

Floyd-Warshall Algorithm For Solving the All-Pairs Shortest Path Problem

<https://cs.pomona.edu/classes/cs140/>

Outline

Topics and Learning Objectives

- Discuss and analyze the Floyd-Warshall Algorithm
- 

Exercise

- None

All-Pairs Shortest Path Problem

There is
no start
vertex

Compute the shortest path from every vertex to every other vertex

- Input: a weighted graph
- Output:
 - Shortest path from $u \rightarrow v$ for all values of u and v
 - Report that a negative cycle has been discovered
- Can we solve this problem with what we know already?

SSSP \rightarrow APSP

How do we turn a solution to the single-source shortest path (SSSP) problem into a solution for the all-pairs shortest path (APSP) problem?

- This is called a reduction!
- How many times do we need to run a SSSP procedure for APSP?

- a. 1
- b. $n - 1$
- c. n
- d. n^2

BF
Dijk

What SSSP algorithms do we know?

Running time of APSP if we **don't** allow negative edges?

- $n * O(\text{Dijkstra's Algorithm}) = O(n m \lg n)$
- For **sparse** graphs: $O(n^2 \lg n)$
- For **dense** graphs: $O(n^3 \lg n)$

Running time of APSP if we **do** allow negative edges?

- $n * O(\text{Bellman-Ford}) = O(n^2 m)$
- For **sparse** graphs: $O(n^3)$ ↙
- For **dense** graphs: $O(n^4)$ ↙

Consider APSP on **dense** graphs.

- How many values are we going to output?

$$n^2$$

- What is the potential length of a shortest path?

$$n - 1$$

- What is the lower bound on the running time of ASPS?
- It is tempting to say that the lower bound is n^3
- However, this lower bound has yet to be determined
- Consider the matrix multiplication procedure developed by Strassen

Specialized APSP Algorithm

- Although we can use Bellman-Ford and Dijkstra's algorithms, there are, in fact, specialized APSP algorithms
- The Floyd-Warshall algorithm solves the APSP problem deterministically in $O(n^3)$ on all types of graph
- It works with negative edge lengths
- Meaning that it is as good as Bellman-Ford for sparse graphs,
- And much better than Bellman-Ford for dense graphs.

Question

	Sparse Graphs	Dense Graphs
Dijkstra's n times	$O(n^2 \lg n)$	$O(n^3 \lg n)$
Bellman-Ford n times	$O(n^3)$	$O(n^4)$
Floyd-Warshall	$O(n^3)$	$O(n^3)$

- What algorithm would you choose for sparse graphs?
 - Dijkstra's n times if there are no negative edges, Floyd-Warshall otherwise
- What algorithm would you choose for dense graphs?
 - Always Floyd-Warshall

Optimal Substructure for APSP

Key concept:

- label the vertices 1 through n (giving them an arbitrary order),
- and then introduce the notation $V^{(k)} = \{1, 2, \dots, k\}$

