

Automatic Differentiation

Outline

- Recap neural networks and backpropagation
- Simple minimization examples
- Example with partial derivatives and a compute graph
- Partial derivatives and compute graphs for a one-layer network
- Partial derivatives and compute graphs for a two-layer network
- Automatic differentiation in code

Recap: Neural Networks and Backpropagation

- Take five minutes to draw
 - Whatever will help you remember (no correct or incorrect drawings)
 - You'll keep a running drawing log the rest of the semester

Automatic Differentiation (AD)

- Distinct from

- Symbolic differentiation (exact, slow, must have symbolic representation)
- Numerical differentiation (approximation/imprecise, fast, flexible)

to a degree

- Forms of AD

- Forward mode AD (exact, fast, flexible)
- ★ Reverse mode AD (exact, faster, flexible) (used by PyTorch as the default¹)

PyMatch

- Some terms

- Differentiation: Process of finding a derivative
- Derivative: The rate of change of a function (sometimes at a specific point)
- Partial derivative: Derivative of a function with respect to one of several variables
- Gradient: All partial derivatives

$$f(a) = 4(a - 2)^2 - 3$$

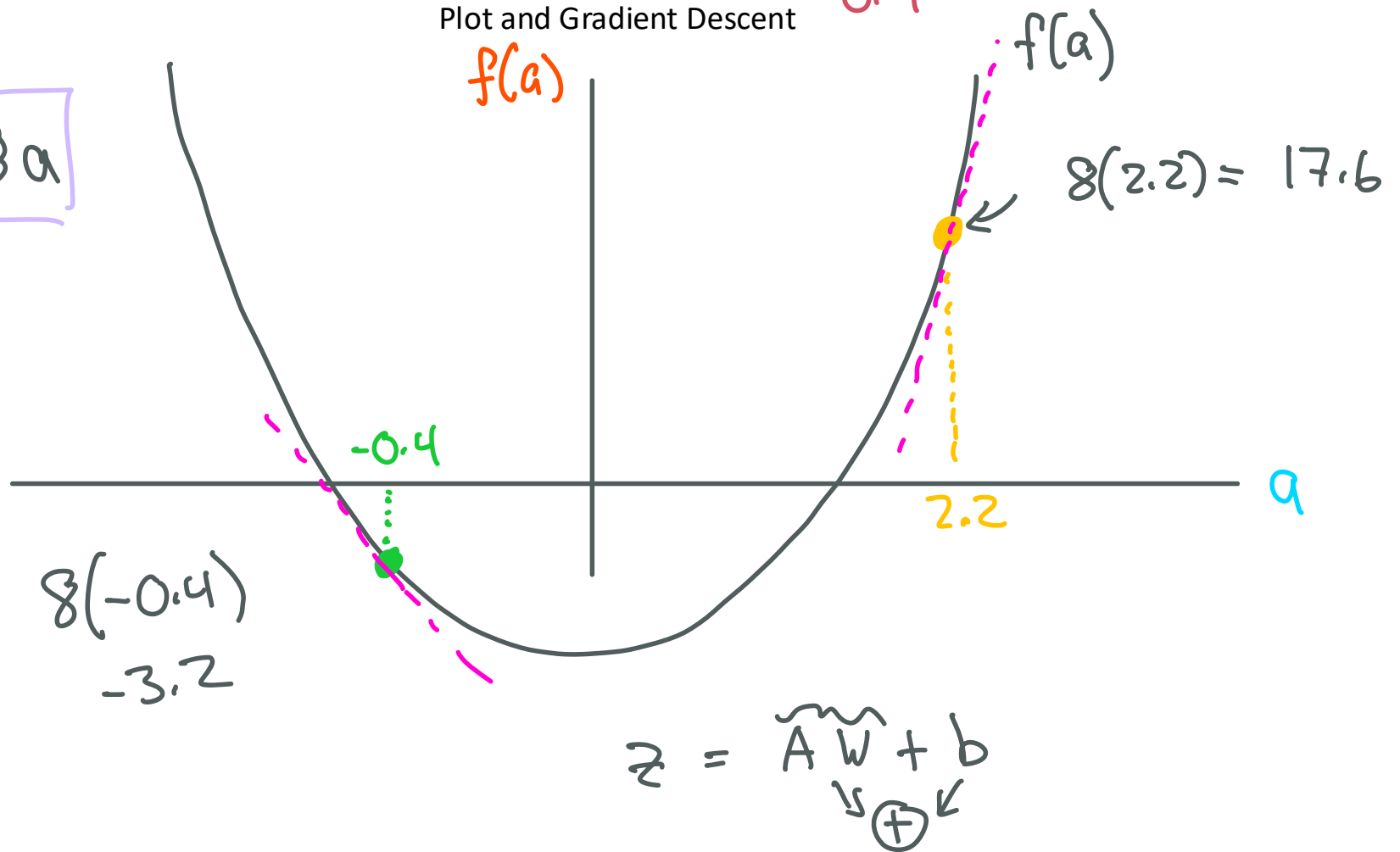
Plot

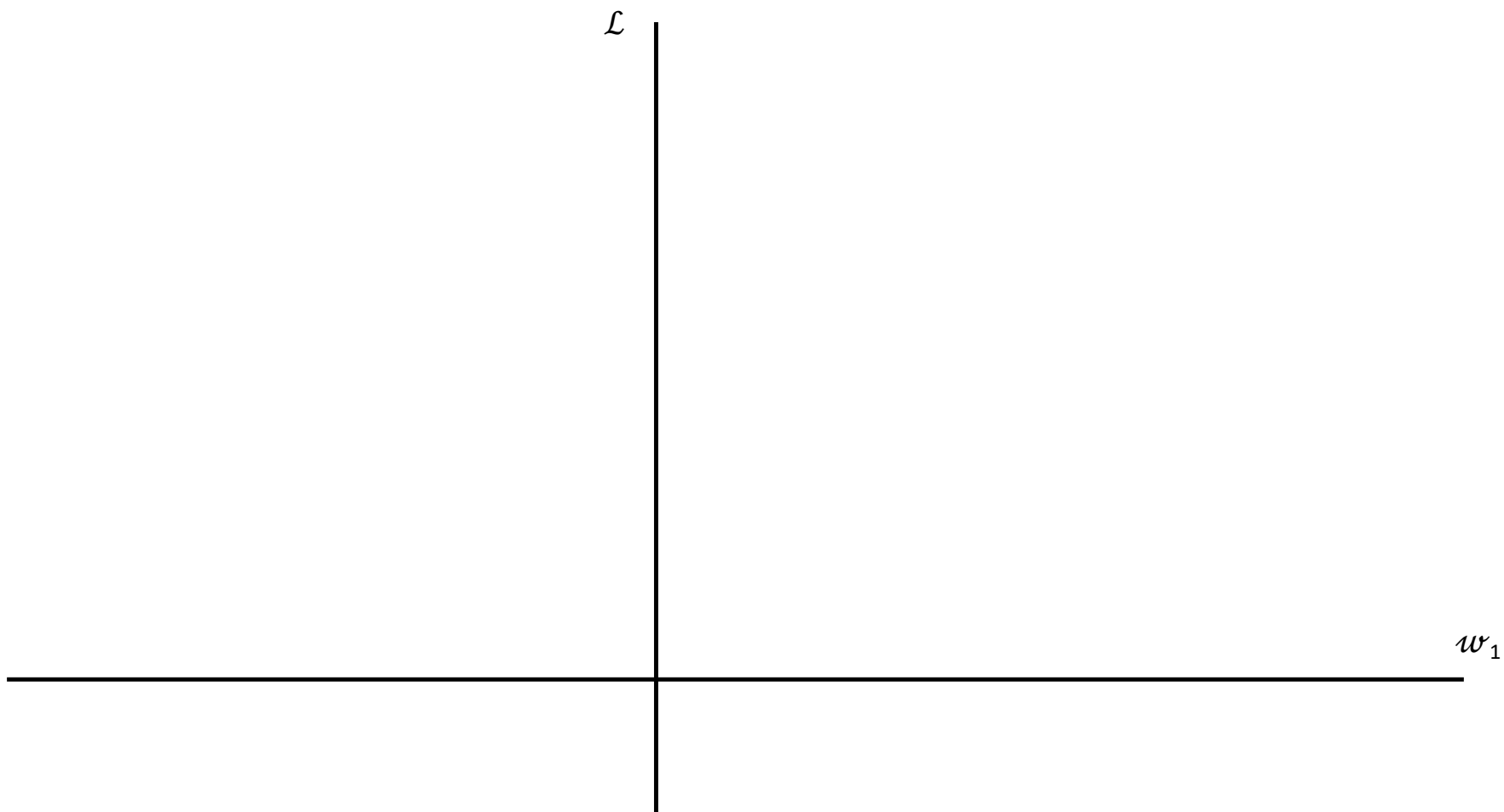
Closed-form solution

$$f(a) = 4a^2 - 3, \text{ where } a = \del{1.8} \text{ and } a = 2.2$$

Plot and Gradient Descent

$$\frac{d}{da} f = \boxed{8a}$$





$$f(a, b, c, d) = b(a - c)^2 - d$$

~~$$\frac{d}{da} f$$~~

$$\frac{\partial}{\partial a} f$$

$$\nabla f$$

