#### Lecture 19: Threads

CS 105

April 3, 2019

### Processes

- Definition: A *program* is a file containing code + data that describes a computation
- Definition: A process is an instance of a running program.
  - One of the most profound ideas in computer science
  - Not the same as "program" or "processor"
- Process provides each program with two key abstractions:
  - Private address space
    - Each program seems to have exclusive use of main memory.
    - Provided by kernel mechanism called *virtual memory*
  - Logical control flow
    - Each program seems to have exclusive use of the CPU
    - Provided by kernel mechanism called *context switching*



### **Traditional View of a Process**

Process = process context + code, data, and stack

#### Process context

Code, data, and stack



### Alternate View of a Process

Process = thread + code, data, and kernel context



## A Process With Multiple Threads

- Multiple threads can be associated with a process
  - Each thread has its own logical control flow
  - Each thread has its own stack for local variables
  - Each thread has its own thread id (TID)
  - Each thread shares the same code, data, and kernel context

#### Thread 1 (main thread) Thread 2 (peer thread) Shared code and data



### Threads vs. Processes

- How threads and processes are similar
  - Each has its own logical control flow
  - Each can run concurrently with others (possibly on different cores)
  - Each is context switched

# **Concurrent Threads**

- Two threads are *concurrent* if their flows overlap in time
- Otherwise, they are sequential
- Examples:
  - Concurrent: A & B, A&C
  - Sequential: B & C

Time



### **Concurrent Thread Execution**

- Single Core Processor
  - Simulate parallelism by time slicing
- Multi-Core Processor
  - Can have true parallelism



### Threads vs. Processes

- How threads and processes are similar
  - Each has its own logical control flow
  - Each can run concurrently with others (possibly on different cores)
  - Each is context switched
- How threads and processes are different
  - Threads share all code and data (except local stacks)
    - Processes (typically) do not
  - Threads are somewhat less expensive than processes
    - Process control (creating and reaping) twice as expensive as thread control
    - Linux numbers:
      - ~20K cycles to create and reap a process
      - ~10K cycles (or less) to create and reap a thread

## Logical View of Threads

- Threads associated with process form a pool of peers
  - · Unlike processes which form a tree hierarchy



# Posix Threads (Pthreads) Interface

- Pthreads: Standard interface for ~60 functions that manipulate threads from C programs
  - Creating and reaping threads
    - pthread\_create()
    - pthread\_join()
  - Determining your thread ID
    - pthread\_self()
  - Terminating threads
    - pthread\_cancel()
    - pthread\_exit()
    - exit() [terminates all threads], RET [terminates current thread]

### The Pthreads "hello, world" Program





### Using Threads for Parallelism

- on a multi-core system, the OS can schedule concurrent threads in parallel on multiple cores
- ... so concurrent programs can run faster that sequential programs



### Shared Variables in Threaded Programs

- Question: Which variables in a threaded C program are shared?
  - The answer is not as simple as "global variables are shared" and "stack variables are private"
- Def: A variable x is shared if and only if multiple threads refer to some instance of x.
- Requires answers to the following questions:
  - What is the memory model for threads?
  - How are instances of variables mapped to memory?
  - How many threads might refer to each of these instances?

### **Threads Memory Model**

#### Conceptual model:

- Multiple threads run within the context of a single process
- · Each thread has its own separate thread context
  - Thread ID, stack, stack pointer, PC, condition codes, and GP registers
- All threads share the remaining process context
  - Code, data, heap, and shared library segments of the process virtual address space
  - Open files and installed handlers
- Operationally, this model is not strictly enforced:
  - Register values are truly separate and protected, but...
  - Any thread can read and write the stack of any other thread

The mismatch between the conceptual and operation model is a source of confusion and errors

### Example Program to Illustrate Sharing

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```
char **ptr; /* global var */
int main()
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    long i;
    pthread t tid;
    char *msqs[2] = \{
        "Hello from foo",
        "Hello from bar"
    };
    ptr = msqs;
    for (i = 0; i < 2; i++)
        Pthread create(&tid,
            NULL,
            thread,
             (void *)i);
    Pthread exit(NULL);
                            sharing.
```

