Kruskal's MST Algorithm

https://cs.pomona.edu/classes/cs140/

Outline

Topics and Learning Objectives

- Introduce Kruskal's algorithms for MSTs
- Discuss disjoint sets

Exercise

• Kruska's exercise

Trick Question for the Day

Which is asymptotically bigger?

 $O(m \lg n)$ or $O(m \lg m)$

Minimum-Spanning-Tree Overview

Input: an undirected graph where each edge has an associated cost

Output: a minimum-spanning-tree

- 1. Connects the entire graph as a tree, but
- 2. Has a minimal cost

Assumptions:

- 1. The input graph is connected
- 2. The edges costs are distinct (only necessary/useful for our proof)

Cut Property: if e is the cheapest edge crossing a cut, then it must be in the MST

Kruskal's

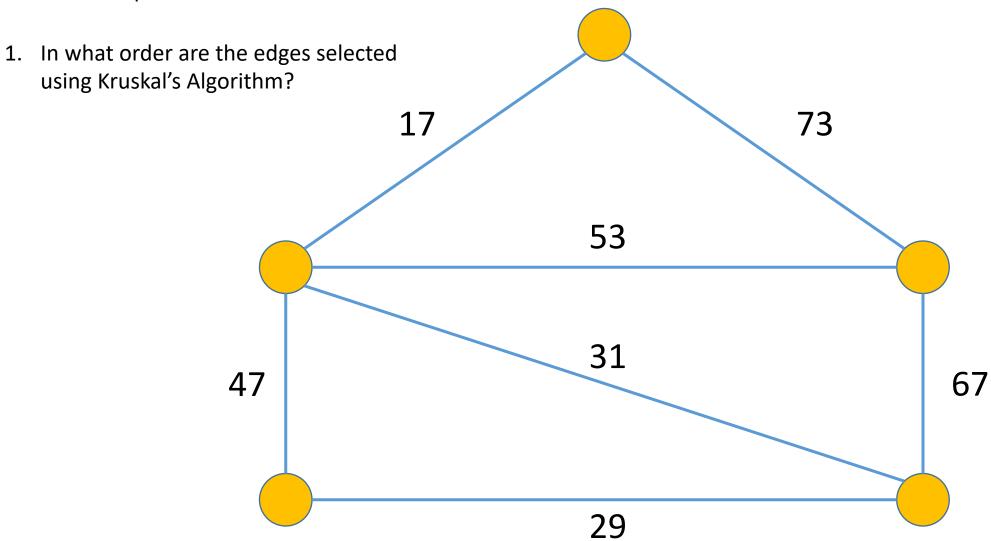
A greedy algorithm for finding the minimum spanning tree

Why are we learning another one?

- Kruskal's will motivate a new data structure: Union-Find (disjoint-set)
- It will also let us talk a bit about clustering

Can you think of another greedy algorithm for solving MST?

Exercise question 1.



Theorem: Kruskal's algorithm is correct (computes the MST)

Let T* = the output of Kruskal's algorithm

Graph/Cut/Tree Lemmas and Properties

- Empty Cut Lemma: a graph is not connected if there exists a cut (A, B) with zero crossing edges
- Double Crossing Lemma: suppose the cycle C has an edge crossing the cut
 (A, B), then there must be at least one more edge in C that crosses the cut
- No Cycle Corollary: if e is the only edge crossing some cut (A, B), then it is not in any cycle
- <u>Cut Property</u>: if e is the cheapest edge that crosses the cut (A, B) then it must be in the MST

Theorem: Kruskal's algorithm is correct (computes the MST)

Let T* = the output of Kruskal's algorithm

Does Kruskal's output a spanning tree (what are the properties)?

- No cycles
- Connected

```
Sort E by edge cost
T = empty

For e in E:
   if T U {e} has no cycles
   add e to T
```

```
Sort E by edge cost
T = empty

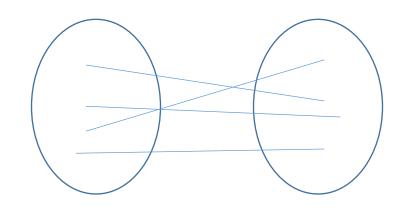
For e in E:
    if T U {e} has no cycles
    add e to T
```

Theorem: Kruskal's algorithm is correct (computes the MST)

Let T* = the output of Kruskal's algorithm

Does Kruskal's output a spanning tree (what are the properties)?