$$f(a, b) = a^3 b^2$$

Minimize with respect to a

$$f = a^{**3} * b^{**2}$$

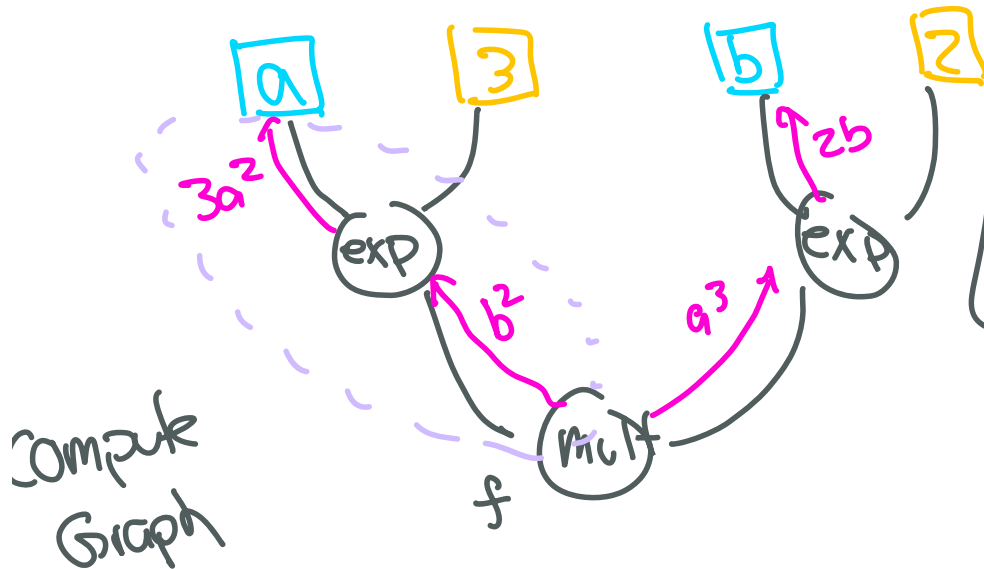
Tensor

Tensor

$$\frac{\partial f}{\partial a} = \frac{\partial}{\partial a} a^3 b^2 = 3a^2 b^2$$

[1, 2, 3] (3,1)
 [[1, 2, 3], (2,3)
 [4, 5, 6]]

[[1, 2, 3] Jagged
 [1, 2] X ...



f.backward()

$$\frac{\partial f}{\partial a} = 3a^2 b^2$$

One-Layer Network (MSE and Sigmoid) Compute Graph

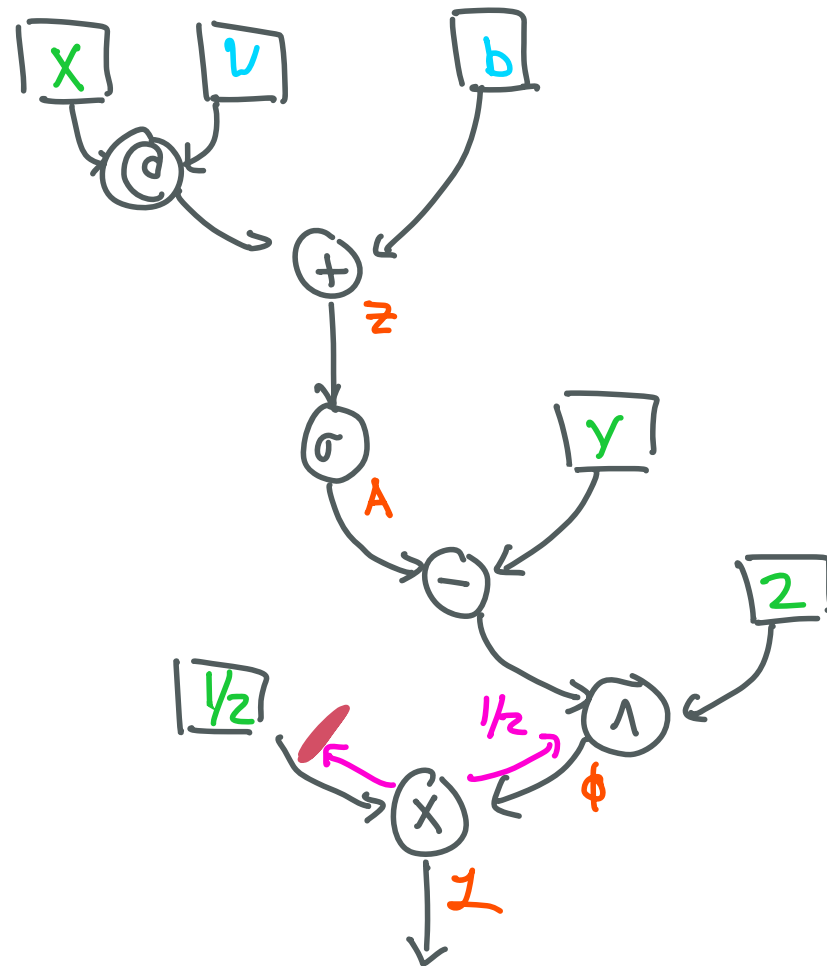
- $Z = XW^T + b$
- $A = \sigma(Z) = \sigma(XW^T + b)$
- $\mathcal{L} = \frac{1}{2}(A - Y)^2$

$\mathcal{L}.backward()$

$$\mathcal{L} = \frac{1}{2} (\sigma(XW^T + b) - Y)^2$$

$$\mathcal{L} = \alpha \cdot \phi$$

$$\frac{\partial \mathcal{L}}{\partial \alpha} = \phi, \quad \frac{\partial \mathcal{L}}{\partial \phi} = \alpha$$