```
void *thread(void *vargp)
    long myid = (long)vargp;
    static int cnt = 0;
    printf("[\$ld]: \$s (cnt=\$d) \n",
         myid, ptr[myid], ++cnt);
    return NULL;
```

Peer threads reference main thread's stack indirectly through global ptr variable

### Mapping Variable Instances to Memory

- Global variables
  - Def: Variable declared outside of a function
  - Virtual memory contains exactly one instance of any global variable
- Local variables
  - Def: Variable declared inside function without static attribute
  - Each thread stack contains one instance of each local variable
- Local static variables
  - Def: Variable declared inside function with the static attribute
  - Virtual memory contains exactly one instance of any local static variable.

### Mapping Variable Instances to Memory



### **Shared Variable Analysis**

#### Which variables are shared?

Variable instance	<i>Referenced by main thread?</i>	<i>Referenced by</i> peer thread 0?	<i>Referenced by peer thread 1?</i>
ptr	yes	yes	yes
cnt	no	yes	yes
i.m	yes	no	no
msgs.m	yes	yes	yes
myid.p0	no	yes	no
myid.pl	no	no	yes

- Answer: A variable  $\times$  is shared iff multiple threads reference at least one instance of  $\times$ . Thus:
  - ptr, cnt, and msgs are shared
  - i and myid are not shared

### Pros and Cons of Thread-Based Designs

- + Threads are more efficient than processes
- + Easy to share data structures between threads e.g., logging information, file cache
- Unintentional sharing can introduce subtle and hardto-reproduce errors!
  - The ease with which data can be shared is both the greatest strength and the greatest weakness of threads
  - Hard to know which data shared & which private
  - Hard to detect by testing
    - Probability of bad race outcome very low. But nonzero!

#### badcnt.c: Improper Synchronization

```
/* Global shared variable */
volatile long cnt = 0; /* Counter */
int main(int argc, char **argv)
{
    long niters;
```

```
pthread_t tid1, tid2;
```

```
niters = atoi(argv[1]);
Pthread_create(&tid1, NULL,
        thread, &niters);
Pthread_create(&tid2, NULL,
        thread, &niters);
Pthread_join(tid1, NULL);
Pthread_join(tid2, NULL);
```

```
/* Check result */
if (cnt != (2 * niters))
    printf("BOOM! cnt=%ld\n", cnt);
else
    printf("OK cnt=%ld\n", cnt);
exit(0);
```

badcnt.c

linux> ./badcnt 10000
OK cnt=20000
linux> ./badcnt 10000
BOOM! cnt=13051
linux>

**cnt** should equal 20,000. What went wrong?

}

### Assembly Code for Counter Loop

C code for counter loop in thread i

```
for (i = 0; i < niters; i++)
    cnt++;</pre>
```

Asm code for thread i

movq testq jle movl	(%rdi), %rcx %rcx,%rcx .L2 \$0, %eax	$H_i$ : Head
.L3: movq addq movq addq cmpq jne .L2:	<pre>cnt(%rip),%rdx \$1, %rdx %rdx, cnt(%rip) \$1, %rax %rcx, %rax .L3</pre>	<pre>     L<sub>i</sub>: Load cnt     U<sub>i</sub>: Update cnt     S<sub>i</sub>: Store cnt     T<sub>i</sub>: Tail </pre>

### Safe Schedules

- A schedule of instructions is safe if the resulting concurrent computation returns the correct answer
- Assume two threads executing routine thread. Which of the following schedules are safe?
  - $H_1, L_1, U_1, S_1, H_2, L_2, U_2, S_2, T_2, T_1$
  - $H_2, L_2, H_1, L_1, U_1, S_1, T_1, U_2, S_2, T_2$
  - $H_1, H_2, L_2, U_2, S_2, L_1, U_1, S_1, T_1, T_2$

### **Progress Graphs**

#### Thread 2



A *progress graph* depicts the discrete *execution state space* of concurrent threads.

Each axis corresponds to the sequential order of instructions in a thread.

Each point corresponds to a possible *execution state* (Inst<sub>1</sub>, Inst<sub>2</sub>).

E.g.,  $(L_1, S_2)$  denotes state where thread 1 has completed  $L_1$  and thread 2 has completed  $S_2$ .

### **Trajectories in Progress Graphs**

Thread 2



A *trajectory* is a sequence of legal state transitions that describes one possible concurrent execution of the threads.

Example:

H1, L1, U1, H2, L2, S1, T1, U2, S2, T2

## **Critical Sections and Unsafe Regions**



L, U, and S form a *critical section* with respect to the shared variable cnt

Instructions in critical sections (wrt some shared variable) should not be interleaved

Sets of states where such interleaving occurs form *unsafe regions* 

### **Critical Sections and Unsafe Regions**



## **Enforcing Mutual Exclusion**

- *Question:* How can we guarantee a safe trajectory?
- Answer: We must synchronize the execution of the threads so that they can never have an unsafe trajectory.
  - i.e., need to guarantee *mutually exclusive access* for each critical section.
- Possible solutions:
  - Locks
  - Semaphores
  - Condition variables