## Red-Black Trees (A Balanced BST)

https://cs.pomona.edu/classes/cs140/

Some notes taken from http://www.geeksforgeeks.org/

### Outline

Topics and Learning Objectives

- Discuss tree balancing (rotations, insertions, deletions)
- Prove the balancing characteristic of red-black trees —
- Discuss the running time of red-black tree operations



#### Extra Resources

- Introduction to Algorithms, 3rd, chapter 13
- <u>https://www.cs.usfca.edu/~galles/visualization/RedBlack.html</u>

#### Implementations

Althought Red-Black trees are not the most modern choice, they do appear in

- Java: <u>TreeMap<K,V></u>
- C++: <u>std::map</u>



Not something you should use in practice.

### **Balanced** Binary Search Trees

- Why is balancing important?
- What is the worst case for a binary tree?
- Balanced tree: the height of a balanced tree stays O(lg n) after insertions and deletions
- Many different types of balanced search trees:
  - AVL Tree, Splay Tree, B Tree, Red-Black Tree

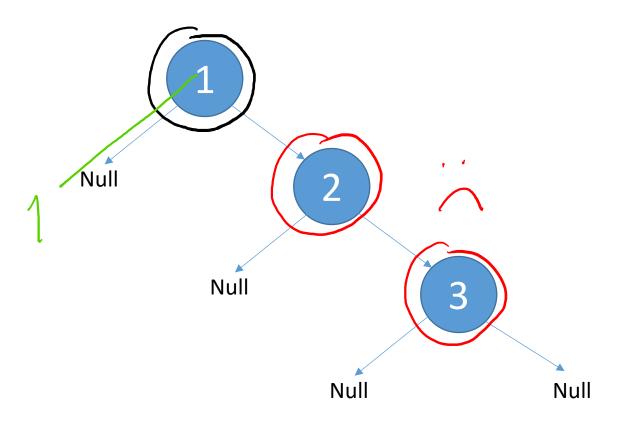
#### **Red**-Black Trees Invariants

- 1. Each node must be labeled either red or black
- NULL NULL MULL

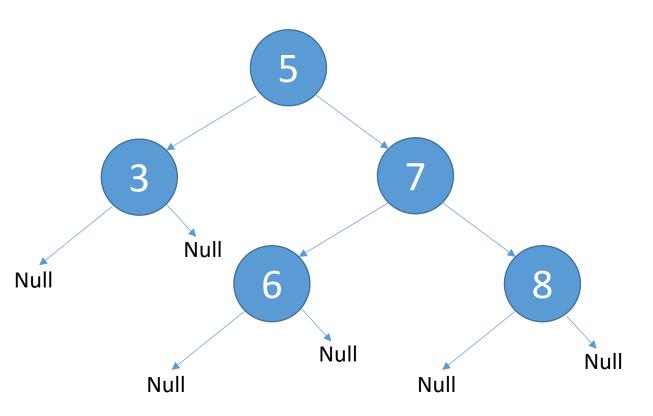
- 2. The root must be labeled black
- 3. The tree cannot have two red nodes in a row (for any red node its parent, left, and right must be black)
- 4. Every root-NULL path must include the same number of black nodes

Can a Red-Black tree of any height have only black nodes? VeS

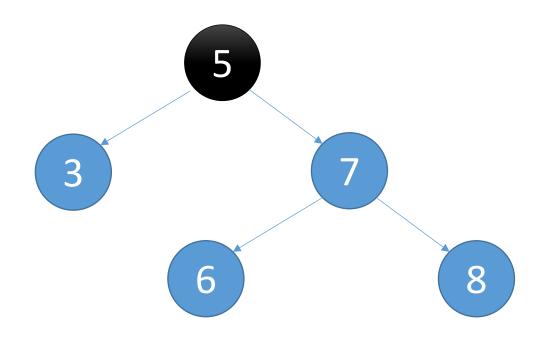
Can a "chain" be a red-black tree?



- 1. Each node must be labeled either red or black
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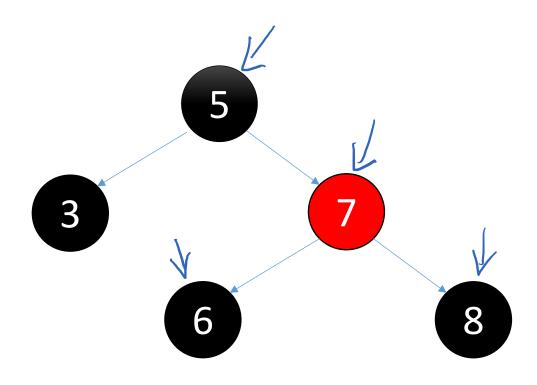
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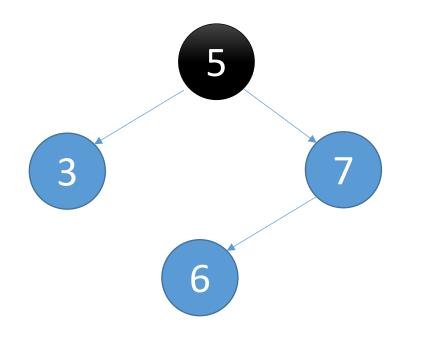
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# **Red**-Black Trees We could also move the black color down one level

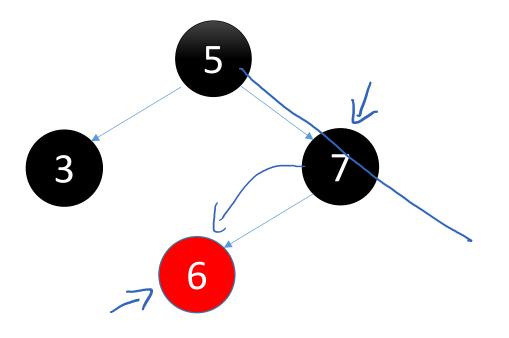
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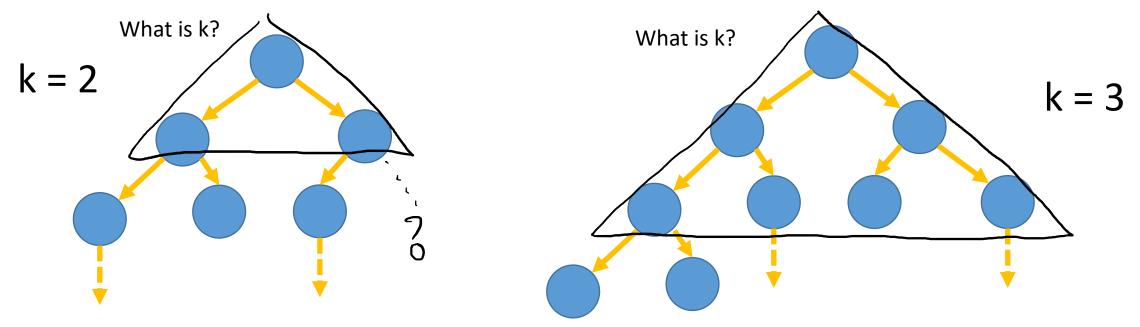


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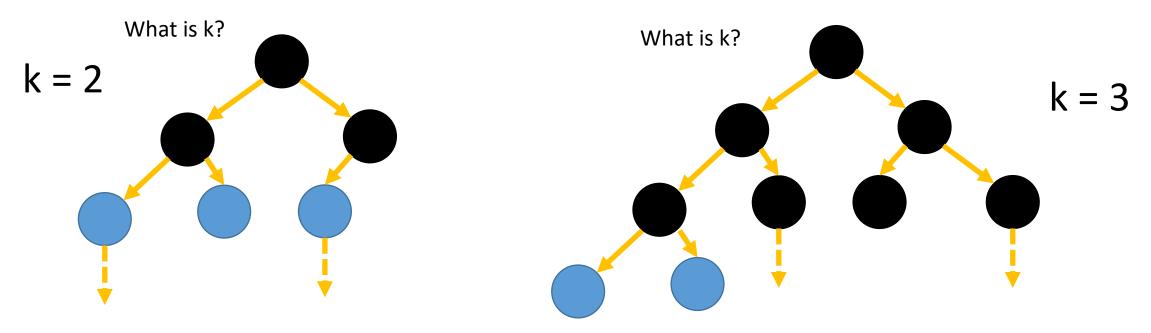
#### How did **Red**-Black Trees get their name?

• Claim: every Red-Black tree has a  $t_{height} \le 2 \lg(n+1) = O(\lg n)$ 

 Observation: if every root-NULL path has ≥ k nodes, then the tree includes a perfectly balanced top portion with k levels



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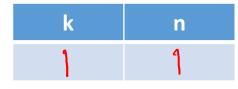


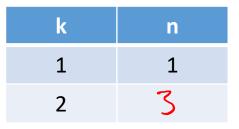
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What is the <u>minimum</u> number of nodes (n) in the tree based on k?

Exercise question 1

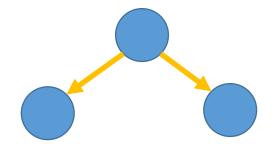






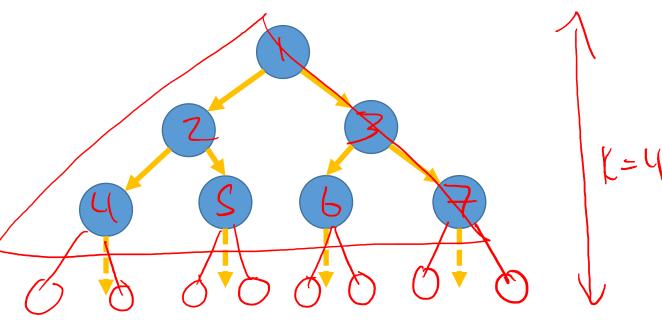
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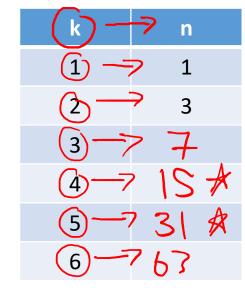
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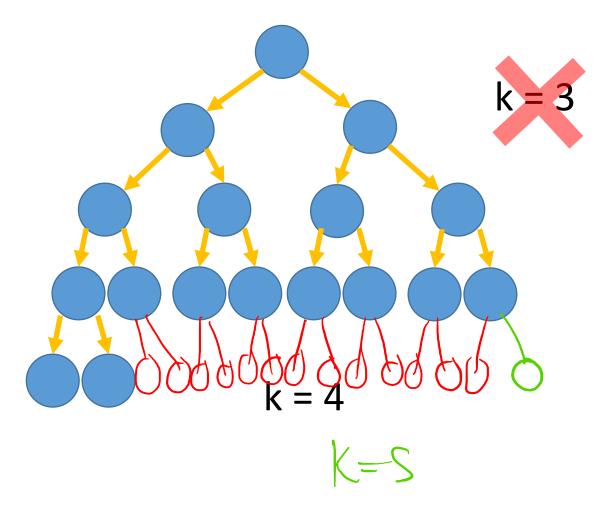
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- Claim: every Red-Black tree has a  $t_{height} \le 2 \lg(n+1)$
- Observation: if every root-NULL path has ≥ k nodes, then the tree includes a perfectly balanced top portion with k levels

What is the <u>minimum</u> number of nodes (n) in the tree based on k?