One-Layer Network (MSE and Sigmoid) Compute Graph

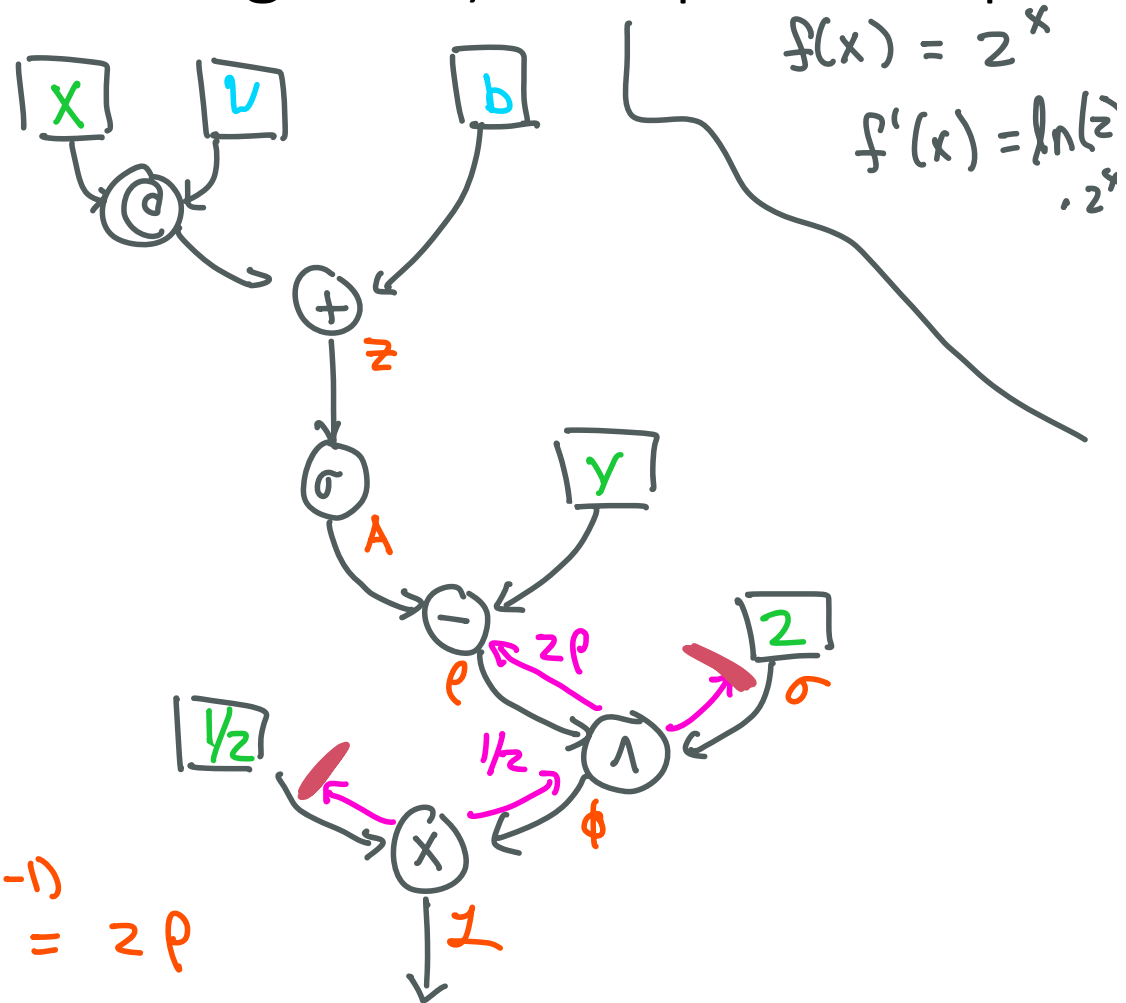
- $Z = XW^T + b$
- $A = \sigma(Z) = \sigma(XW^T + b)$
- $\mathcal{L} = \frac{1}{2}(A - Y)^2$

2. backward()

$$\mathcal{L} = \frac{1}{2} (\sigma(xv^T + b) - Y)^2$$

$$\phi = \rho$$

$$\frac{\partial \phi}{\partial \rho} = \sigma \rho^{(\sigma-1)} = 2 \rho^{(2-1)} = 2 \rho$$