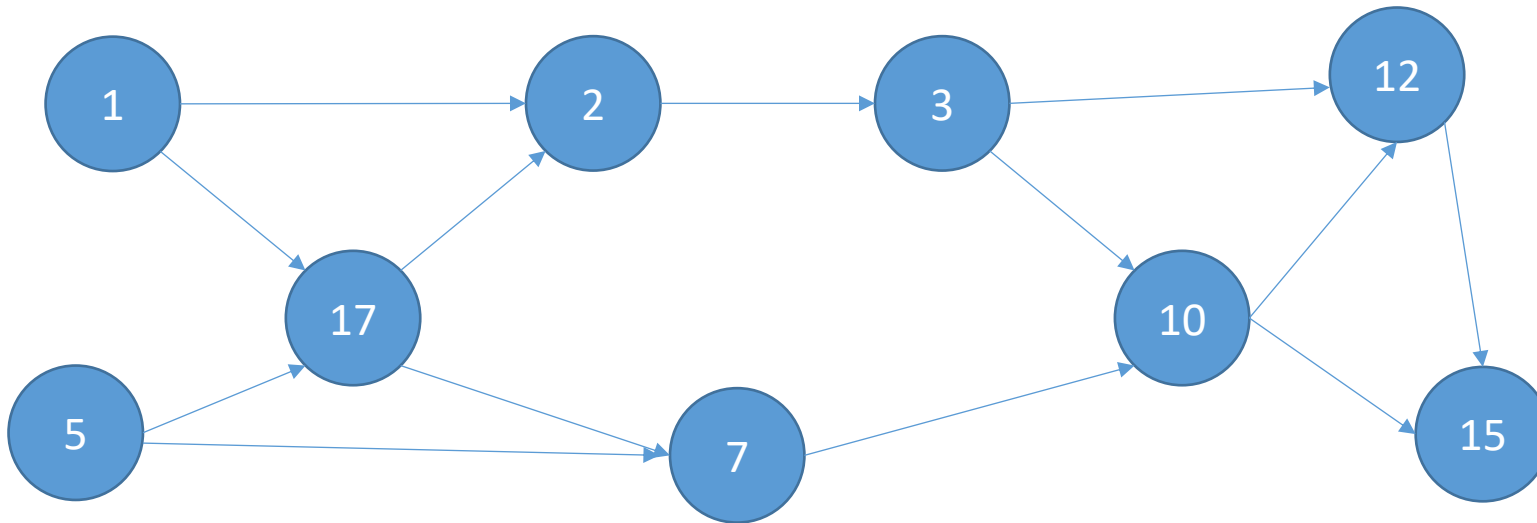
Optimal Substructure Lemma:

- Assume, for now, that the graph does **not** include a **negative cycle**
- Fix a source vertex i , a destination vertex j , and a value for k
- Then let P be the shortest $i \rightarrow j$ path with internal nodes from $V^{(k)}$

Example Substructure

Optimal Substructure Lemma:

- Fix a source vertex i , a destination vertex j , and a value for k
- Then let P be the shortest $i \rightarrow j$ path with internal nodes from $V^{(k)}$