2<sup>k</sup> - 1 was the <u>minimum</u> number of nodes

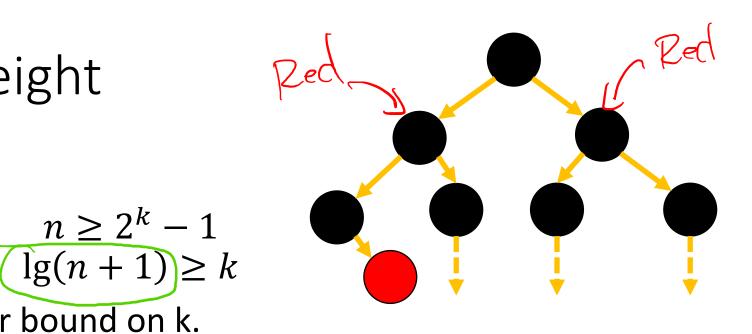
 $n \ge 2^k - 1$  $\lg(n+1) \ge k$ 

• So, we have:

- So, we now have an upper bound on k.
- But how does k help us bound the actual height of the tree?
- What does k tell us about the number of black nodes you can have?
- What is the <u>maximum</u> number of black nodes on any root-Null path?

Observation: if every root-NULL path has  $\geq k$ nodes, then the tree includes a perfectly balanced top portion with k levels

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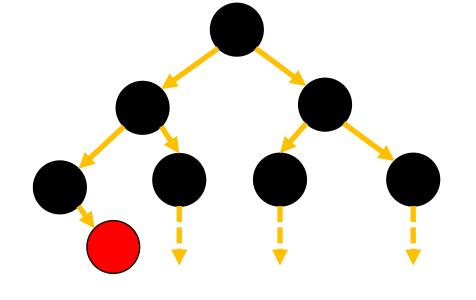


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- But how does k help us bound the actual height of the tree?
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- What is the maximum number of black nodes on any root-Null path?

Observation: if every root-NULL path has  $\geq k$ nodes, then the tree includes a perfectly balanced top portion with k levels At most k black nodes

At most lg(n + 1) black nodes

• So, we have:



- So, How many red nodes
- Bui on any root-Null path? | height of the tree?
- What does k ten us about the number of black nodes you can have?

 $n > 2^k - 1$ 

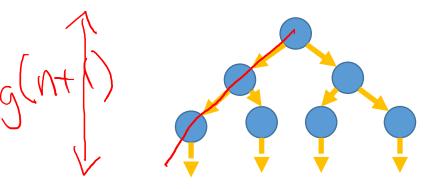
• What is the maximum number of black nodes on any root-Null path?

Observation: if every root-NULL path has ≥ k nodes, then the tree includes a perfectly balanced top portion with k levels At most k black nodes

At most lg(n + 1) black nodes

- Thus: in a Red-Black tree with n nodes, there is a root-NULL path with at most lg (n + 1) black nodes
- By invariant (4): every root-NULL path has  $\leq \lg(n+1)$  black nodes
- By invariant (3): every root-NULL path has  $\leq \lg(n+1)$  red nodes
- Thus, a total of  $\leq 2\lg(n+1)$  nodes on every root-NULL path

# of Red + # of Black



- 1. Each node must be labeled either red or black
- 2. The root must be labeled black
- 3. The tree cannot have two red nodes in a row (for any red node its parent, left, and right must be black)
- Every root-NULL path must include the same number of black nodes

- If our tree can be colored as a Red-Black tree, then every root-NULL path has  $\leq 2\lg(n+1)$  nodes total
- The longest path will dictate the height of the tree
- So, height of the tree is at most  $2\lg(n+1)$   $\lg(n+1)$

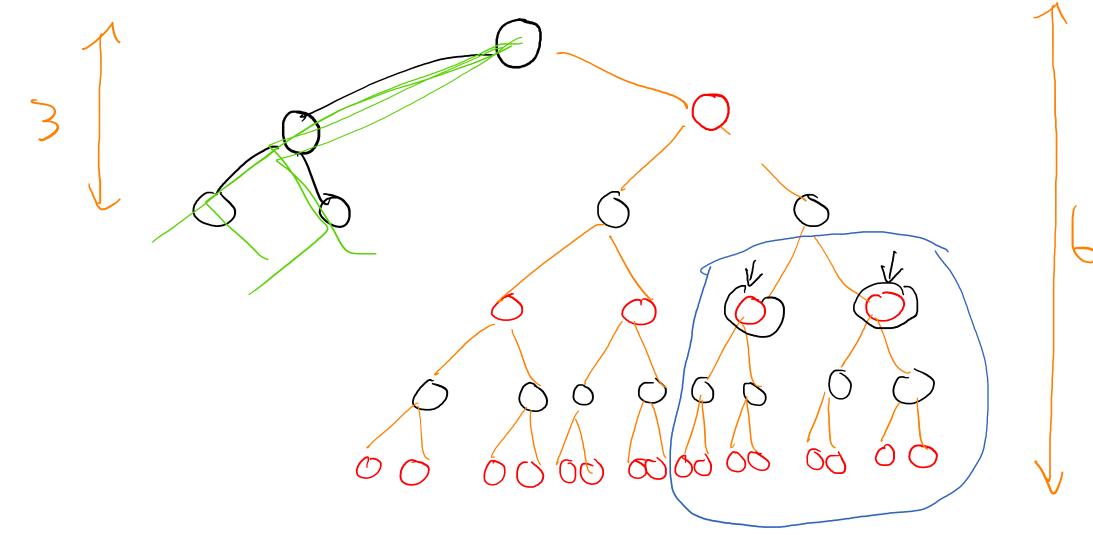
-fake3(lgn)

ZQO

- A tree cannot contain a *chain* of three nodes
- Thus, the height of the tree is  $O(\lg n) \rightarrow G(\lg n)$
- Why is this important?

Exercise question 2

Draw a <u>Worst-Case</u> (most lopsided) Red-Black Tree with a minimum of 3 black nodes on every root-NULL path

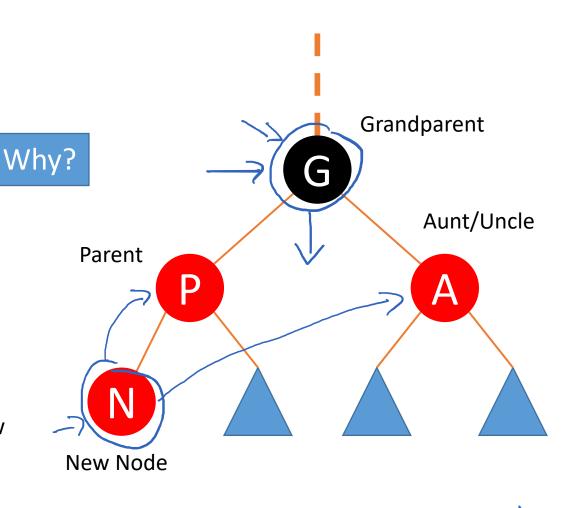


- 1. Insert the new node
- 2. Color it red
- 3. Fix colors to enforce Red-Black Tree invariants
  - 1. This is a recursive process

 Insert the new node (always insert as a leaf)



- 2.) If the inserted node is the root, then color it black, otherwise color it red
- 3. If the new node is not root and its parent is black, then we are done
- 4. Otherwise, look at the node's aunt
  - a) If aunt is red
    - I. Change color of parent and aunt to black
    - II. Change color of the new node and the grandparent to red
    - III. Go to step (2) and treat grandparent as new node



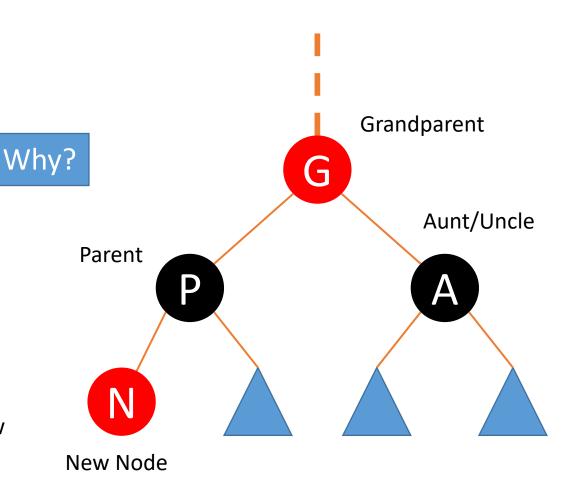
Move the black color down

"Aunt" is usually called "Uncle"

 Insert the new node (always insert as a leaf)

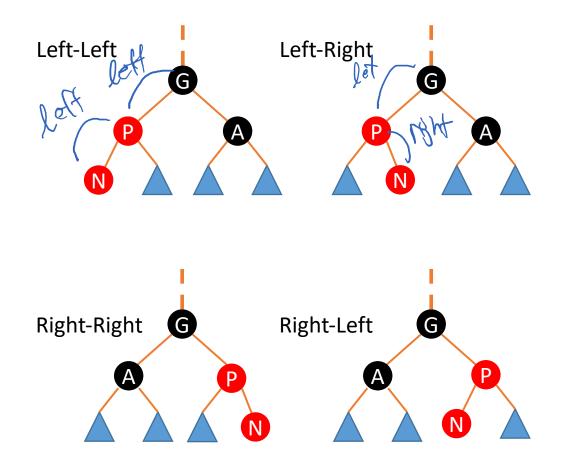


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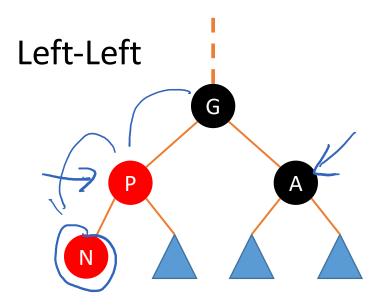
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- Insert the new node (always insert as a leaf)
- 2. If the inserted node is the root, then color it black, otherwise color it red
- 3. If the new node is not root and its parent is black, then we are done
- 4. Otherwise, look at the node's aunt
  - a) If aunt is red
  - b) If aunt is black
    - I. Put the new node, its parent, and the grandparent "in order" with the middle node as the root
    - II. We have four possibilities for the current positions of N, P, and G

