orders of seeing the vertices:
 - ▶ **Preorder**: Put the vertex on a queue before the recursive calls.
 - ▶ **Postorder**: Put the vertex on a queue after the recursive calls.
 - ▶ **Reverse postorder**: Put the vertex on a stack after the recursive calls.

Depth-first orders

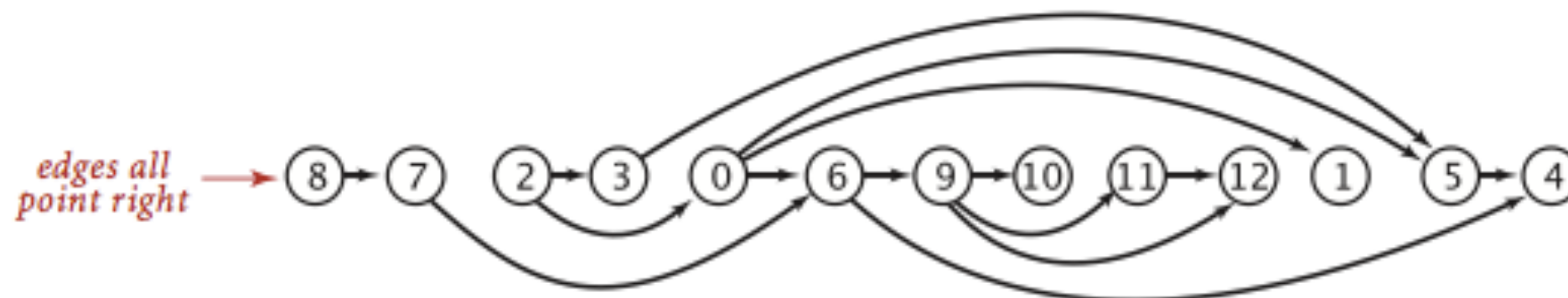
```
public class DepthFirstOrder {
    private boolean[] marked;           // marked[v] = has v been marked in dfs?
    private Queue<Integer> preorder;    // vertices in preorder
    private Queue<Integer> postorder;   // vertices in postorder
    private Stack<Integer> reversePostOrder; // vertices in reverse postorder

    /**
     * Determines a depth-first order for the digraph {@code G}.
     * @param G the digraph
     */
    public DepthFirstOrder(Digraph G) {
        postorder = new Queue<Integer>();
        preorder = new Queue<Integer>();
        reversePostOrder = new Stack<Integer>();
        marked = new boolean[G.V()];
        for (int v = 0; v < G.V(); v++)
            if (!marked[v]) dfs(G, v);
    }

    // run DFS in digraph G from vertex v and compute preorder/postorder
    private void dfs(Digraph G, int v) {
        marked[v] = true;
        preorder.enqueue(v);
        for (int w : G.adj(v)) {
            if (!marked[w]) {
                dfs(G, w);
            }
        }
        postorder.enqueue(v);
        reversePostOrder.push(v);
    }
}
```


Topological sort

- ▶ **Goal:** Order the vertices of a DAG so that all edges point from an earlier vertex to a later vertex.
- ▶ Think of modeling major requirements as a DAG.
- ▶ Reverse postorder in DAG is a topological sort.
- ▶ With DFS, we can topologically sort a DAG in $|E| + |V|$ time.





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4.2 TOPOLOGICAL SORT DEMO

Summary

- ▶ Single-source reachability in a digraph: DFS/BFS.
- ▶ Shortest path in a digraph: BFS.
- ▶ Topological sort in a DAG: DFS.

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Is a digraph strongly connected?

- ▶ Pick a random starting vertex s .
- ▶ Run DFS/BFS starting at s .
 - ▶ If have not reached all vertices, return false.
- ▶ Reverse edges.
- ▶ Run DFS/BFS again on reversed graph.
 - ▶ If have not reached all vertices, return false.
 - ▶ Else return true.

Readings:

- ▶ Textbook: Chapter 4.2 (Pages 566-594)
- ▶ Website:
 - ▶ <https://algs4.cs.princeton.edu/42digraph/>

Practice Problems:

- ▶ 4.2.1-4.27