One-Layer Network (MSE and Sigmoid) Compute Graph

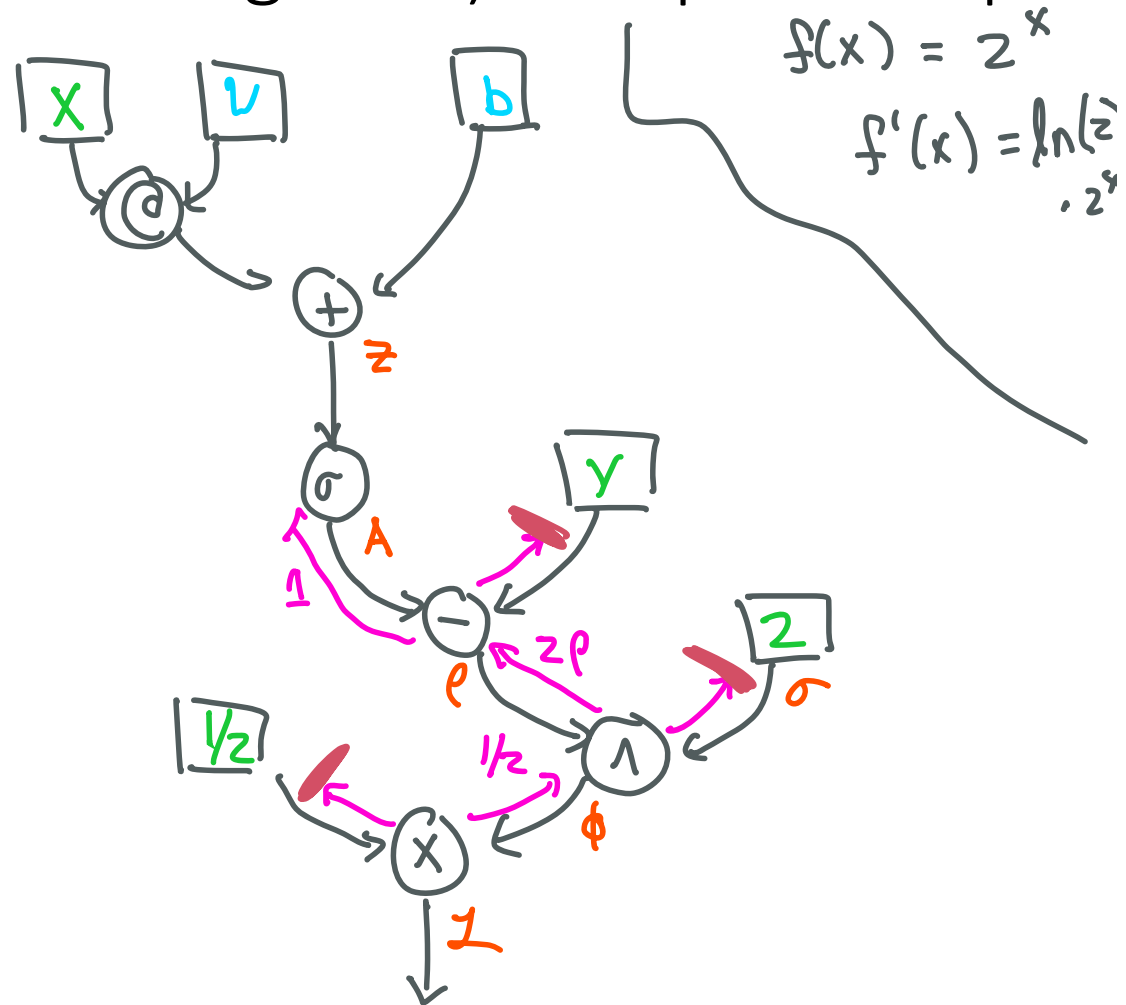
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2. backward()

$$\mathcal{L} = \frac{1}{2} (\sigma(XW^T + b) - Y)^2$$

$$e = A - Y$$

$$\frac{\partial \mathcal{L}}{\partial A} = 1, \quad \frac{\partial \mathcal{L}}{\partial Y} = -1$$



One-Layer Network (MSE and Sigmoid) Compute Graph

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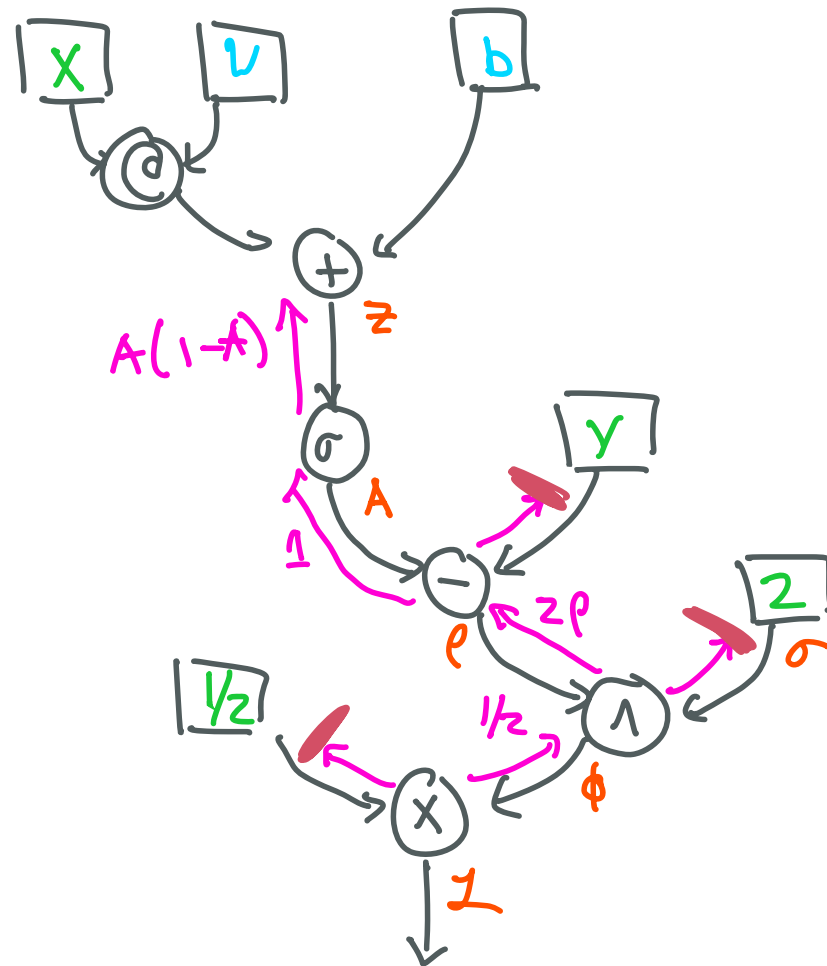
$\mathcal{L}.backward()$