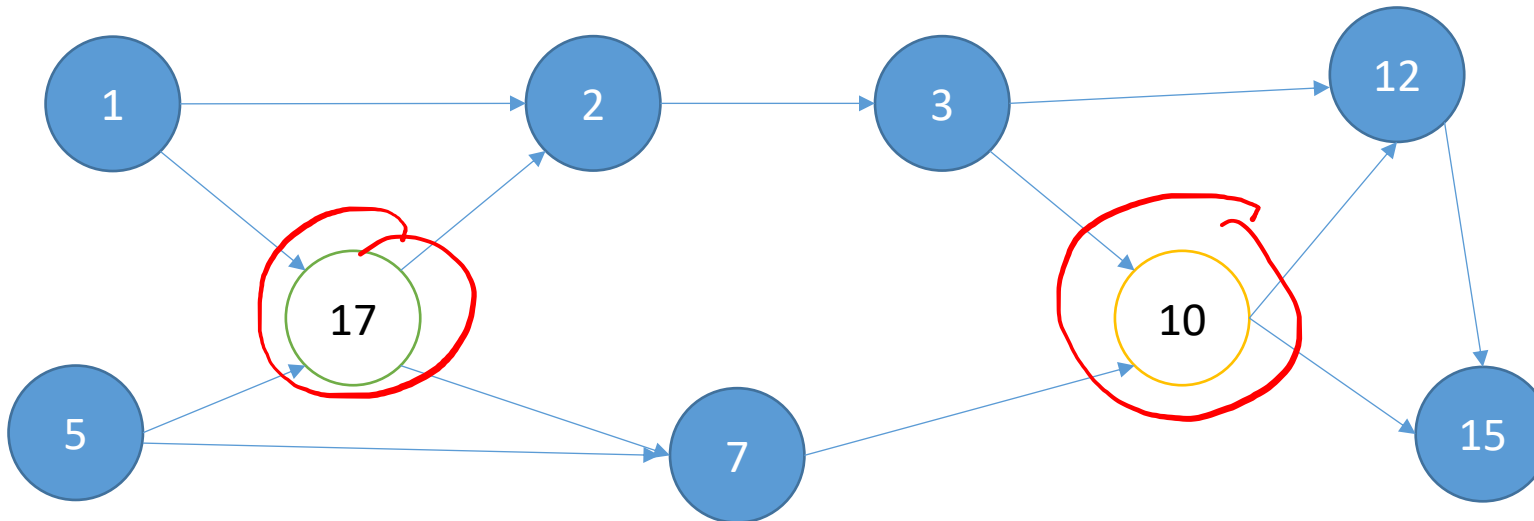


Example Substructure

Optimal Substructure Lemma:

- Fix a source vertex i , a destination vertex j , and a value for k
- Then let P be the shortest $i \rightarrow j$ path with internal nodes from $V^{(k)}$