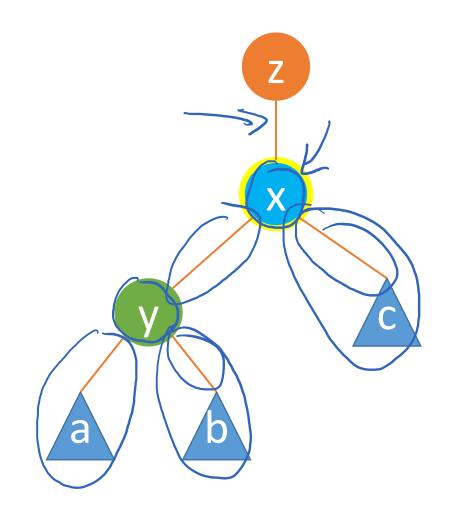


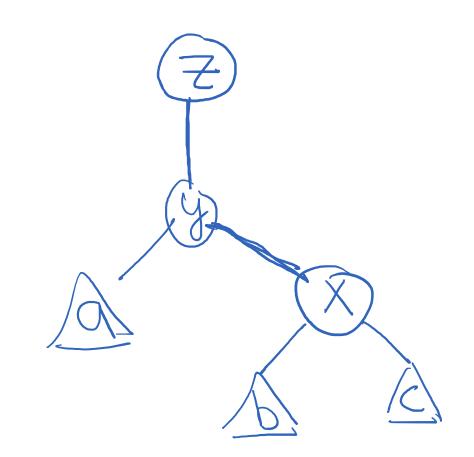
#### Red-Black Trees, Inserting a Node: Left-Left

1. Right rotate around the grandparent

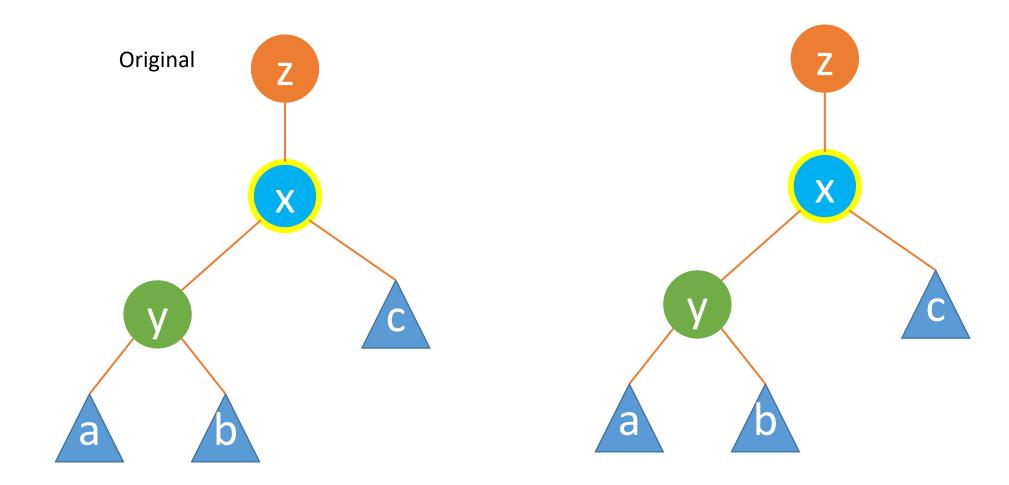


#### Tree Rotations: Right

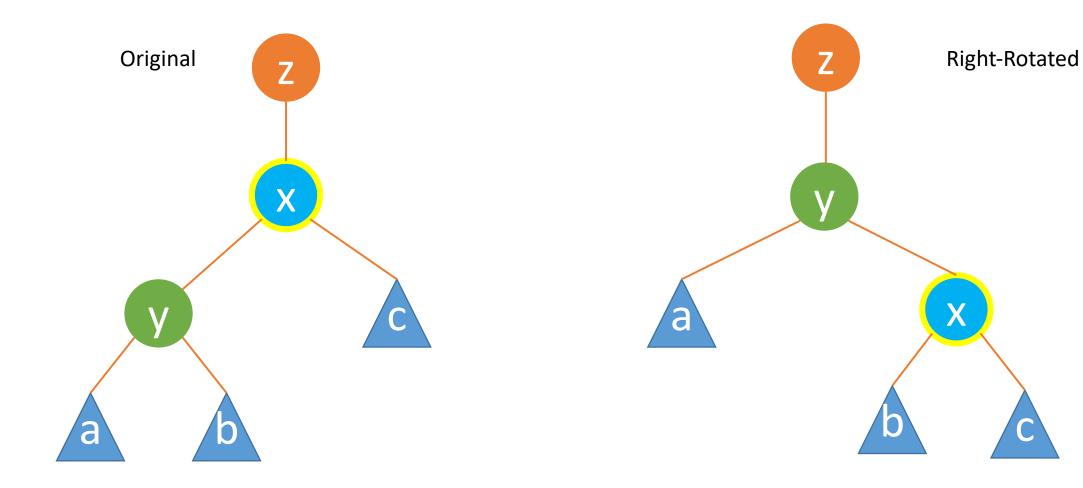




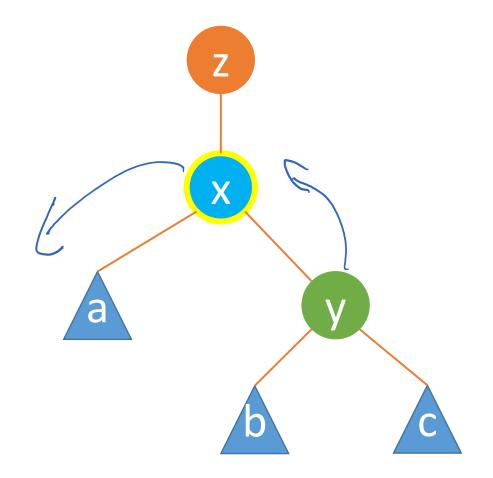
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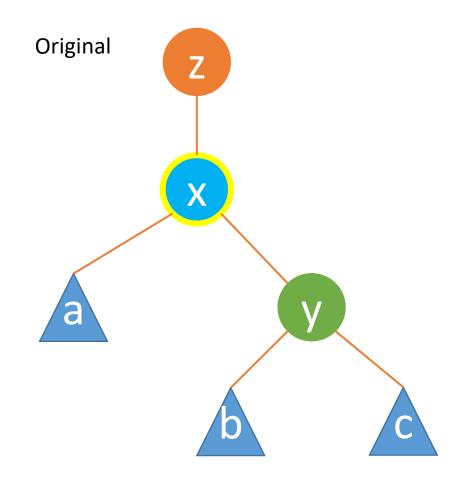
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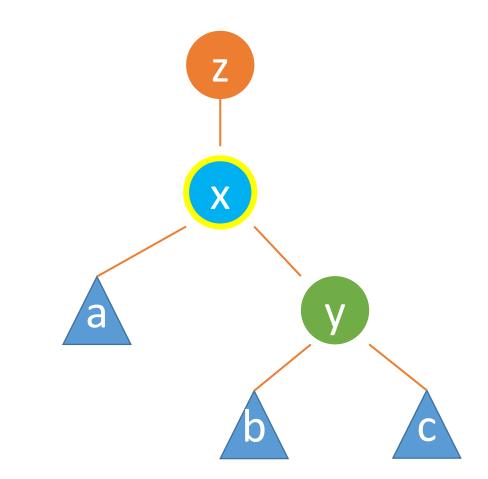


#### Tree Rotations: Left

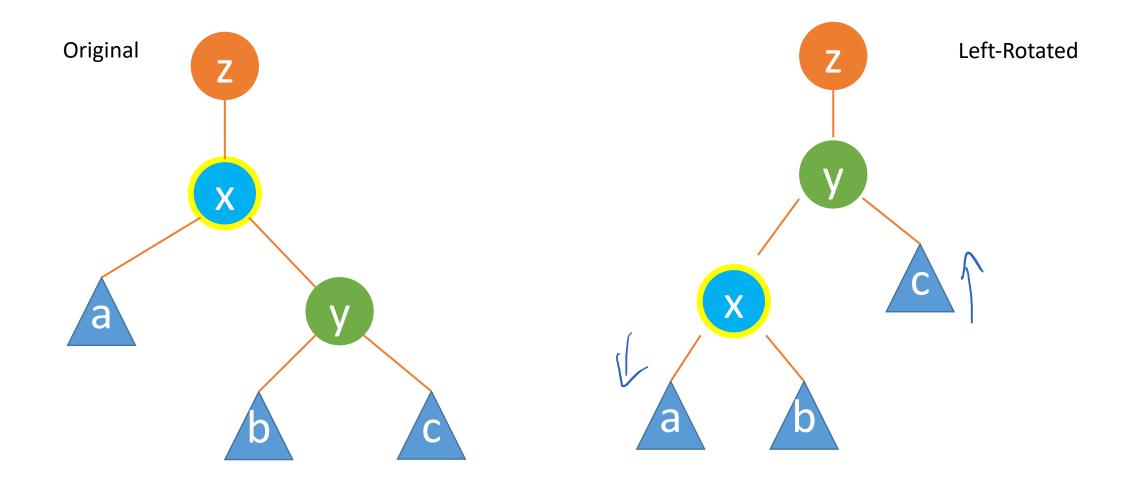


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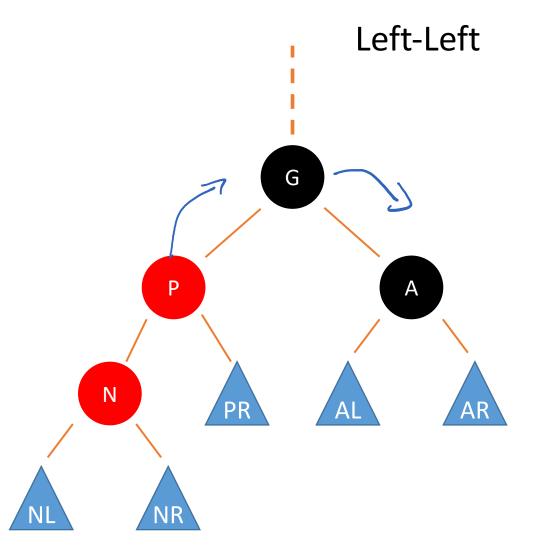