- No cycles (this is given by the definition of the algorithm)
- Connected



Proof of Connectivity

- Given the Empty Cut Lemma, we only need to show that Kruskal's produces a tree T* that crosses every cut.
- Fix a cut (A,B)
- Since G is connected, at least one of its edges crosses (A,B)
- Kruskal's algorithm considers each edge once
- Let's fast-forward to the first time that it encounters an edge crossing (A,B)
- Claim: this 1st edge is guaranteed to be in T*
- Given the No Cycle Corollary the claim is true
- It is also the minimum edge to cross the cut (sorted edges)

For the second part of the proof, we need to prove that T* is minimal

We just finished proving that Kruskal's outputs some spanning tree T*

Claim: every edge is justified by the <u>Cut Property</u>

- Remember that satisfying the <u>Cut Property</u> implies that we have an MST
- This was very explicit in Prim's Algorithm

Prim's Minimum Spanning Tree Algorithm

```
X = \{s\}
T = empty
while X is not V:
     let e = (u, v) be the cheapest edge of G
         with u in X and v not in X
     add e to T
     add v to X
```

Proving that we can use the <u>Cut Property</u>

- Consider each iteration where edge (u, v) is added to T*
- Since T* U {(u, v)} has no cycle, T* currently has no u->v path
- Thus, there must be a cut (A, B) separating u and v. For example:
 - All findable from u in A
 - All findable form v in B
 - All other vertices can be partitioned arbitrarily
- Hence, (u, v) is the first crossing cut for (A, B)
- Additionally, it must be the cheapest such cut since we sorted the edges
- Finally, the edge (u, v) is justified by the <u>Cut Property</u>

What have we done?

We proved that Kruskal's outputs a spanning tree

- No cycles by definition
- Connectivity by the <u>Empty Cut Lemma</u>

We then proved that Kruskal's outputs the minimum spanning tree

- The <u>Cut Property</u> implies that we are left with the MST
- We showed that Kruskal's uses the <u>Cut Property</u> because the edges are sorted

Implementation of Kruskal's

```
Sort E by edge cost
                                                         O(m \lg m)
T = empty
For e in E:
                                                            O(m)
     if T U {e} has no cycles
                                                     Naïvely O(n+m)
           add e to T
```

O(m lg m) + O(m) * O(n+m)

O(mn+m²)

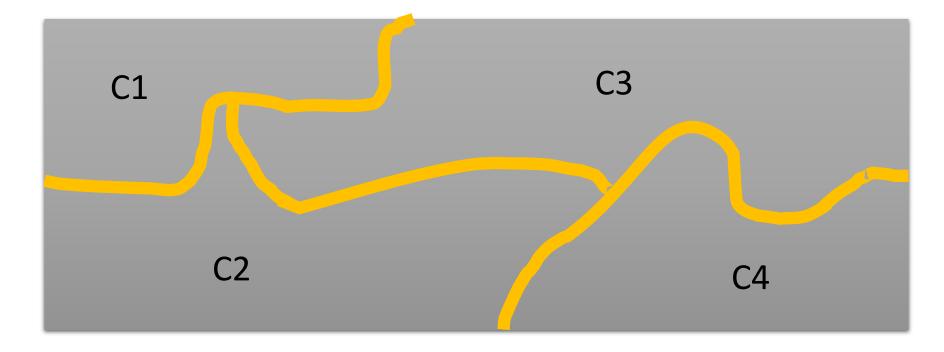
```
Sort E by edge cost
T = empty
```

```
For e in E:
    if T U {e} has no cycles
    add e to T
```

What can we change (should we change) to do better than O(mn)?

The Union-Find Data Structure

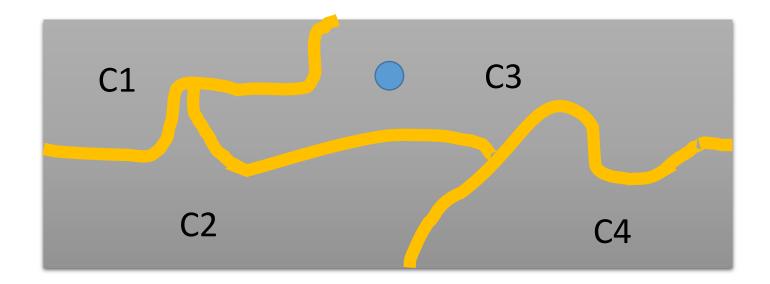
- Also known as the disjoint-set data structure
- Used to maintain a partition of objects



Union-Find

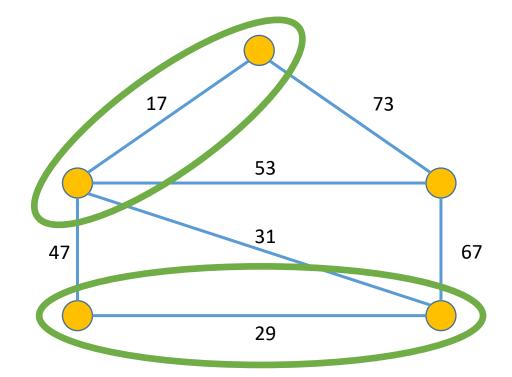
Operations:

- Find(x): return the name of the group to which x belongs
- Union(Ci, Cj): merge the two partitions into a single partition



How does this help us with Kruskal's?

