

# Lecture 35: Graphs III

CS 62

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# Single Source Shortest Path Problem

- From a starting node  $s$ , find the shortest path (and its length) to all other (reachable) nodes
- The collection of all shortest paths form a tree which is called... the *shortest path tree*!
- If all edges have the same weight, we can use *BFS*.
- Otherwise ...

# Single Source Shortest Path Problem

- If all edges have weights  $\geq 0$  then use Dijkstra's algorithm
- Essentially BFS with priority queue
- Priorities are best known distance to a node from  $S$
- We can keep track of parent nodes to get shortest path
- Example of a **greedy** algorithm

# Dijkstra's algorithm (1956) pseudocode

```
Q = {}; //set with unvisited vertices
for(every vertex v in V) {
    dist[v] = Infinity;
    parents[v] = null;
    Q.add(v);
}
dist[s] = 0;
while (!Q.isEmpty()) {
    u = vertex in Q with min dist[u];
    Q.remove(u);
    for(every edge (u,v)) {
        tentative = dist[u] + weight(u,v);
        if (tentative < dist[v]) {
            dist[v] = tentative;
            parents[v] = u;
        }
    }
}
```

# Dijkstra's algorithm (1984) pseudocode

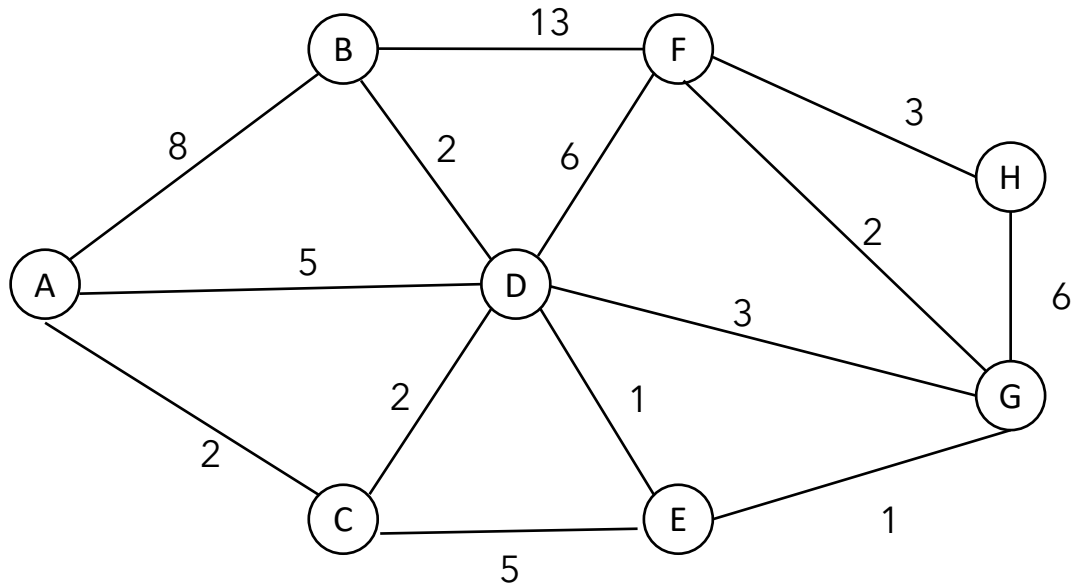
```
Q = new PriorityQueue();
for(every vertex v in V) {
    dist[v] = Infinity;
    parents[v] = null;
    Q.addWithPriority(v, dist[v]);
}

dist[s] = 0;
Q.addWithPriority(s, 0);
while (!Q.isEmpty()) {
    u = Q.extractmin();
    Q.remove(u);
    for(every edge (u,v)) {
        tentative = dist[u] + weight(u,v);
        if (tentative < dist[v]) {
            dist[v] = tentative;
            parents[v] = u;
            Q.reducePriority(v, tentative);
        }
    }
}
```

# Run-time of Dijkstra

- Adding and removing from priority queue:  $O(\log n)$ 
  - Each goes on and off once, so  $O(n \log n)$
- **reduce\_priority**:  $O(\log n)$ 
  - Worst case, once for each edge, so  $O(m \log n)$
- Total time:  $O((m + n) \log n)$

# Dijkstra on sample graph



# Dijkstra on sample graph

	A	B	C	D	E	F	G	H
Init	$0_A$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
A	$0_A$	$8_A$	$2_A$	$5_A$	$\infty$	$\infty$	$\infty$	$\infty$
C	$0_A$	$8_A$	$2_A$	$4_C$	$7_C$	$\infty$	$\infty$	$\infty$
D	$0_A$	$6_D$	$2_A$	$4_C$	$5_D$	$10_D$	$7_D$	$\infty$
E	$0_A$	$6_D$	$2_A$	$4_C$	$5_D$	$10_D$	$6_E$	$\infty$
B	$0_A$	$6_D$	$2_A$	$4_C$	$5_D$	$10_D$	$6_E$	$\infty$
G	$0_A$	$6_D$	$2_A$	$4_C$	$5_D$	$8_G$	$6_E$	$12_G$
F	$0_A$	$6_D$	$2_A$	$4_C$	$5_D$	$8_G$	$6_E$	$11_F$
H	$0_A$	$6_D$	$2_A$	$4_C$	$5_D$	$8_G$	$6_E$	$11_F$

*Follow the subscripts to find shortest path from start to any vertex*



# Practice Time