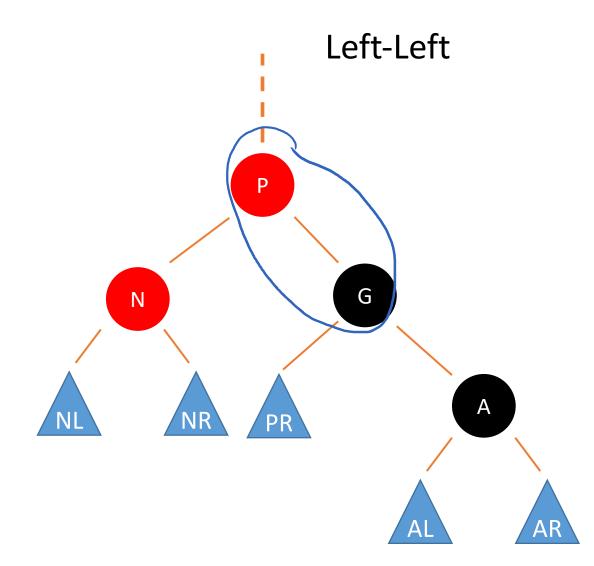
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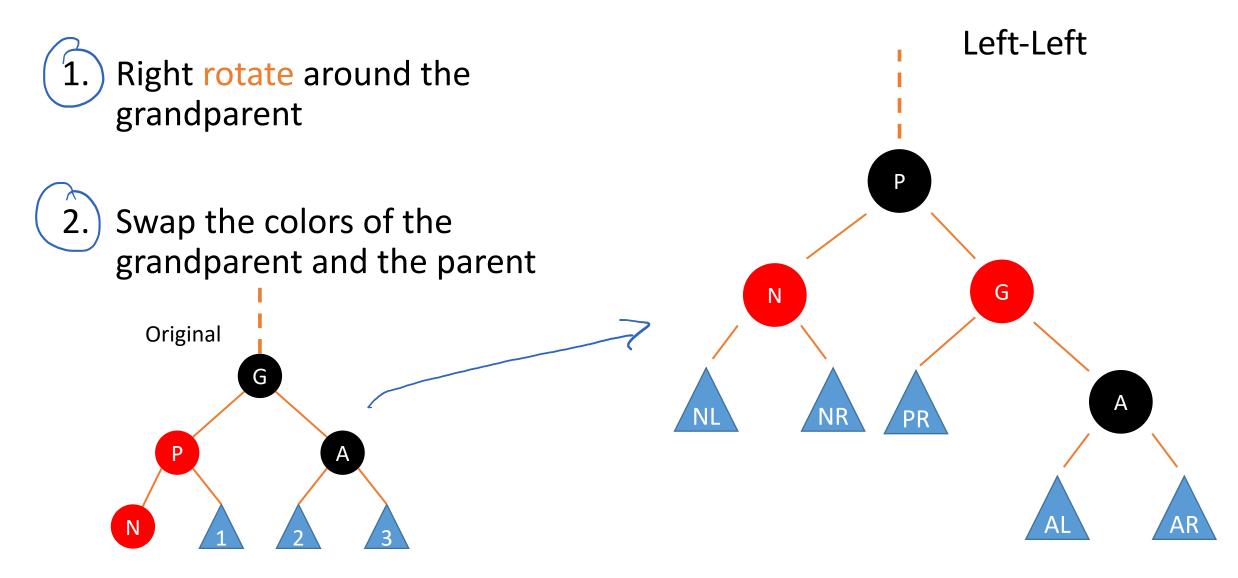


1. Right rotate around the grandparent

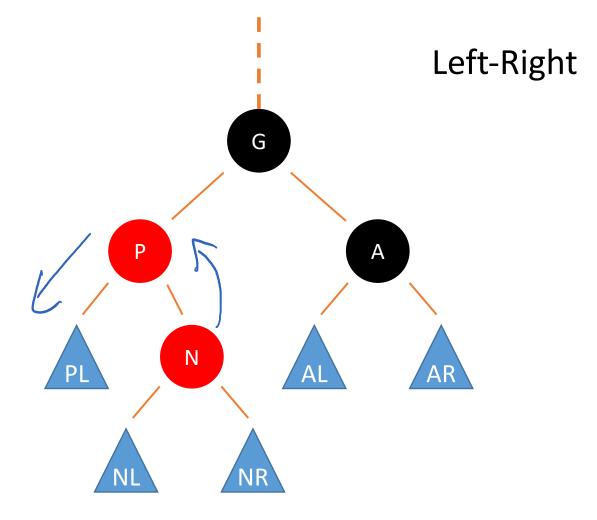


- 1. Right rotate around the grandparent
- 2. Swap the colors of the grandparent and the parent

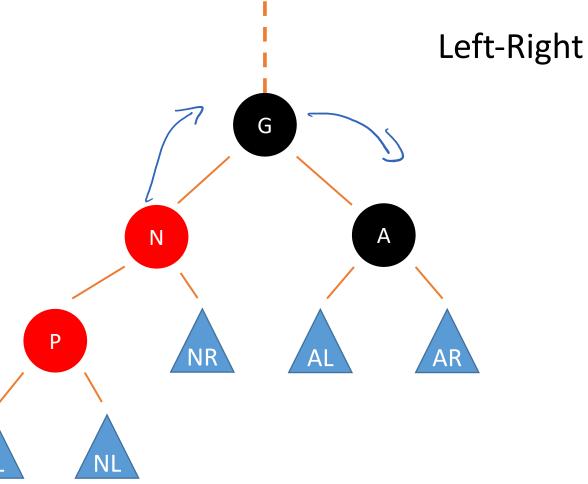




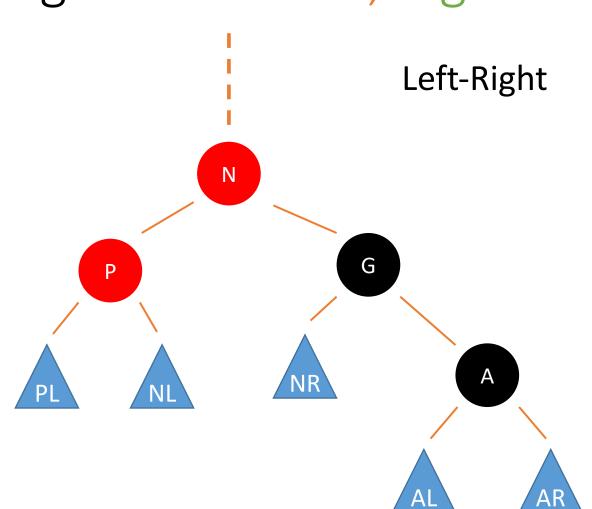
1. Left rotate around the parent



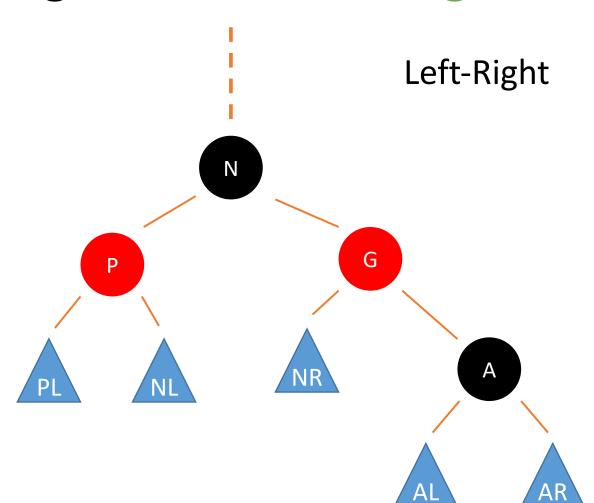
- 1. Left rotate around the parent
- 2. Right rotate around the grandparent



- 1. Left rotate around the parent
- 2. Right rotate around the grandparent
- Swap the colors of the grandparent and the new node



- 1. Left rotate around the parent
- 2. Right rotate around the grandparent
- Swap the colors of the grandparent and the new node



### Red-Black Trees, Inserting a Node

- What about the Right-Right and Right-Left options?
- They are the inverse of the cases we've just covered.
- What are the running times of these procedures?
  - Inserting the new node?
  - Recoloring?
  - Restructuring?
- We're not going to cover deletion, but what are your thoughts?
  - Operation? (<u>http://www.geeksforgeeks.org/red-black-tree-set-3-delete-2/</u>)
  - Running time?

FUNCTION RBTreeInsert(tree, new\_node)

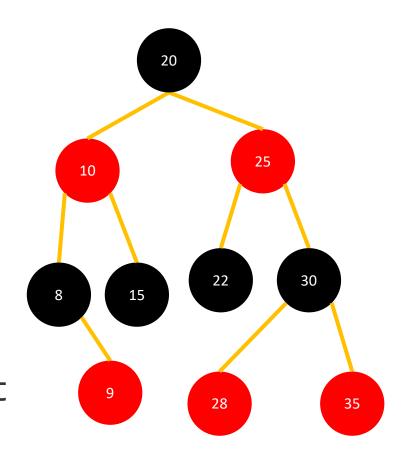
```
# Search for position of new_node
parent = NONE
current_node = tree.root
```

WHILE current\_node != NONE

parent = current\_node

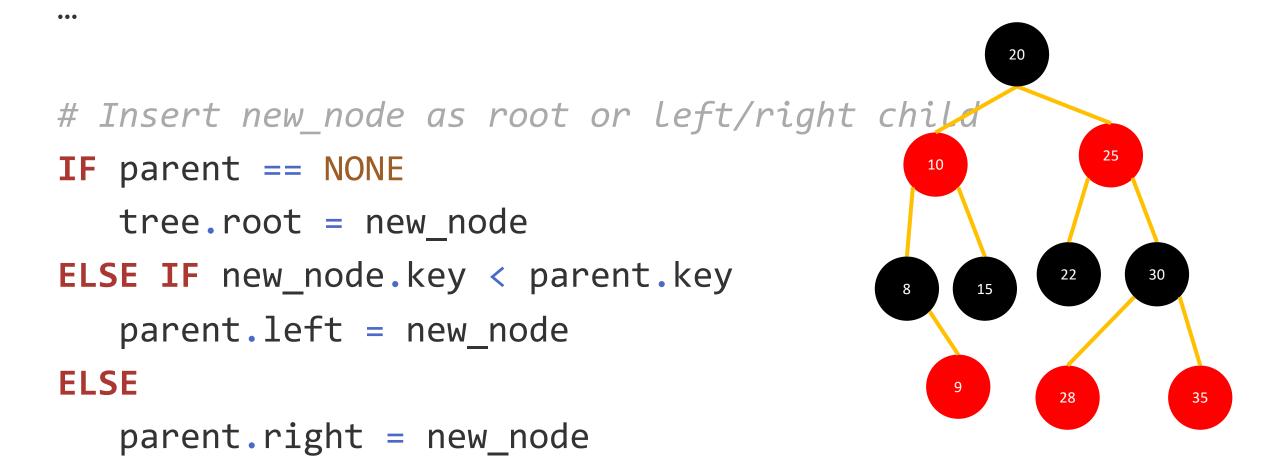
IF new\_node.key < current\_node.key
 current\_node = current\_node.left
ELSE</pre>

```
current_node = current_node.right
new node.parent = parent
```