$i = 17$
 $j = 10$

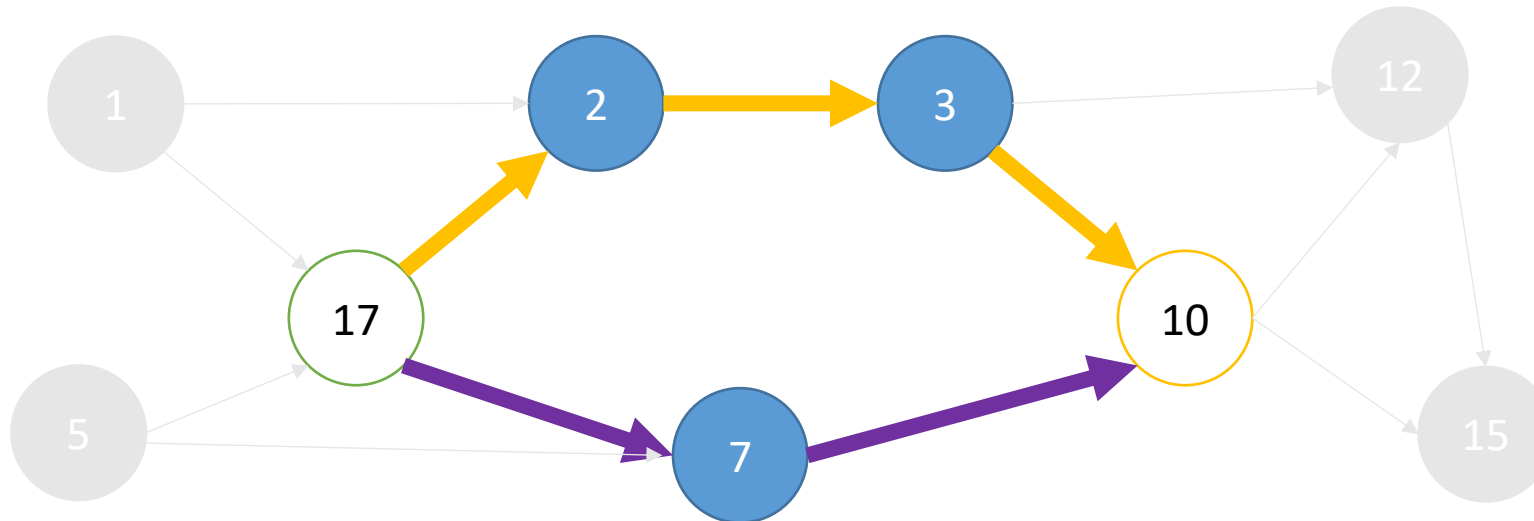


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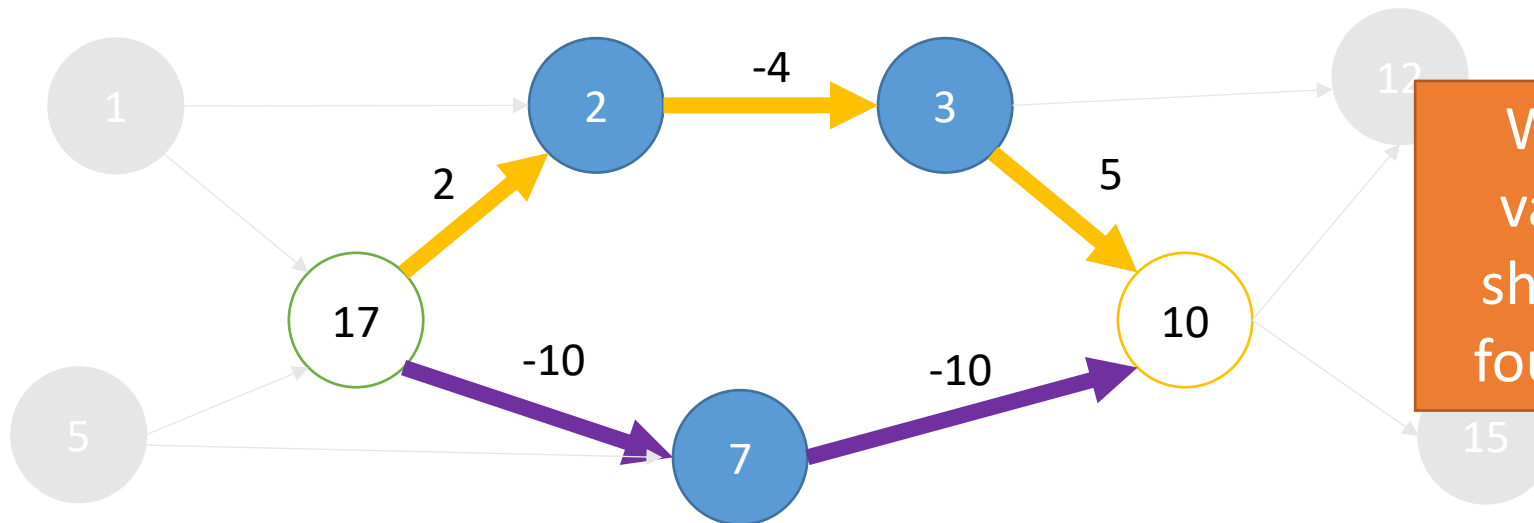


Example Substructure

Optimal Substructure Lemma:

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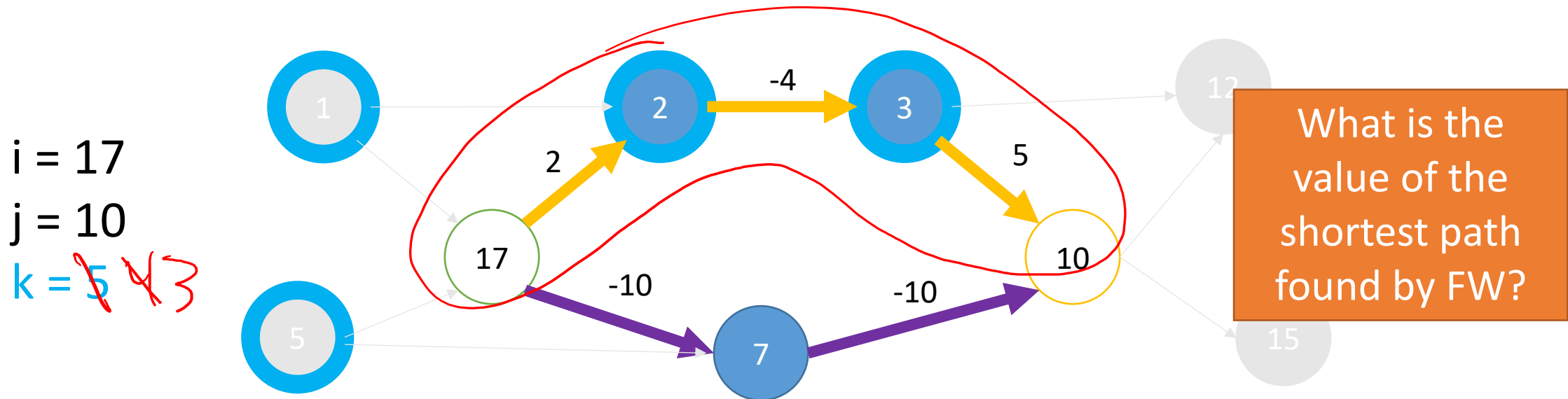


