# Floyd-Warshall Algorithm For Solving the <u>All-Pairs</u> Shortest Path Problem

https://cs.pomona.edu/classes/cs140/

## Outline

#### **Topics and Learning Objectives**

Discuss and analyze the Floyd-Warshall Algorithm

#### **Exercise**

None

#### All-Pairs Shortest Path Problem

Compute the shortest path from every vertex to every other vertex

- Input: a weighted graph (no need for a start vertex)
- Output:
  - Shortest path from u → v for all values of u and v
  - Or report that a negative cycle has been discovered
- Can we solve this problem with what we know already?

## SSSP → APSP

How do we turn a solution to the single-source shortest path (SSSP) problem into a solution for the all-pairs shortest path (APSP) problem?

- This is called a reduction!
- How many times do we need to run a SSSP procedure for APSP?
  - a. 1
  - b. n-1
  - c. n
  - $d. n^2$

# SSSP algorithms

Running time of APSP if we don't allow negative edges?

```
• n * O(Dijkstra's Algorithm) = O(n m lg n)
```

• For sparse graphs: O(n² lg n)

• For dense graphs: O(n³ lg n)

Running time of APSP if we do allow negative edges?

• n \* O(Bellman-Ford) =  $O(n^2 m)$ 

• For sparse graphs: O(n<sup>3</sup>)

• For dense graphs: O(n<sup>4</sup>)

## Consider APSP on dense graphs.

How many values are we going to output?



What is the potential length of a shortest path?

- What is the lower bound on the running time of APSP?
- It is tempting to say that the lower bound is n<sup>3</sup>
- However, this lower bound has yet to be determined
- Consider the matrix multiplication procedure developed by Strassen

# Specialized APSP Algorithm

 Although we can use Bellman-Ford and Dijkstra's algorithms, there are, in fact, specialized APSP algorithms

• The Floyd-Warshall algorithm solves the APSP problem deterministically in O(n<sup>3</sup>) on all types of graph

- It works with negative edge lengths
- Meaning that is is as good as Bellman-Ford for sparse graphs,
- And much better than Bellman-Ford for dense graphs.

## Question

	Sparse Graphs	Dense Graphs
Dijkstra's n times	O(n <sup>2</sup> lg n)	O(n <sup>3</sup> lg n)
Bellman-Ford n times	O(n <sup>3</sup> )	O(n <sup>4</sup> )
Floyd-Warshall	O(n <sup>3</sup> )	O(n <sup>3</sup> )

- What algorithm would you choose for sparse graphs?
  - Dijkstra's n times if there are no negative edges, Floyd-Warshall otherwise
- What algorithm would you choose for dense graphs?
  - Always Floyd-Warshall

## Optimal Substructure for APSP

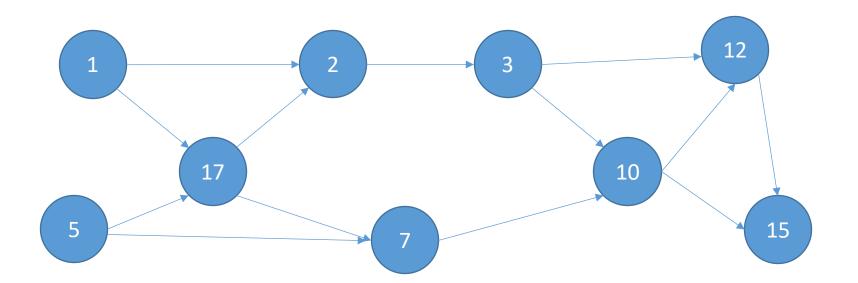
#### Key concept:

- label the vertices 1 though n (giving them an arbitrary order),
- and then introduce the notation  $V^{(k)} = \{1, 2, ..., k\}$

- Assume, for now, that the graph does not include a negative cycle
- Fix a source vertex i, a destination vertex j, and a value for k
- Then let P be the shortest  $i \rightarrow j$  path with <u>internal</u> nodes from  $V^{(k)}$