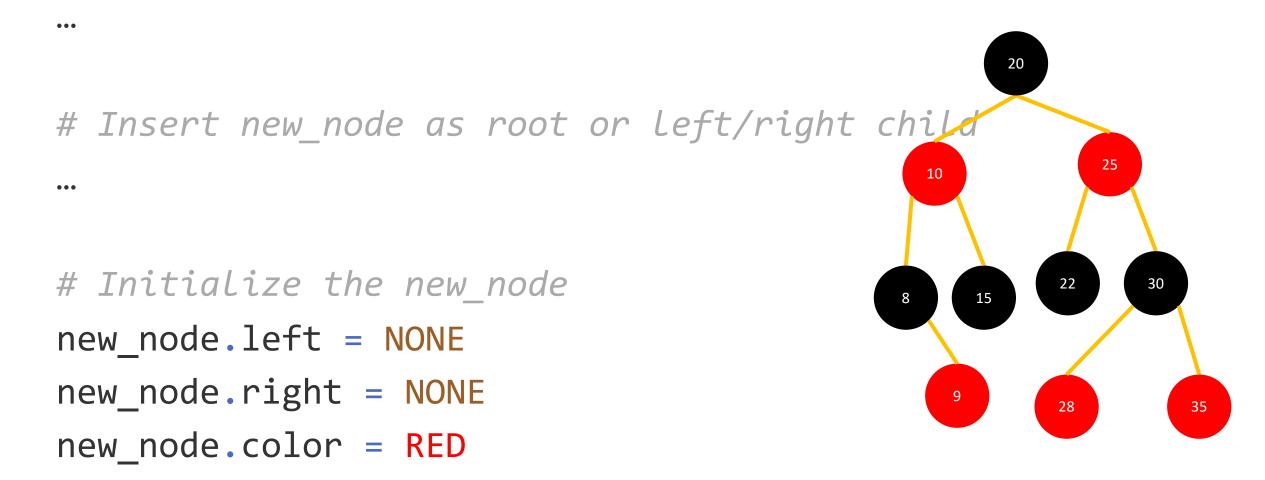
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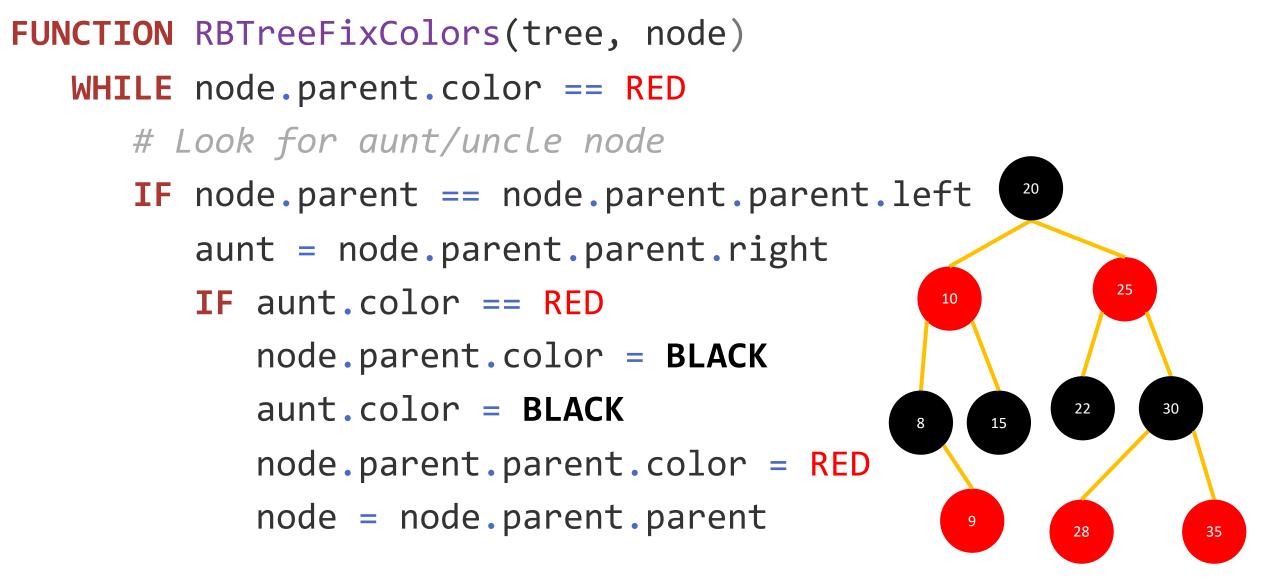


FUNCTION RBTreeInsert(tree, new\_node)

# Search for position of new\_node



RBTreeFixColors(tree, new\_node)

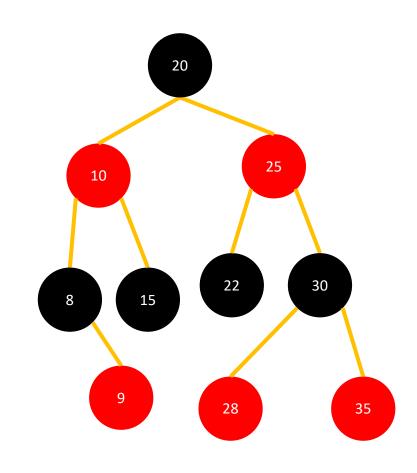


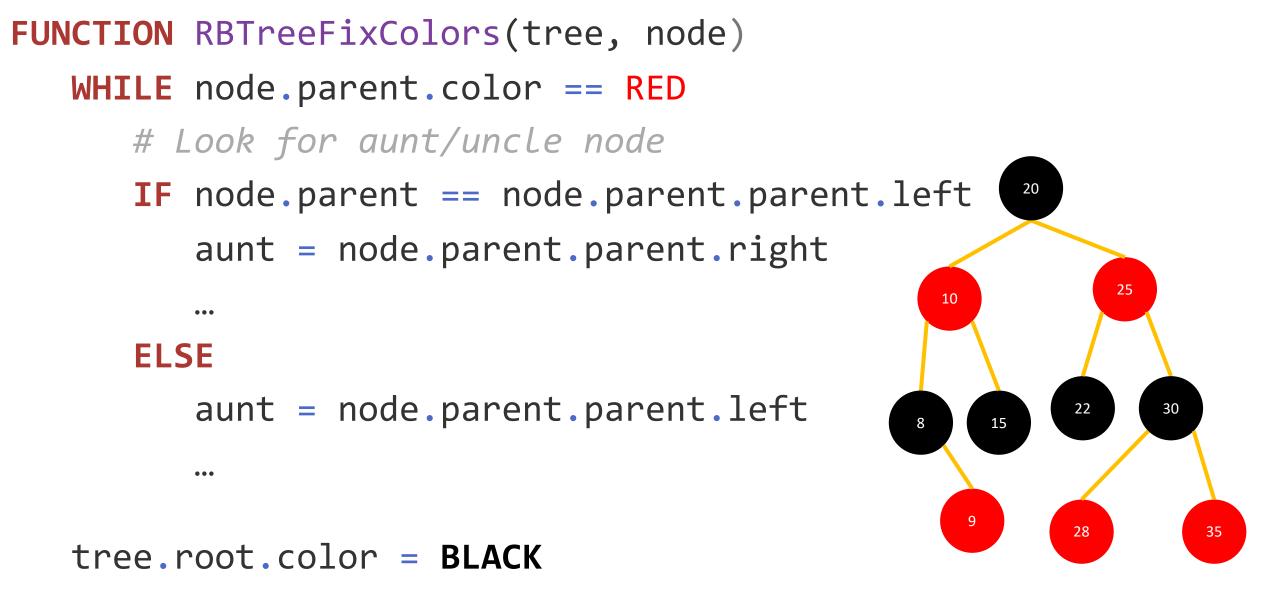
```
FUNCTION RBTreeFixColors(tree, node)
   WHILE node.parent.color == RED
      # Look for aunt/uncle node
      IF node.parent == node.parent.parent.left
                                                        20
          aunt = node.parent.parent.right
                                                             25
          IF aunt.color == RED
                                                   10
             ...
          ELSE
                                                           22
                                                      15
           IF node == node.parent.right
              node = node.parent
                                                    9
                                                           28
              LeftRotate(tree, node)
           node.parent.color = BLACK
           node.parent.parent.color = RED
           RightRotate(tree, node.parent.parent)
```

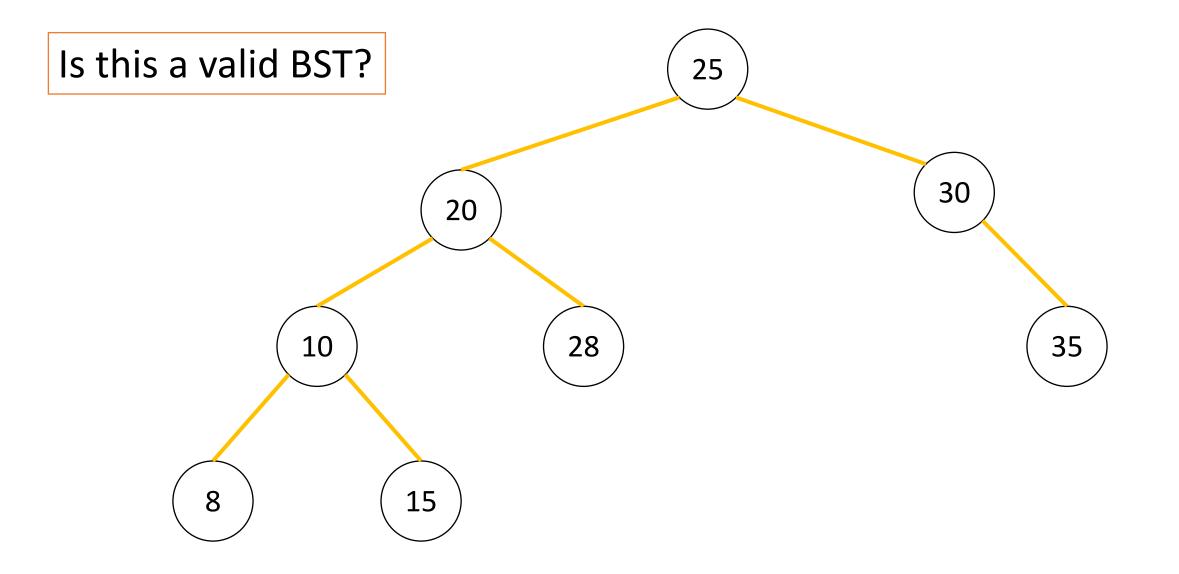
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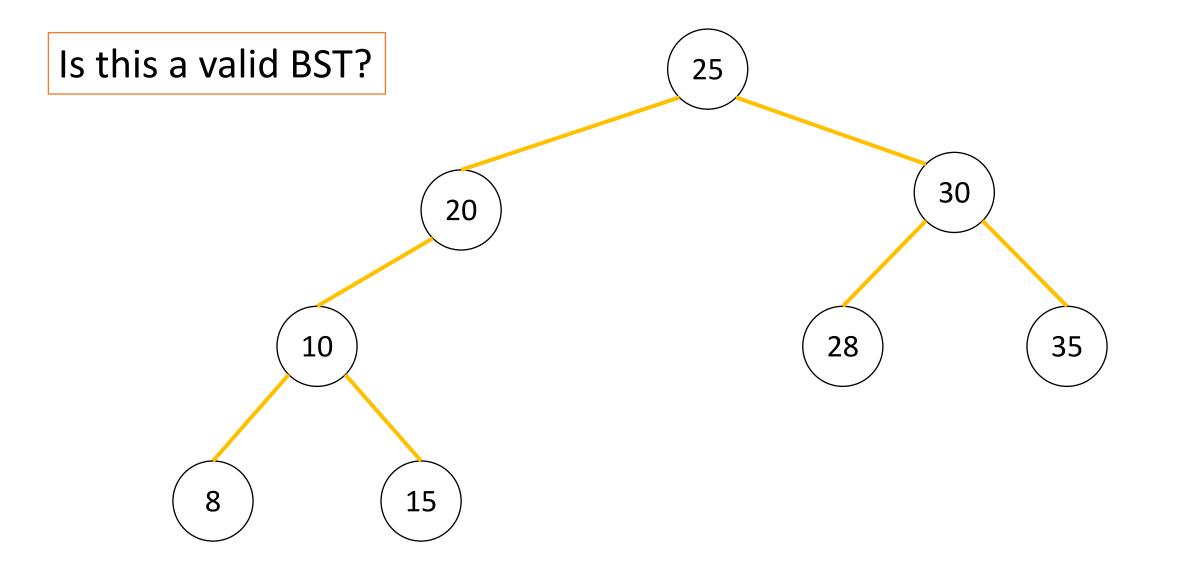
**FUNCTION** RBTreeFixColors(tree, node) WHILE node.parent.color == RED # Look for aunt/uncle node **IF** node.parent == node.parent.parent.left 20 aunt = node.parent.parent.right 25 10 ... ELSE aunt = node.parent.parent.left 30 22 15 **IF** aunt.color == **RED** node.parent.color = BLACK 9 35 28 aunt.color = **BLACK** node.parent.parent.color = RED node = node.parent.parent