What is the value of the shortest path found by FW?

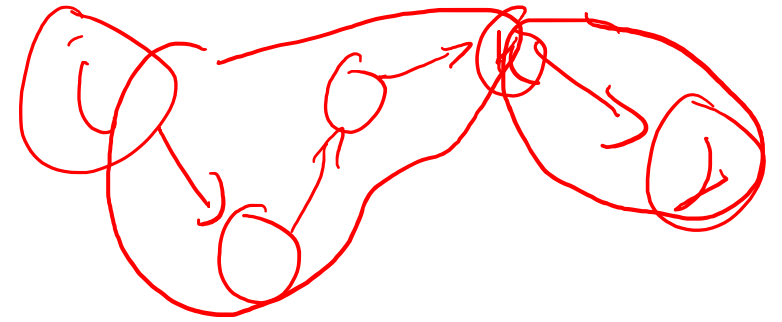
Example Substructure

Optimal Substructure Lemma:

- Fix a source vertex i , a destination vertex j , and a value for k
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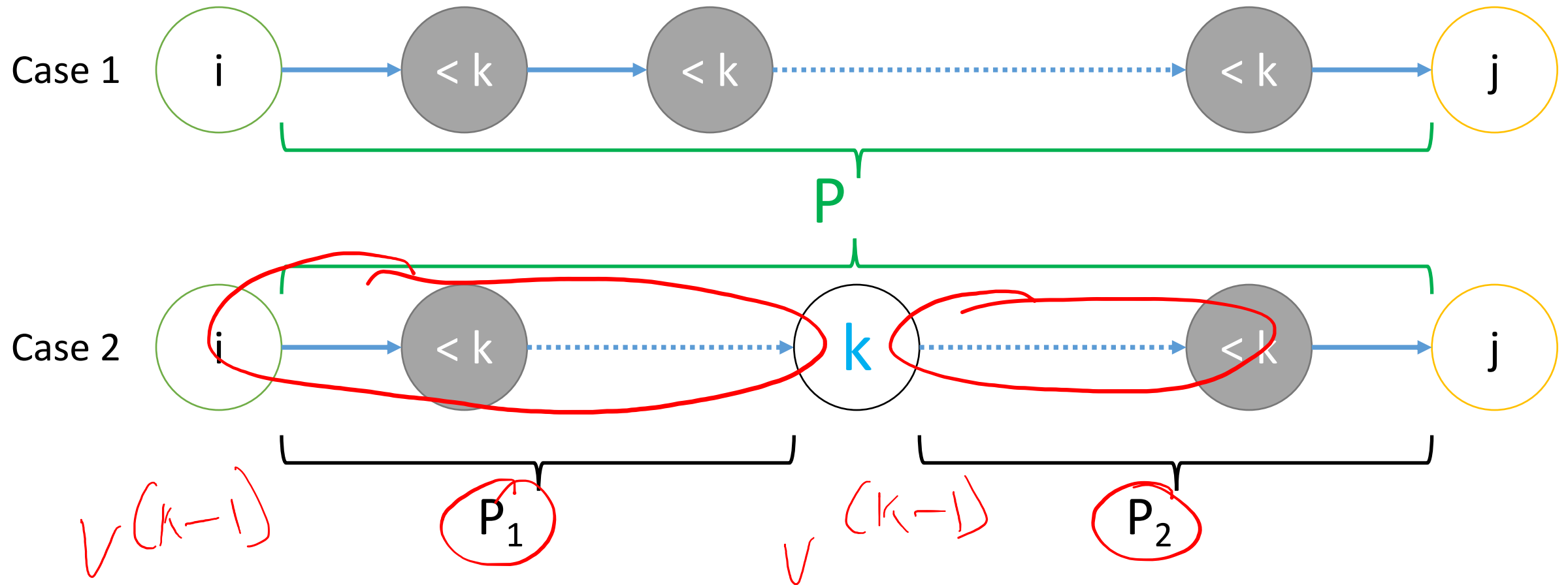
Optimal Substructure Lemma



