

REVIEW

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CS 140 – Spring 2023

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Admin

Final

- posted on Gradescope
- due Wednesday (4/10) at 11:59pm (seniors: 4/4 at noon)
- time-limited (3 hours – with some flexibility to scan, etc.)
- You may use:
 - the book
 - your notes
 - the class notes
 - the assignments
 - ONLY these things
- Do NOT discuss it with anyone until after Wednesday at 11:59pm

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Test taking advice

- Read the questions carefully!
- Don't spend too much time on any problem
 - if you get stuck, move on and come back
- When you finish answering a question, reread the question and make sure that you answered everything the question asked
- Think about how you might be able to reuse an existing algorithm/approach
- Show your work (I can't give you partial credit if I can't figure out what went wrong)
- Don't rely on the book/notes for conceptual things
 - Do rely on the notes for a run-time you may not remember, etc.

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High-level approaches

Algorithm tools

- Divide and conquer
 - assume that we have a solver, but that can only solve sub-problems
 - define the current problem with respect to smaller problems
 - Key: sub-problems should be non-overlapping
- Dynamic programming
 - Same as above
 - Key difference: sub-problems are **overlapping**
 - Once you have this recursive relationship:
 - figure out the data structure to store sub-problem solutions
 - work from bottom up (or memoize)

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High-level approaches

Algorithm tools cont.

- Greedy
 - Same idea: most greedy problems can be solve using dynamic programming (but generally slower)
 - Key difference: Can decide between overlapping sub-problems without having to calculate them (i.e. we can make a local decision)
- Flow
 - Min-capacity cut
 - Bottleneck edge
 - Matching problems
 - Numerical maximization/minimization problems
- Linear programming (very light coverage)

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Data structures

A data structure

- Stores data
- Supports access to/questions about data efficiently
 - the different bias towards different actions
- No single best data structure

Fast access/lookup?

- If keys are sequential: array
- If keys are non-sequential or non-numerical: hashtable
- Guaranteed run-time/ordered: balanced binary search tree

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Data structures

Min/max?

- heap
- binomial heaps

Fast insert/delete at positions?

- linked list

Others

- stacks/queues
- extensible data structures
- balanced BSTs
- disjoint sets

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Graphs

Graph types

- directed/undirected
- weighted/unweighted
- trees, DAGs
- cyclic
- connected

Algorithms

- connectedness
- contains a cycle
- traversal
 - dfs
 - bfs

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Graphs

Graph algorithms cont.

- ▣ minimum spanning trees (Prim's, Kruskal's)
- ▣ shortest paths
 - single source (BFS, Dijkstra's, Bellman-Ford)
 - all pairs (Johnson's, Floyd-Warshall)
- ▣ topological sort
- ▣ flow

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Other topics...

Analysis tools

- ▣ recurrences (master method, recurrence trees)
- ▣ big-O
- ▣ amortized analysis

NP-completeness

- ▣ proving NP-completeness
- ▣ reductions

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Proofs: general

Be clear and concise

Make sure you state assumptions and justify each step

Make sure when you're done you've shown what you need to show

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Proof by induction

1. State what you're trying to prove
We show that XXX using proof by induction
2. Prove base case
3. State the inductive hypothesis
4. Inductive proof
 - a. State what you want to show (may include a variable change, e.g., k in instead of n)
 - b. Show a step by step derivation from the left hand side resulting in the right hand side. Give justifications for steps that are non-trivial

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Prof by induction: structural

[5 points] A full binary tree is a tree where every node is either a leaf or has two children. (Note this is different than a complete binary tree where all levels are full.) Prove using induction that in a full binary tree the number of internal nodes, I , is equal to the number of leaves, L , minus 1, i.e., $I = L - 1$.

1. State what you're trying to prove
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4. Inductive proof
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Other (important) places we saw proofs

Recurrences (substitution method)

Big O (needed find constants c no)

Greedy algorithm correctness (proof by contradiction or stays ahead—induction —)

Proof of algorithm correctness (MSTs, Flow)

NP-completeness (proving correctness of reductions)

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Recurrences

Three ways to solve:

- Substitution
- Recurrence tree (may still have to use substitution to verify)
- Master method

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Recurrences

$$T(n) = 2T(n/3) + d$$

$$T(n) = aT(n/b) + f(n)$$

if $f(n) = O(n^{\log_b a - \epsilon})$ for $\epsilon > 0$, then $T(n) = \Theta(n^{\log_b a})$

if $f(n) = \Theta(n^{\log_b a})$, then $T(n) = \Theta(n^{\log_b a} \log n)$

if $f(n) = \Omega(n^{\log_b a + \epsilon})$ for $\epsilon > 0$ and $af(n/b) \leq cf(n)$ for $c < 1$
then $T(n) = \Theta(f(n))$

$$T(n) = T(n-1) + \log n$$

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Dynamic programming

Method for solving problems where optimal solutions can be defined in terms of optimal solutions to subproblems

AND

the subproblems are overlapping

Local decisions result in *different* subproblems. Not obvious how to make the first choice.

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DP advice

Write the recursive definition

- What is the input/output to the problem?
- What would a solution look like? What are the options for picking the first component of a solution?
- Assume you have a solver for subproblems. How can you combine the first decision with answer to subproblem.

Define DP structure: what are subproblems indexed by?