$$\mathcal{L} = \frac{1}{2}(\sigma(XW^T + b) - Y)^2$$

$$A = \sigma(z)$$

$$\frac{\partial A}{\partial z} = \sigma(z)(1 - \sigma(z))$$

$$\frac{\partial \mathcal{L}}{\partial z} = A(1 - A)$$



One-Layer Network (MSE and Sigmoid) Compute Graph

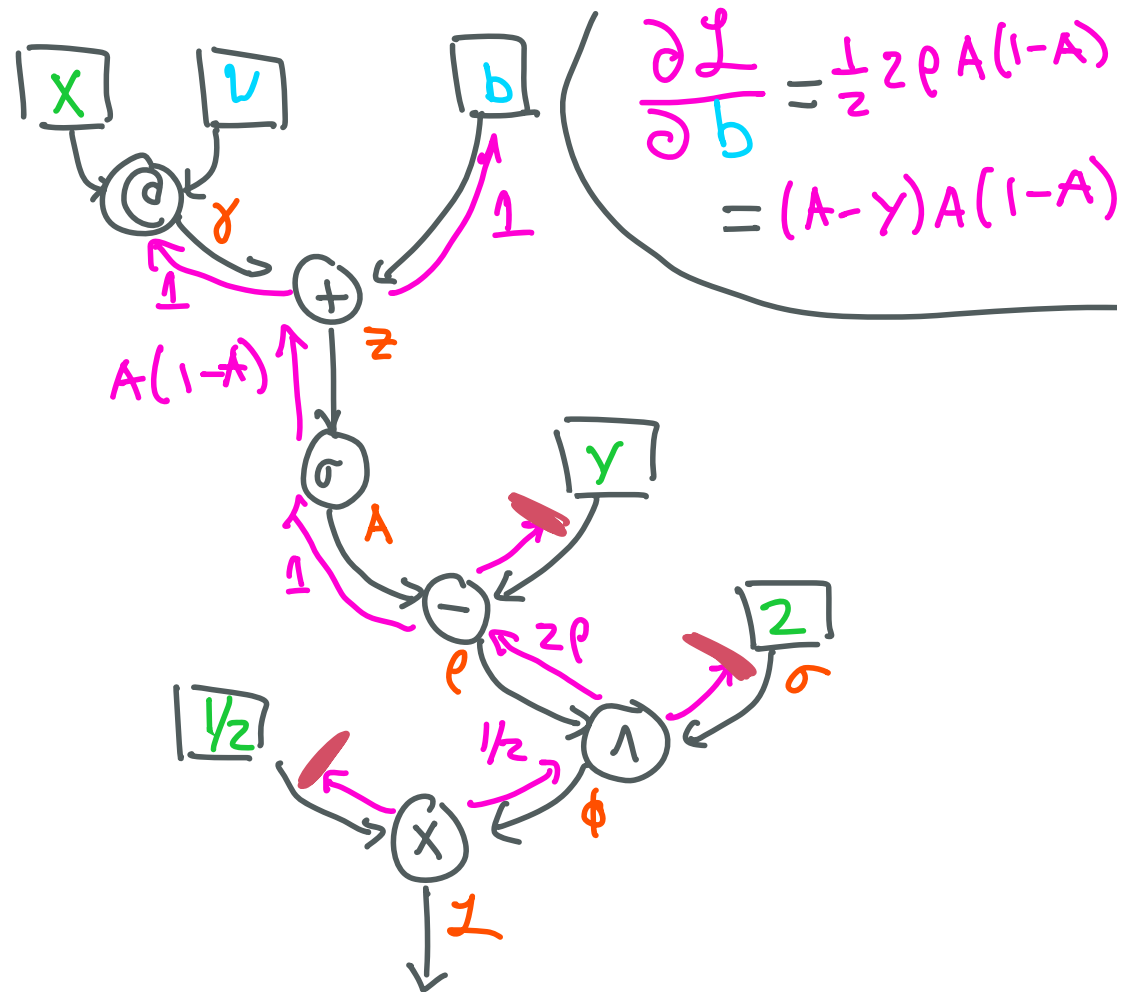
- $Z = \textcircled{XW^T} + b$
- $A = \sigma(Z) = \sigma(XW^T + b)$
- $\mathcal{L} = \frac{1}{2}(A - Y)^2$