Suppose that G has no negative cycles. Let P be the shortest (cycle-free) path $i \rightarrow j$, where all internal nodes come from $V^{(k)}$. Then:

- Case 1: if k is not internal to P , then P is also a shortest path $i \rightarrow j$ with all internal nodes from $V^{(k-1)}$.
- Case 2: if k is internal to P , then:
 - Let P_1 = the shortest $i \rightarrow k$ path with nodes from $V^{(k-1)}$ and
 - Let P_2 = the shortest $k \rightarrow j$ path with nodes from $V^{(k-1)}$
 - Effectively, k splits the path into two optimal subproblems

Picture of our cases



Anch

Floyd-Warshall Algorithm Base Cases

Let A = 3D array, where $A[i, j, k]$ = the length of the shortest $i \rightarrow j$ path with all internal nodes from $\{1, 2, \dots, k\}$

- Which index (i , j , or k) do you think represents our base case?

What is the value of $A[i, j, 0]$ when...

- $i = j$? 0
- there is a direct edge from i to j c_{ij}
- there is no edge directly connecting i to j ∞

```
FUNCTION FloydWarshall(graph)
    # Base 1 indexing for vertices labeled 1 through n
    pathLengths = [n by n by (n + 1) array]

    # Base case
    FOR vFrom IN [1 ..= n]
        FOR vTo IN [1 ..= n]

            IF i == j
                length = 0

            ELSE IF graph.hasEdge(vFrom, vTo)
                length = graph.edges[vFrom][vTo].weight

            ELSE
                length = INFINITY

            pathLengths[vFrom][vTo][0] = length

    # Table building
    continued next slide...
```

FUNCTION FloydWarshall(graph)

Base 1 indexing for vertices labeled 1 through n
pathLengths = [n by n by (n + 1) array]

Base case

cut from previous slide...

Table building

FOR k **IN** [1 ..= n]

FOR vFrom **IN** [1 ..= n]

FOR vTo **IN** [1 ..= n]

Case 1

 withoutK = pathLengths[vFrom][vTo][k - 1]

Case 2

 withKSubPathA = pathLengths[vfrom][k][k - 1]

 withKSubPathB = pathLengths[k][vTo][k - 1]

 pathLengths[vFrom][vTo][k] = min(
 withoutK,
 withKSubPathA + withKSubPathB
)

Floyd-Warshall Algorithm



Running time?

- $O(n^3)$

Correctness?

- Substructure lemma

- Where are the final answers?
- How does it handle negative cycles?
- Reconstruction is similar to other dynamic programming problems.

```
# Table building
FOR k IN [1 ..= n]
  FOR vFrom IN [1 ..= n]
    FOR vTo IN [1 ..= n]

      # Case 1
      withoutK = pathLengths[vFrom][vTo][k - 1]

      # Case 2
      withKSubPathA = pathLengths[vFrom][k][k - 1]
      withKSubPathB = pathLengths[k][vTo][k - 1]

      pathLengths[vFrom][vTo][k] = min(
        withoutK,
        withKSubPathA + withKSubPathB
      )
```