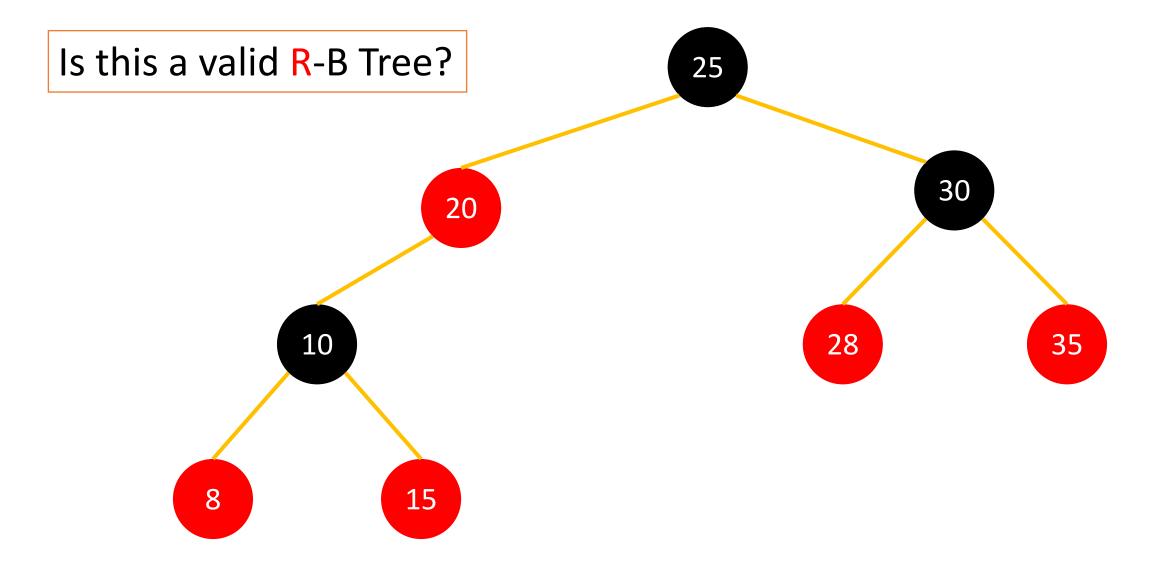
**FUNCTION** RBTreeFixColors(tree, node) WHILE node.parent.color == RED # Look for aunt/uncle node ... ELSE aunt = node.parent.parent.left ... **ELSE IF** node == node.parent.left node = node.parent RightRotate(tree, node) node.parent.color = BLACK node.parent.parent.color = RED LeftRotate(tree, node.parent.parent)