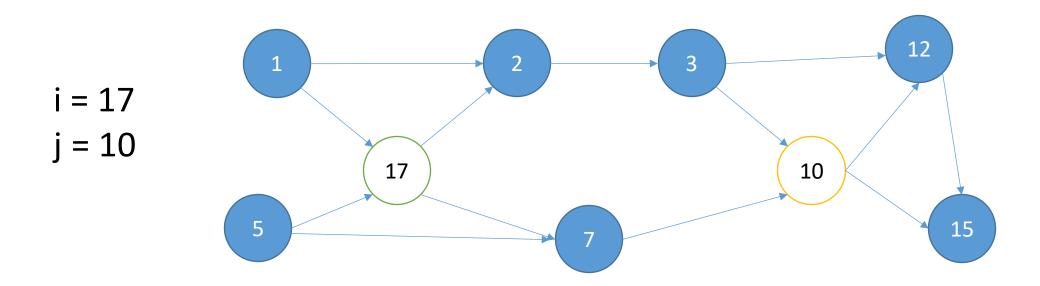
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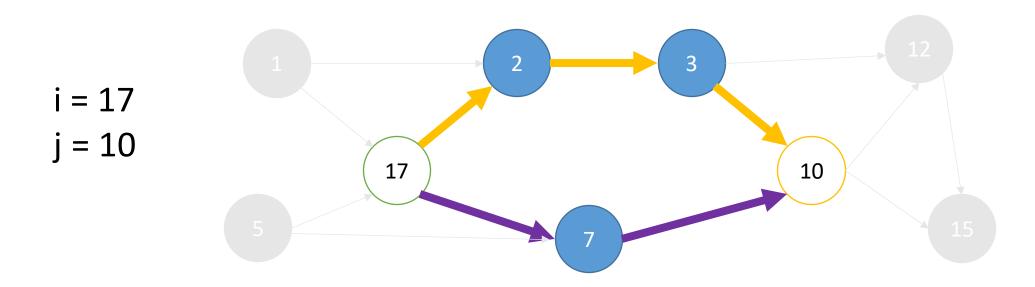
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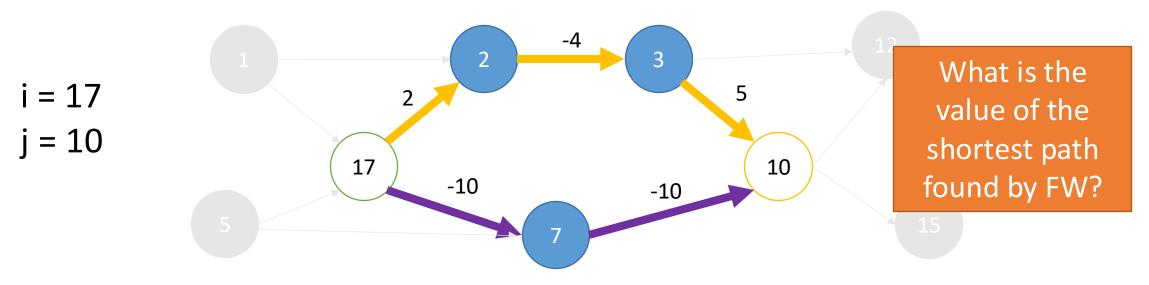
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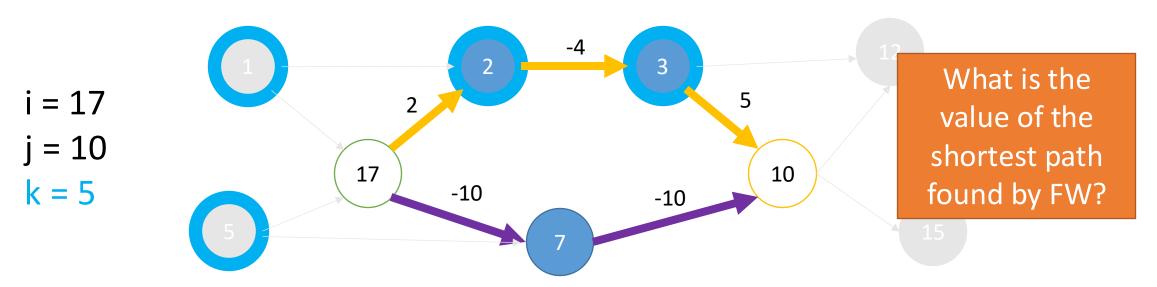
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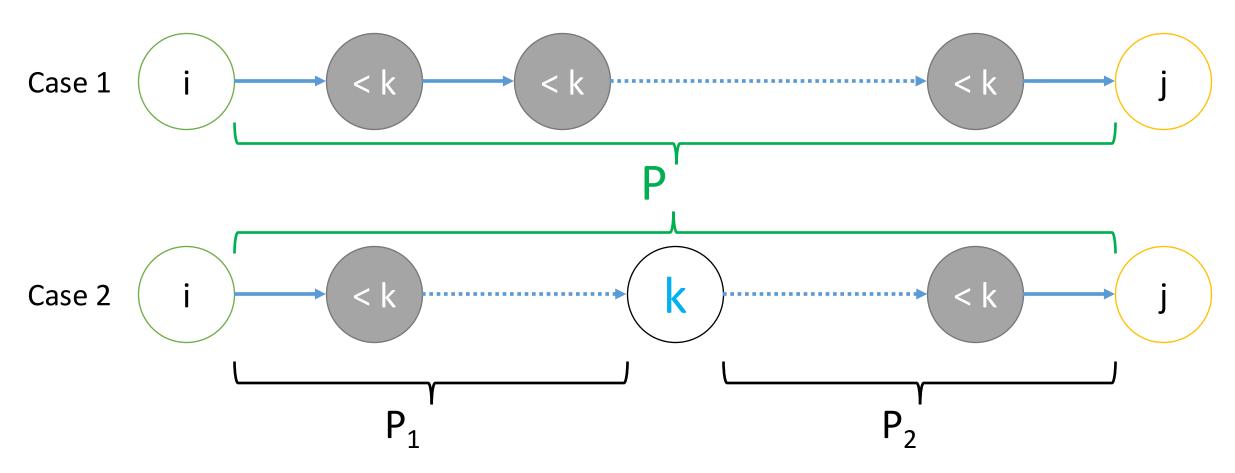


