

# Lecture 21: Heaps & Heapsort

CS 62  
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## Lab Today

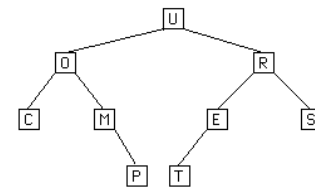
- Build binary search trees *Different from heap!*
- A binary tree is a binary search tree iff
  - it is empty or
  - if the value of every node is both greater than or equal to every value in its left subtree and less than or equal to every value in its right subtree.
- How do you build binary search tree?
  - Insert by following from root until find empty slot

## Quiz Friday

- Array representations of trees
- Priority queues
- Heapsort

## Array Representation of Trees

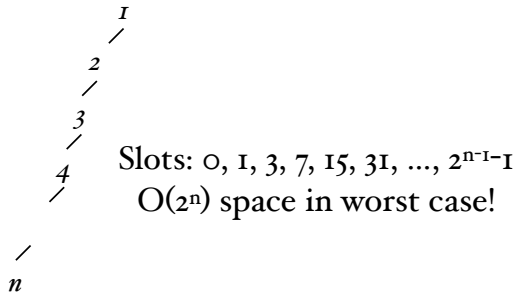
- `data[0..n-1]` can hold values in trees
  - left subtree of node  $i$  in  $2*i+1$ , right in  $2*i+2$ ,
  - parent in  $(i-1)/2$



Indices: 0 1 2 3 4 5 6 7 8 9 10 11 12 13 14  
data[]: U O R C M E S - - - P T - - -

## How bad can it be?

- What if long stringy tree (e.g. only single left-most branch)?
  - How much space to hold  $n$  elements.
  - If complete what is height?



## Min-Heap

- Min-Heap  $H$  is complete binary tree s.t.
  - $H$  is empty, or
  - Both of the following hold:
    - The value in root position is smallest value in  $H$
    - The left and right subtrees of  $H$  are also heaps.  
*Equivalent to saying parent  $\leq$  both left and right children*
- Excellent implementation for priority queue
  - Dequeue elements w/lowest priority values before higher

## Implementations

- As regular queue (array or linked) where either keep in order or search for lowest to remove:
  - One of add or remove will be  $O(n)$
- Heap representation (in arraylist) is more efficient:  $O(\log n)$  for both add and remove.
  - Insert into heap:
    - Place in next free position,
    - “Percolate” it up.
  - Delete:
    - remove root,
    - move last element in array up to root. “Push” it down.

See VectorHeap code!

*Called PriorityQueue class in standard Java*

## Sorting with Trees

## Tree Sort

- Build Binary search tree (later)
- Do Inorder traversal, adding elts to array
  - Inorder traversal:  $O(n)$
  - Building tree:
    - $\log 1 + \log 2 + \dots + \log n = O(n \log n)$  in best (& average) case
    - $O(n^2)$  in worst case
- $O(n \log n)$  in best & average case
- $O(n^2)$  in worst case :-(  
*What is worst case?*
- Heapsort is always better!

## Heapsort

- Make vector into a heap:
  - $n$  add operations =  $O(n \log n)$
- Remove elements in order
  - $n$  remove operations =  $O(n \log n)$
- Total:  $O(n \log n)$ 
  - If clever can make into heap in  $O(n)$
  - ... but still  $O(n \log n)$  total.
  - $O(1)$  extra space (for swaps)

## Comparing Sorts

- Quicksort: fastest on average  $O(n \log n)$ , but worst case is  $O(n^2)$  & takes  $O(\log n)$  extra space
- Heapsort:  $O(n \log n)$  in average & worst case. No extra space.
  - Bit slower on average than quick & mergesorts.
- Mergesort:  $O(n \log n)$  in average and worst case.  $O(n)$  extra space.
  - Performs well on external files where not all fit in memory.