State how to fill in the table (including base cases and where the answer is)

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All-pairs shortest paths

V * Bellman-Ford: $O(V^2E)$

Floyd-Warshall: $\theta(V^3)$

Johnson's: $O(V^2 \log V + VE)$

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Floyd-Warshall: Recursive relationship

d_{ij}^k = shortest path from vertex i to vertex j
using only vertices $\{1, 2, \dots, k\}$

Two options:

- 1) Vertex $k+1$ doesn't give us a shorter path
- 2) Vertex $k+1$ does give us a shorter path

$$d_{ij}^{k+1} = \min(d_{ij}^k, d_{i(k+1)}^k + d_{(k+1)j}^k)$$

Pick whichever is shorter

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Floyd-Warshall

Calculate d_{ij}^k for increasing k , i.e. $k = 1$ to V

Floyd-Warshall($G = (V, E, W)$):

$d^0 = W$ // initialize with edge weights

for $k = 1$ to V

 for $i = 1$ to V

 for $j = 1$ to V

$d_{ij}^k = \min(d_{ij}^{k-1}, d_{ik}^{k-1} + d_{kj}^{k-1})$

return d^V

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Johnson's algorithm

Create G' with one extra node s with 0 weight edges to all nodes
run Bellman-Ford(G', s)

if no negative-weight cycle

 reweight edges in G with $h(v)$ =shortest path from s to v

$$\hat{w}(u, v) = w(u, v) + h(u) - h(v)$$

 run Dijkstra's from every vertex

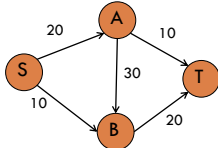
 reweight shortest paths based on G

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Flow graph/networks

Flow network

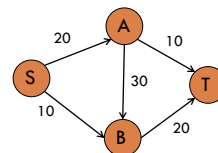
- ▣ directed, weighted graph (V, E)
- ▣ positive edge weights indicating the "capacity" (generally, assume integers)
- ▣ contains a single source $s \in V$ with no incoming edges
- ▣ contains a single sink/target $t \in V$ with no outgoing edges
- ▣ every vertex is on a path from s to t



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Max flow problem

Given a flow network: *what is the maximum flow we can send from s to t that meet the flow constraints?*



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Network flow properties

If one of these is true then all are true (i.e. each implies the the others):

f is a maximum flow

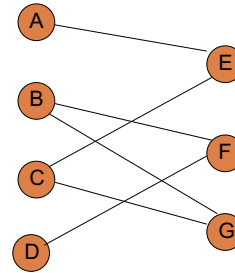
G_f (residual graph) has no paths from s to t

$|f|$ = minimum capacity cut

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Application: bipartite graph matching

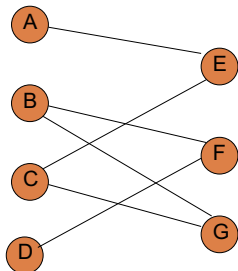
Bipartite graph – a graph where every vertex can be partitioned into two sets X and Y such that all edges connect a vertex $u \in X$ and a vertex $v \in Y$



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Application: bipartite graph matching

Bipartite matching problem: find the *largest* matching in a bipartite graph

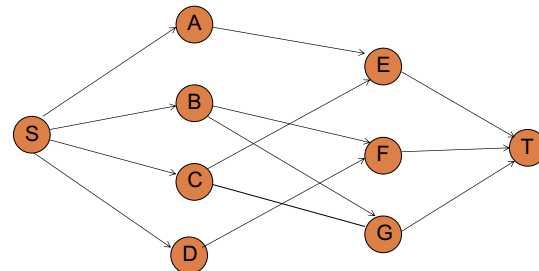


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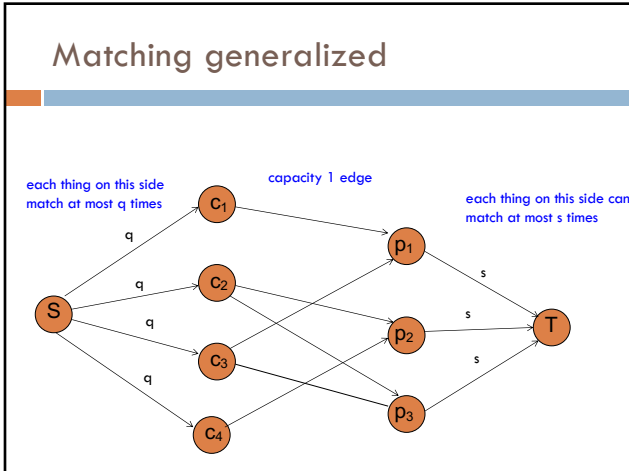
Application: bipartite graph matching

Setup as a flow problem:

all edge weights are 1



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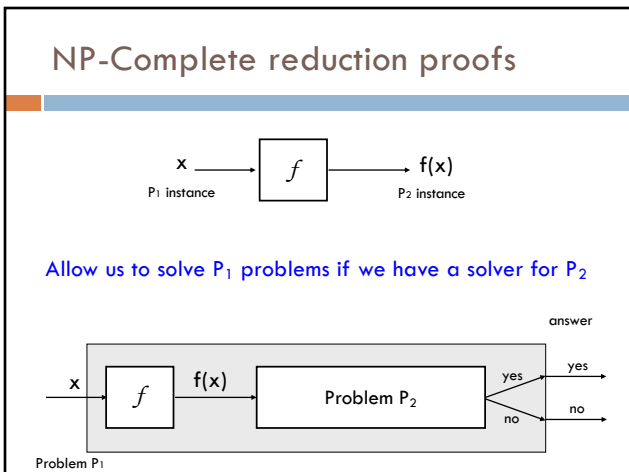
NP-Complete

A problem is NP-Complete if

1. It is in NP (verifiable in polynomial time)
2. It is NP-Hard (there exists a polynomial-time reduction from all known NP-Hard problems)

- (We can show this by showing a reduction from just one NP-Hard problem)

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How many slides this semester?

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