## Optimal Substructure Lemma

Suppose that G has no negative cycles. Let P be the shortest (cycle-free) path  $i \rightarrow j$ , where all internal nodes come from  $V^{(k)}$ . Then:

- Case 1: if k is not internal to P, then P is also a shortest path  $i \rightarrow j$  with all internal nodes from  $V^{(k-1)}$ .
- Case 2: if k is internal to P, then:
  - Let  $P_1$  = the shortest  $i \rightarrow k$  path with nodes from  $V^{(k-1)}$ , and
  - Let  $P_2$  = the shortest  $k \rightarrow j$  path with nodes from  $V^{(k-1)}$
  - Effectively, k splits the path into two optimal subproblems

## Picture of our cases



# Floyd-Warshall Algorithm Base Cases

Let A = 3D array, where A[i, j, k] = the length of the shortest i  $\rightarrow$  j path with all internal nodes from  $\{1, 2, ..., k\}$ 

Which index (i, j, or k) do you think represents our base case?

What is the value of A[i, j, 0] when...

- i = j? 0
- there is a direct edge from i to j c<sub>ij</sub>
- there is no edge directly connecting i to j □

```
FUNCTION FloydWarshall (graph)
   # Base 1 indexing for vertices labeled 1 through n
   pathLengths = [n by n by (n + 1) array]
   # Base case
   FOR vFrom IN [1 \dots = n]
      FOR vTo IN [1 \dots = n]
         IF i == j
            length = 0
         ELSE IF graph.hasEdge(vFrom, vTo)
            length = graph.edges[vFrom][vTo].weight
         ELSE
            length = INFINITY
         pathLengths[vFrom][vTo][0] = length
   # Table building
   continued next slide...
```

```
FUNCTION FloydWarshall (graph)
   # Base 1 indexing for vertices labeled 1 through n
   pathLengths = [n by n by (n + 1) array]
   # Base case
   cut from previous slide...
   # Table building
   FOR k IN [1 ..= n]
      FOR vFrom IN [1 \dots = n]
         FOR vTo IN [1 ..= n]
            # Case 1
            withoutK = pathLengths[vFrom][vTo][k - 1]
            # Case 2
            withKSubPathA = pathLengths[vfrom][k][k - 1]
            with KSubPathB = pathLengths [k] [vTo] [k - 1]
            pathLengths[vFrom][vTo][k] = min(
               withoutK,
               withKSubPathA + withKSubPathB
```

# Floyd-Warshall Algorithm

#### Running time?

• O(n<sup>3</sup>)

#### Correctness?

Substructure lemma

- Where are the final answers?
- How does it handle negative cycles?
- Reconstruction is similar to other dynamic programming problems.

```
# Table building
FOR k IN [1 ..= n]
   FOR vFrom IN [1 \dots = n]
      FOR vTo IN [1 \dots = n]
         # Case 1
         withoutK = pathLengths[vFrom][vTo][k - 1]
         # Case 2
         withKSubPathA = pathLengths[vfrom][k][k - 1]
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         pathLengths[vFrom][vTo][k] = min(
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