$\mathcal{L}. \text{backward}(C)$

$$\mathcal{L} = \frac{1}{2} (\sigma(XW^T + b) - Y)^2$$

$$z = y + b$$

$$\frac{\partial z}{\partial y} = 1, \quad \frac{\partial z}{\partial b} = 1$$



One-Layer Network (MSE and Sigmoid) Compute Graph

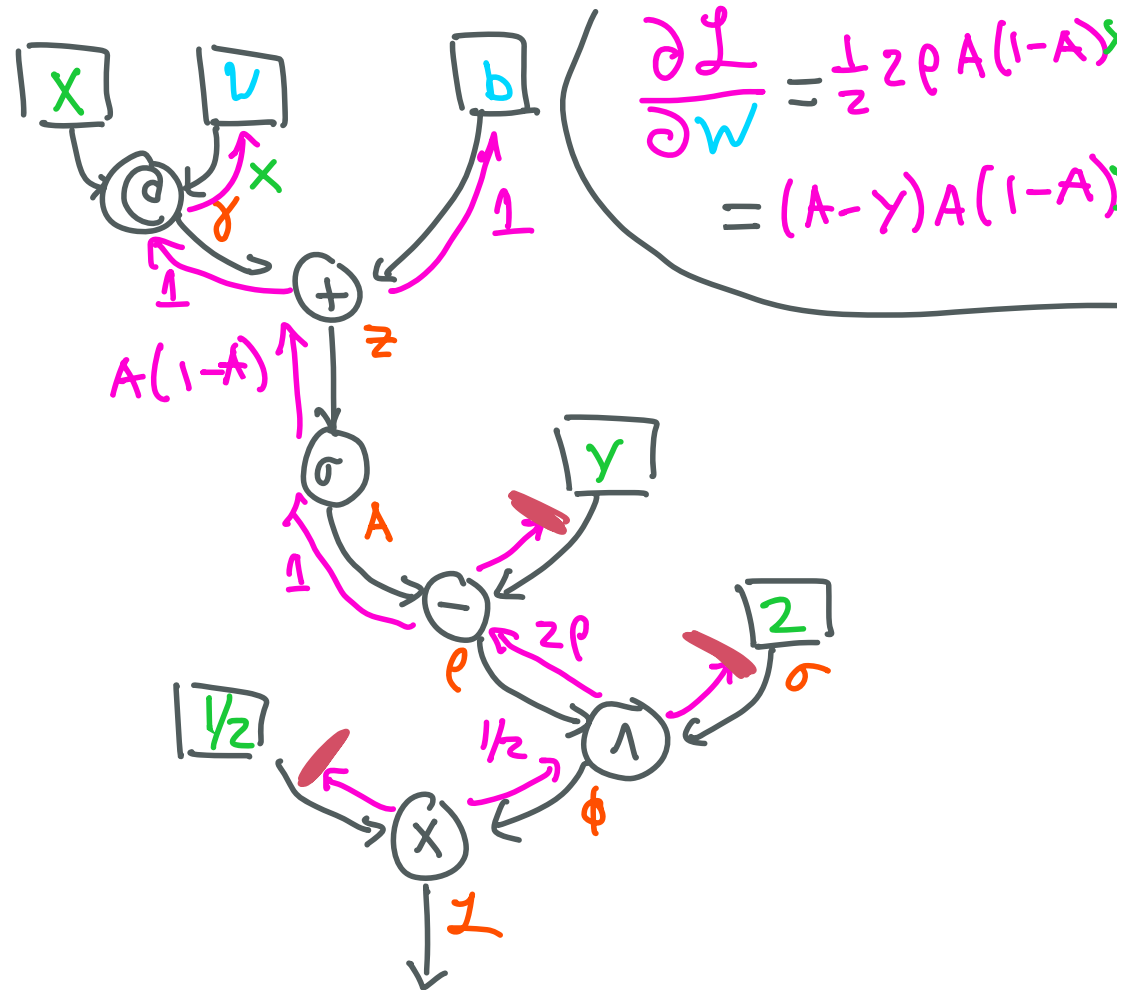
- $Z = XW^T + b$
- $A = \sigma(Z) = \sigma(XW^T + b)$
- $\mathcal{L} = \frac{1}{2}(A - Y)^2$

$\mathcal{L}.backward()$

$$\mathcal{L} = \frac{1}{2}(\sigma(XW^T + b) - Y)^2$$

$$\gamma = XW^T$$

$$\frac{\partial \gamma}{\partial X} = \text{~~W~~}, \quad \frac{\partial \gamma}{\partial W} = X$$



Two-Layer Network (MSE and Sigmoid)

- $Z^{[1]} = A^{[0]}W^{[1]T} + b^{[1]T}$
- $A^{[1]} = \sigma(Z^{[1]})$
- $Z^{[2]} = A^{[1]}W^{[2]T} + b^{[2]T}$
- $A^{[2]} = \sigma(Z^{[2]})$
- $\mathcal{L} = \frac{1}{2}(A^{[2]} - Y)^2$

Exercise for
the reader

Manual Differentiation

- How does the derivation change if we add hidden layers?