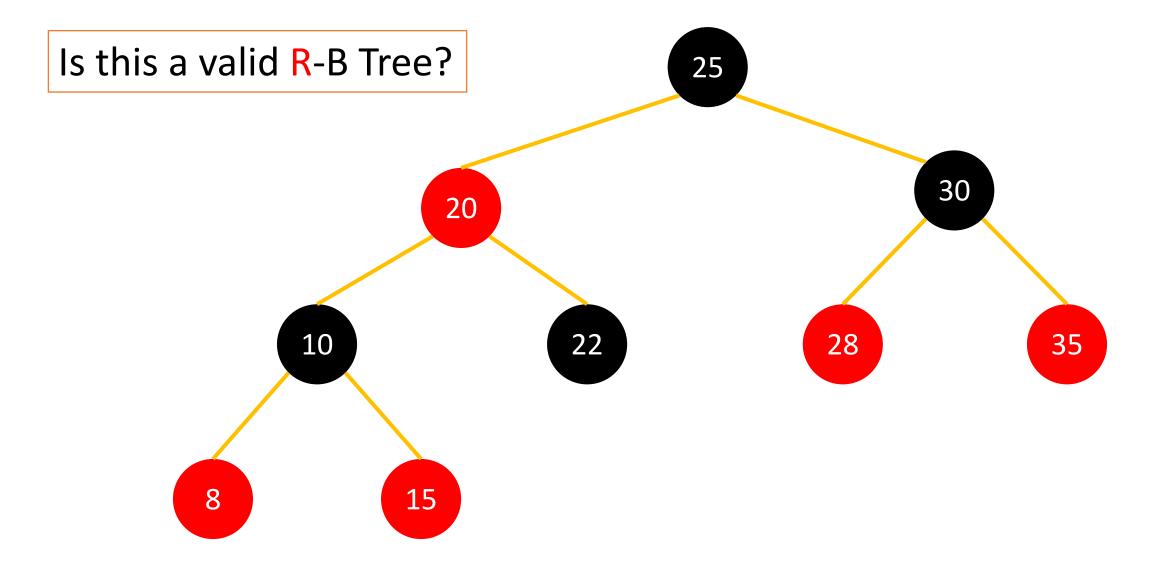


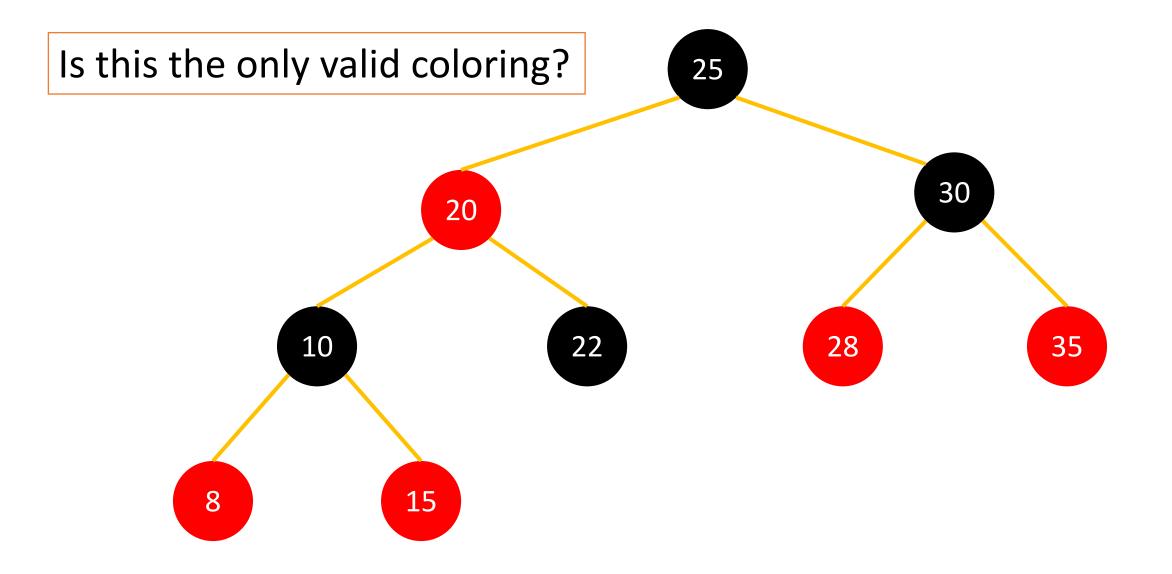


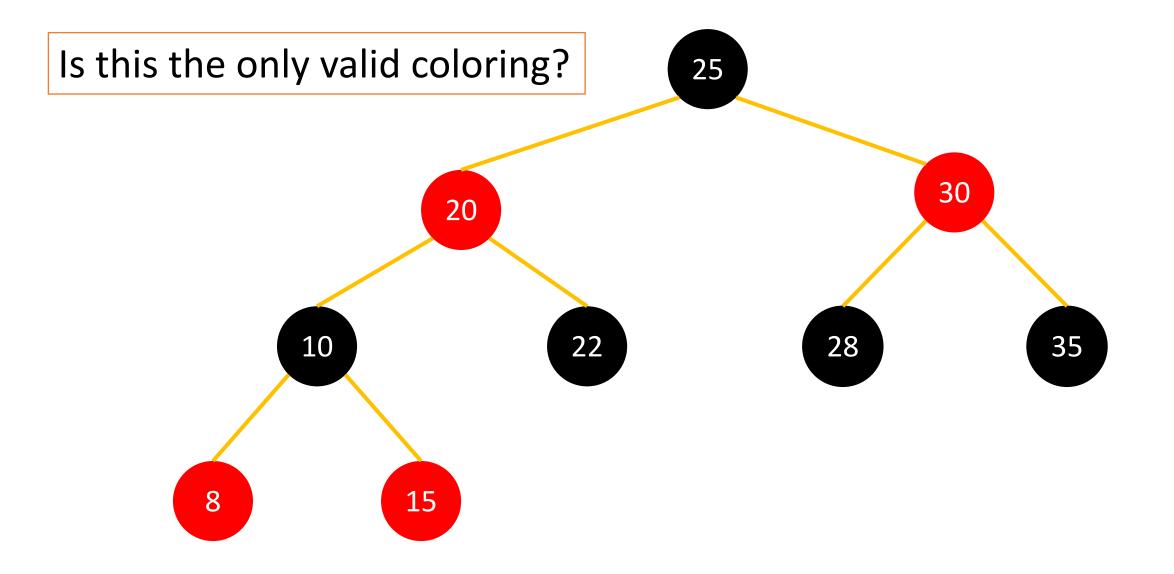


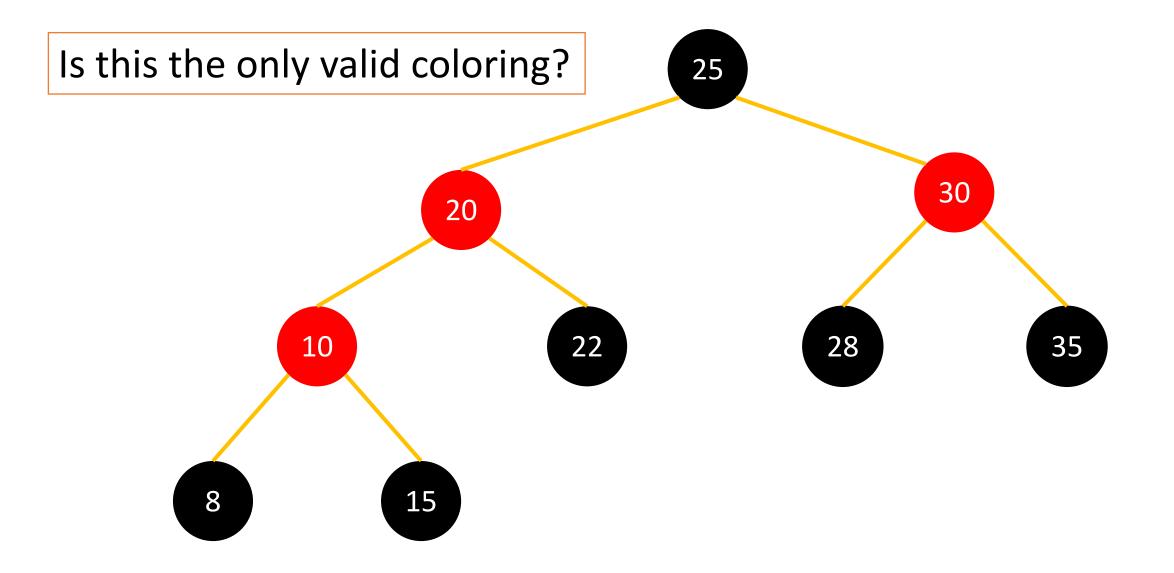


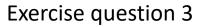


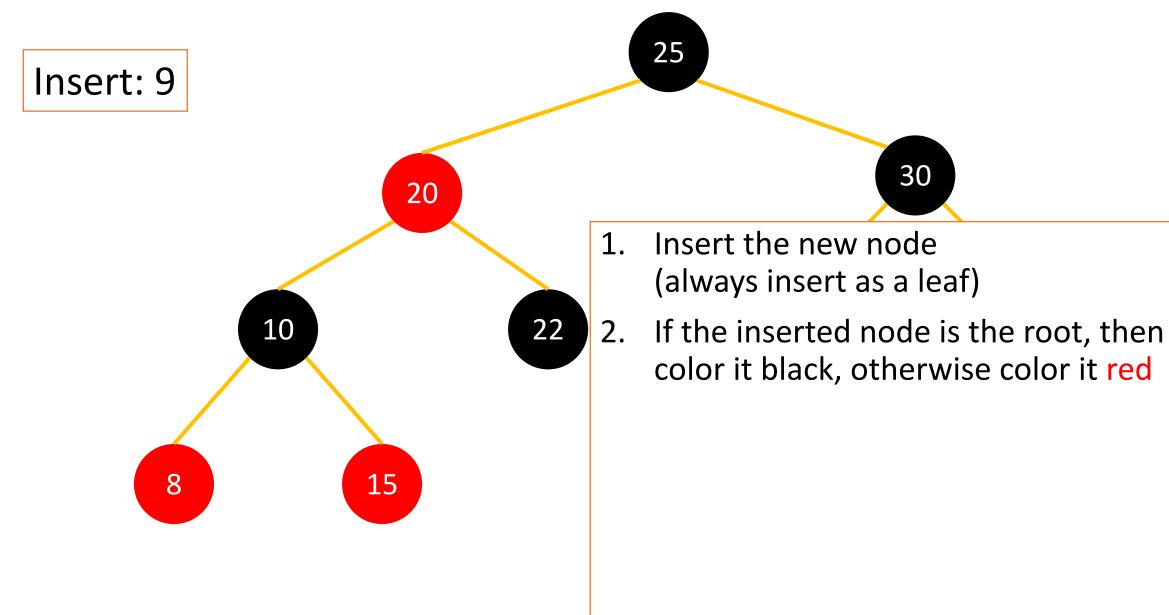


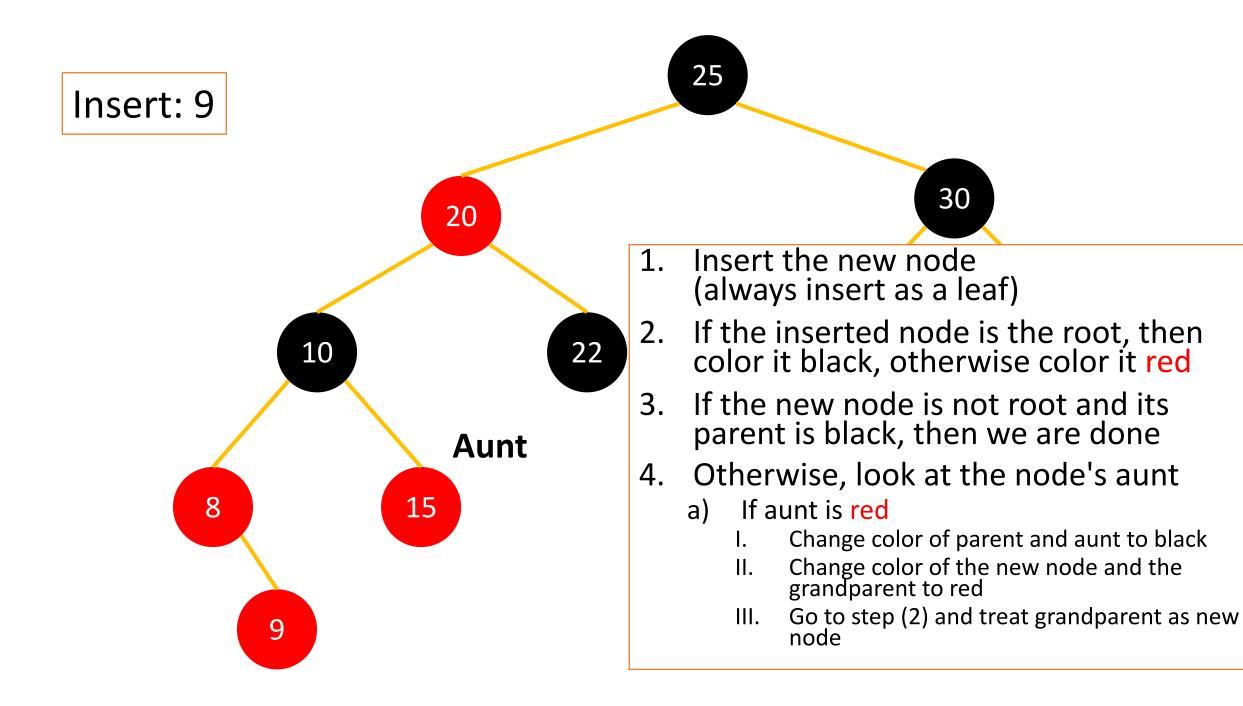


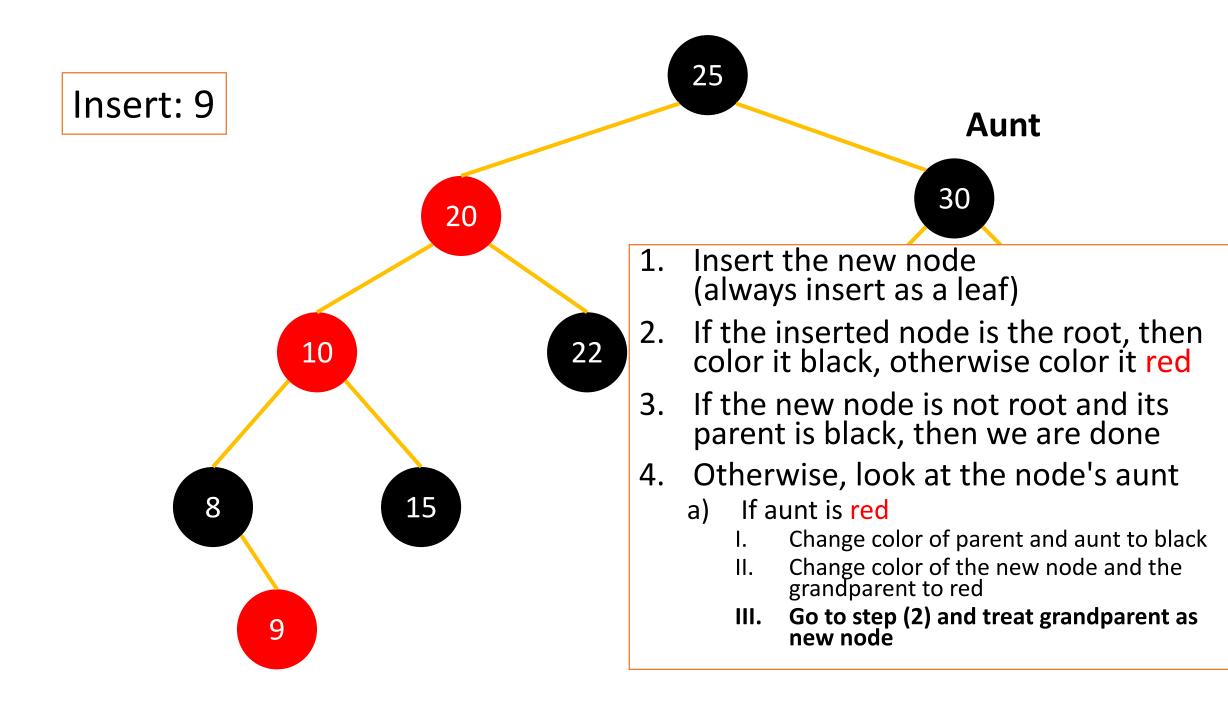


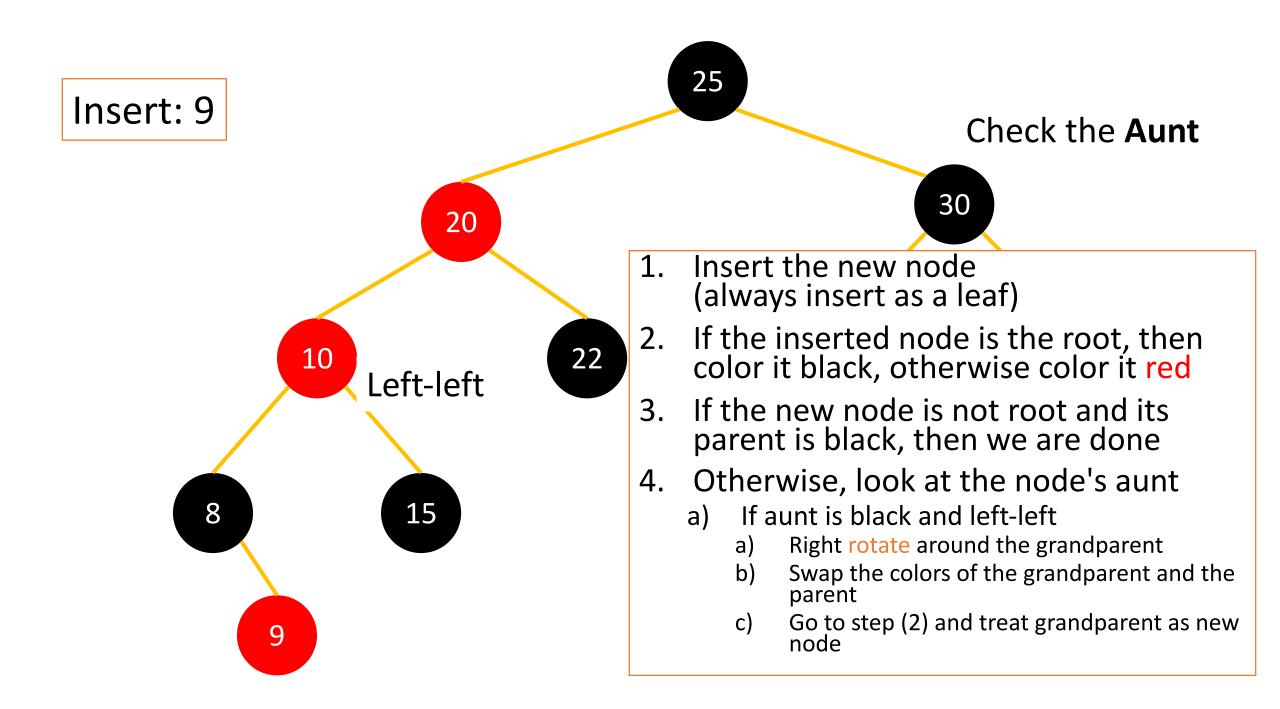


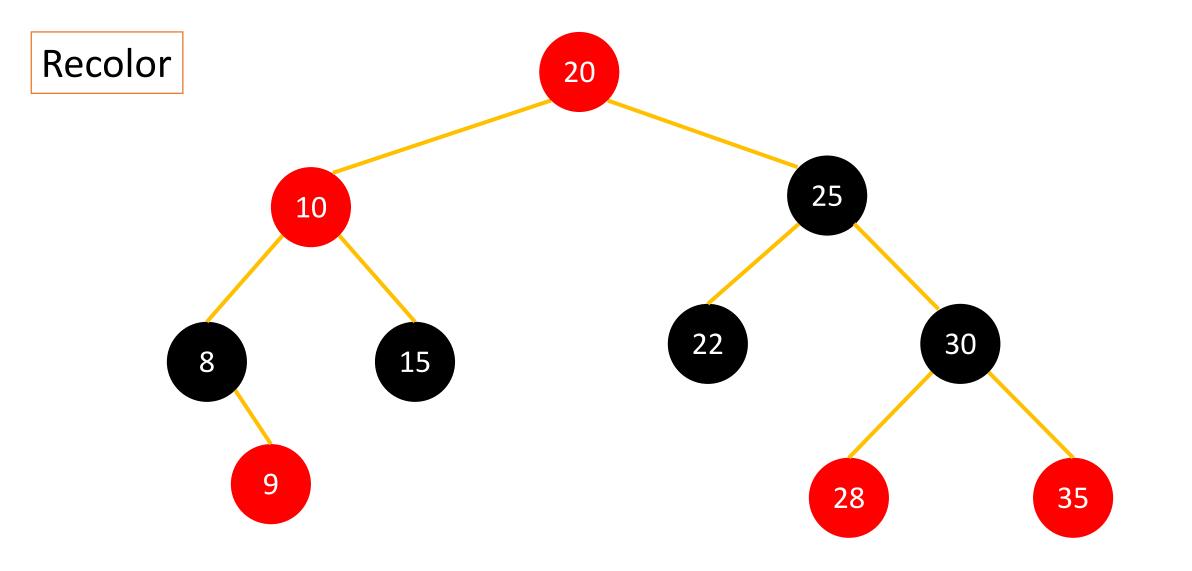


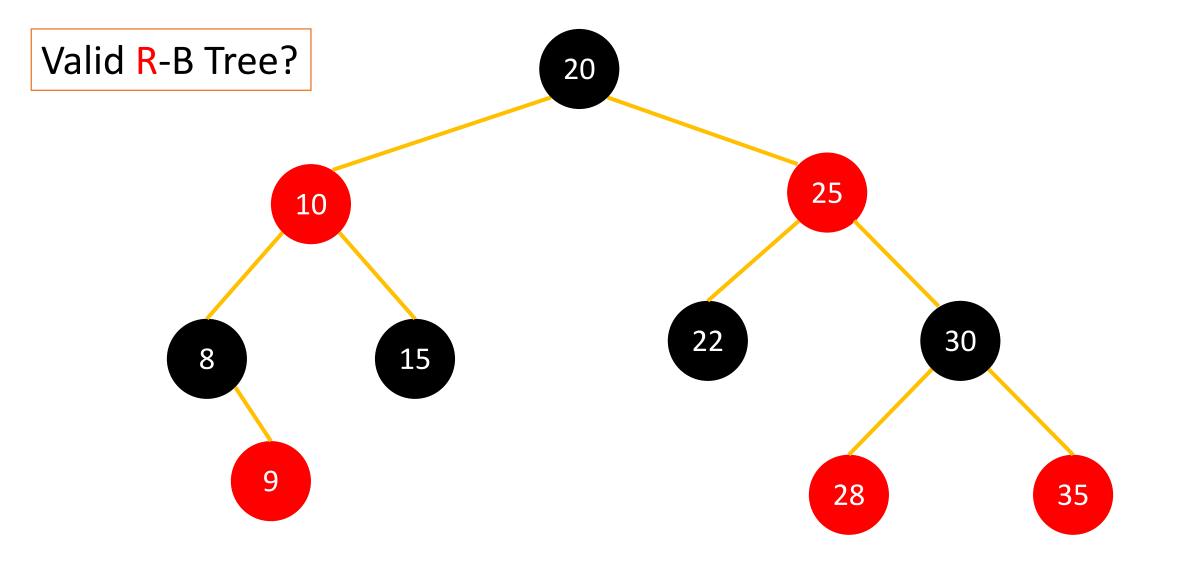


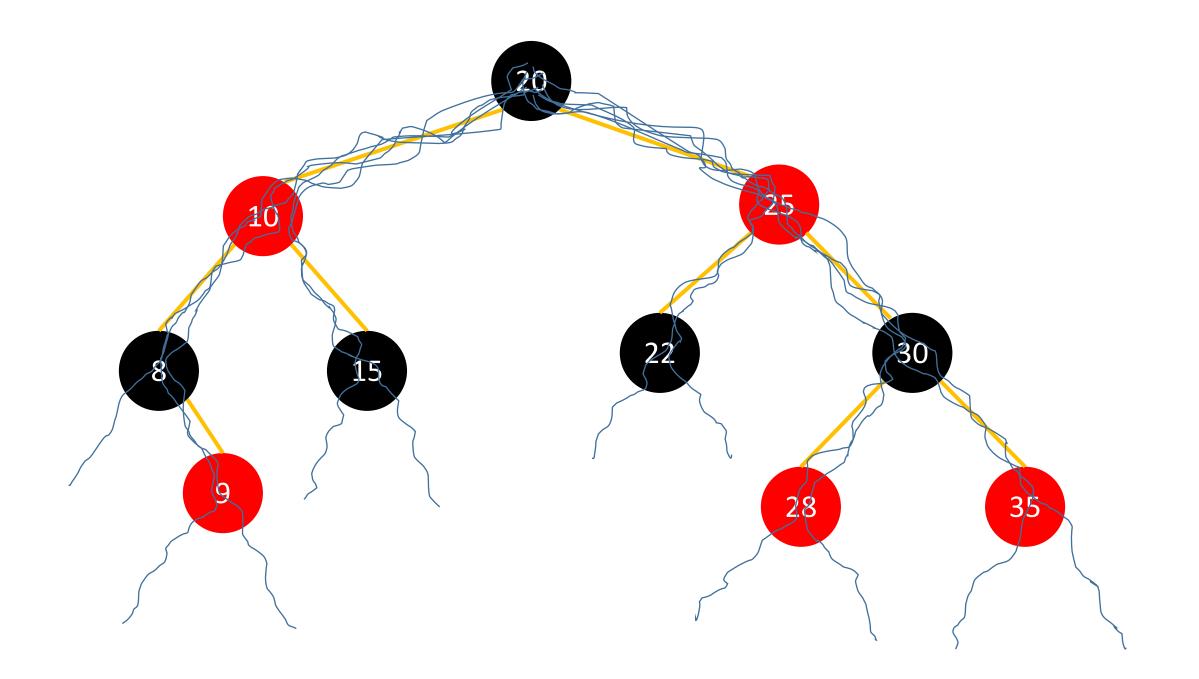












### **BST Summary**

- Most BST operations take O(height) time.
- With an unbalanced tree this could be as bad as O(n)
- We want to ensure that the height of the tree is O(lg n)
- Red-Black trees provide one mechanism for creating balanced trees, meaning that they guarantee O(lg n) for applicable BST operation
- This requires extra work while inserting and deleting in the form of tree rotations
- Bottom line: as long as our tree satisfies the Red-Black tree invariants (which it does with appropriate insert/delete procedures), then we can assume optimal running time for BSTs