

# Local Search for Max-Cut

CS 181 — Advanced Algorithms

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## The Max-Cut Problem

**Max-Cut (Unweighted).** Given an undirected graph  $G = (V, E)$ , find a partition of  $V$  into two sets  $S$  and  $\bar{S} = V \setminus S$  that maximizes the number of *crossing edges*:

$$\text{cut}(S) = |\{ \{u, v\} \in E \mid u \in S, v \in \bar{S} \}|.$$

Max-Cut is **NP-hard**, so we seek an efficient approximation algorithm. We saw a *local search* algorithm: start with any partition, and repeatedly improve it by moving a single vertex from one side to the other.

## The Local Search Algorithm

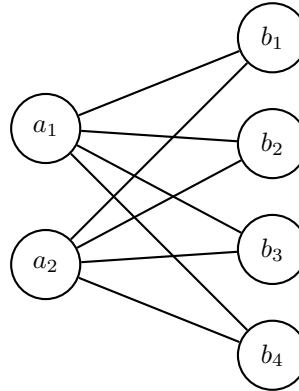
**Algorithm** LOCALSEARCH( $G$ ):

1. Start with an arbitrary partition  $(S, \bar{S})$  of  $V$ .
2. **While** there exists a vertex  $v \in V$  such that moving  $v$  to the other side increases  $\text{cut}(S)$ :
  - Move  $v$  (i.e., if  $v \in S$  set  $S \leftarrow S \setminus \{v\}$ ; if  $v \in \bar{S}$  set  $S \leftarrow S \cup \{v\}$ ).
3. Return the partition  $(S, \bar{S})$ .

A partition is called **locally optimal** if no single-vertex move increases the cut value.

1. **Runtime.** Argue that LOCALSEARCH always terminates and give a bound on the number of iterations. (what happens to the value of  $\text{cut}(S)$  after each iteration? What is its maximum possible value?) Give a bound on the overall runtime.

2. **Example** Consider the graph with vertices  $A = \{a_1, a_2\}$  and  $B = \{b_1, b_2, b_3, b_4\}$ . Suppose we run Local Search with the starting partition  $S = \{a_1, b_1, b_2\}$  and  $\bar{S} = \{a_2, b_3, b_4\}$ . What is the cut value returned? What if we start with  $S = \{a_1, a_2\}$ ?



### 3. Tradeoffs

- Explain why there is always a starting solution which causes Local Search to return the optimal solution.
- What if our local move space considered swapping pairs of nodes instead of singletons? What about at most  $k$  nodes each time?