More derivation

- How does the derivation change if we change the activation function?

$$\frac{\partial A}{\partial z} = \sigma(z)(1 - \sigma(z))$$

- How does the derivation change if we change the loss function?

$$\mathcal{L} = \frac{1}{2} (A - Y)^2$$

$$\mathcal{L} = - \left(Y \log(A) + (1 - Y) \log(1 - A) \right)$$

Automatic Differentiation (Autodiff, Autograd)

```
# Forward propagation A0 = X, Yhat = A2  
Z1 = linear(A0, W1, b1)  
A1 = sigmoid(Z1)  
Z2 = linear(A1, W2, b2)  
A2 = sigmoid(Z2)  
  
# Compute loss as the mean-square-error  
bce_loss = torch.mean(Y * torch.log(A2) + (1 - Y) * torch.log(1 - Yhat))  
  
learning_rate = 0.01 # aka alpha or  $\alpha$ 
```

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learning_rate = 0.01 # aka alpha or  $\alpha$ 
```

```
# Compute gradients for W^[2] and b^[2]
dL_dY = (Y / Yhat - (1 - Y) / (1 - Yhat)) / 2
dY_dZ2 = Yhat * (1 - Yhat)
dZ2 = dL_dY * dY_dZ2
dW2 = (1 / N) * dZ2.T @ A1
db2 = dZ2.mean(dim=0)

# Compute gradients for W^[1] and b^[1]
dZ1 = dZ2 @ W2 * ((A1 * (1 - A1)))
dW1 = (1 / N) * dZ1.T @ X
db1 = dZ1.mean(dim=0)

W1 -= learning_rate * dW1
b1 -= learning_rate * db1
W2 -= learning_rate * dW2
b2 -= learning_rate * db2
```

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# Compute gradients for W^[1] and b^[1]
dZ1 = dZ2 @ W2 * ((A1 * (1 - A1)))
dW1 = (1 / N) * dZ1.T @ X
db1 = dZ1.mean(dim=0)
```

```
W1 -= learning_rate * dW1
b1 -= learning_rate * db1
W2 -= learning_rate * dW2
b2 -= learning_rate * db2
```

```
bce_loss.backward()
```

```
W1 -= learning_rate * W1.grad
b1 -= learning_rate * b1.grad
W2 -= learning_rate * W2.grad
b2 -= learning_rate * b2.grad
```

Creating the Compute Graph

Sigmoid compute node from matrix.py

```
def sigmoid(self) -> Matrix:
```

"""Element-wise sigmoid."""

```
result = Matrix(self.data.sigmoid(), children=(self,))
```

```
def _gradient() -> None:
```

```
self.grad += result.data * (1 - result.data) * result.grad
```

```
result._gradient = _gradient
```

```
return result
```

Back propagation
matrix.py

$z = \dots$
 $A = z.\text{sigmoid}()$

$\boxed{z}$
 $\uparrow$
 $\boxed{A}$ grad

Sigmoid math from list2d.py

```
def sigmoid(self) -> List2D:
```

```
vals = [
```

```
    [sigmoid(self.vals[i][j]) for j in range(self.ncol)]
```

```
    for i in range(self.nrow)
```

```
]
```

```
return List2D(*self.shape, vals)
```

list2d.py

Creating the Compute Graph

```
def sigmoid(self) -> Matrix:
    """Element-wise sigmoid."""
    result = Matrix(self.data.sigmoid(), children=(self,))

    def _gradient() -> None:
        self.grad += result.data (1 - result.data) * result.grad

    result._gradient = _gradient
    return result
```

A(1-A)

```
def __matmul__(self, rhs: Matrix) -> Matrix:
    """Matrix multiplication: self @ rhs."""
    result = Matrix(self.data @ rhs.data, children=(self, rhs))

    def _gradient() -> None:
        self.grad += result.grad @ rhs.data.T
        rhs.grad += self.data.T @ result.grad

    result._gradient = _gradient
    return result
```

```
def __add__(self, rhs: float | int | Matrix) -> Matrix:
    """Element-wise addition."""
    rhs_vals = rhs.data if isinstance(rhs, Matrix) else rhs
    children = (self, rhs) if isinstance(rhs, Matrix) else (self,)
    result = Matrix(self.data + rhs_vals, children=children)

    def _gradient() -> None:
        self.grad += result.grad.unbroadcast(*self.shape)
        if isinstance(rhs, Matrix):
            rhs.grad += result.grad.unbroadcast(*rhs.shape)

    result._gradient = _gradient
    return result
```

**1*

**1*

$$T = X v^T$$

$$\begin{bmatrix} 0 \end{bmatrix} = \begin{bmatrix} 1 \end{bmatrix} \begin{bmatrix} 0 \end{bmatrix}$$

Backpropagation (.backward)

```
def backward(self) -> None:
    """Compute all gradients using backpropagation."""
```

$$J = \frac{1}{2} (A - \gamma)^2$$

J.backward()

```
sorted_nodes: list[Matrix] = []
visited: set[Matrix] = set()
```

```
# Sort all elements in the compute graph using a topological ordering (DFS)
# (Creating a closure here for convenience; capturing sorted_nodes and visited)
```

```
def topological_sort(node: Matrix) -> None:
```

```
    if node not in visited:
        visited.add(node)
        for child in node._children:
            topological_sort(child)
        sorted_nodes.append(node)
```

```
# Perform the topological sort
```

```
topological_sort(self)
```

```
# Initialize all gradients with ones
```

```
self.grad.ones_()
```

```
# Update gradients from output to input (backwards)
```

```
for node in reversed(sorted_nodes):
    node._gradient()
```