- What do we store in the data structure?
- What makes a group/partition?



```
Sort E by edge cost
T = empty
```

Motivation

- Speed up the way in which we check for cycles.
- How would you implement the Union-Find data structure?
- Conceptually, we're going to augment each vertex to include another piece of information: the name of its leader

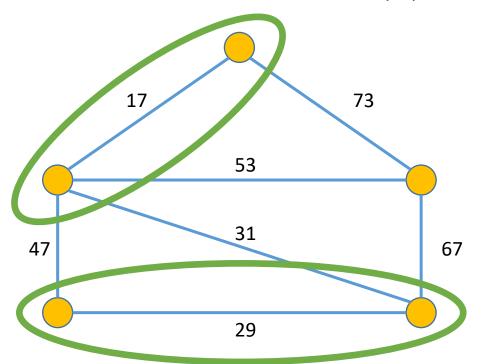
• Invariant: each vertex points to its leader

How long does it take to check for a cycle now?

Checking for cycles

• Given an edge (u, v), we can check if u and v are in the same partition in constant time O(1).

$$Find(u) == Find(v)$$
?

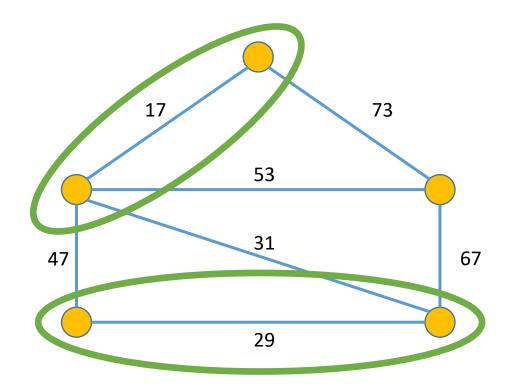


What happens during the next iteration?

What's the catch?

Maintaining the Invariant

• Invariant: each vertex points to its leader



What is the maximum number of vertex leaders that must be fixed after a union?

Exercise Question 2

Union-Find Data Structure

- Put every element in its own partition
 - Every element has its own leader

 Join partitions by copying the leader of the larger partition elements to all elements of the smaller partition

- You can use an array or hash table to keep track of leaders
- No other information/memory is needed

```
Sort E by edge cost
T = empty
```

```
For e in E:
    if T U {e} has no cycles
        add e to T
        union
```

What do we have as a running time now?

What happened?

```
Sort E by edge cost
T = empty
```

```
O(n+m) \rightarrow O(1) (checking leaders)
```

 $O(1) \rightarrow O(n)$ (updating leaders)

Maximum number of leader updates?

How many times can we update the leader of a single vertex?

- We only update the leader of a vertex if we merge it with a bigger partition.
- How many times can we update a vertex's leader?
 - (Or: How many times can we double the size of a partition?)

This is our global view of something happening inside the loop.

```
Sort E by edge cost
                                                                  O(m \lg m)
T = empty
For e in E:
                                                                     O(m)
       if T U {e} has no cycles
                                                       O(1) just for the cycle check
             add e to T
                                                O(n \lg n) for Union (not per iteration)
             union
                                                        Technically this is O(n \lg n + m \lg m)
O(m lg m) — O(n lg n) — O(m) * O(1) —
                                                             O(m lg m)
    Sort
                       Union
```

Loop

Total

Cutting Edge <

1g* X
1g (1g (1g x)))

- Can we do better than O(m lg n)?
- Yes!
- Average O(m) using a randomized algorithm (1995)
- We do not actually know if a deterministic O(m) algorithm exists.
- We do have a deterministic algorithm that is $O(m \alpha(n))$
- α is the inverse Ackermann function
- Which is slower than the Iterated logarithm: Ig*
 - the number of times the logarithm function must be iteratively applied before the result is less than or equal to 1
- An optimal deterministic algorithm was developed in 2002
- But we do not know the exact asymptotic complexity
- Just that it is between O(m) and $O(m \alpha(n))$



x	lg [⋆] x
(<u>-∞</u> , 1] →	0
(1, 2] ->	1
(2, 4)	2
(4, 16)	3
(16, 65536]	4
(65536, 2 ⁶⁵⁵³⁶)	5