NEURAL NETWORKS

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CS159 – Spring 2024

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Admin

Assignment *5*

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Neural Networks

Neural Networks try to mimic the structure and function of our nervous system

People like biologically motivated approaches

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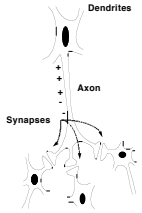
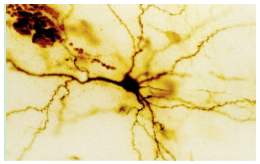
Our Nervous System





Neuron

What do you know?

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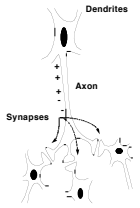
Our nervous system: the computer science view



the human brain is a large collection of interconnected neurons

a NEURON is a brain cell

- they collect, process, and disseminate electrical signals
- they are connected via synapses
- they FIRE depending on the conditions of the neighboring neurons

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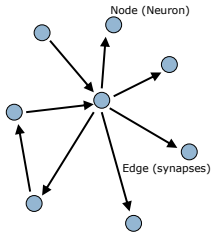
Artificial Neural Networks



our approximation

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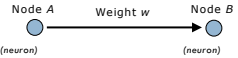

W is the strength of signal sent between A and B.

If *A* fires and *w* is **positive**, then *A* **stimulates** *B*.

If *A fires* and *w* is **negative**, then *A* **inhibits** *B*.

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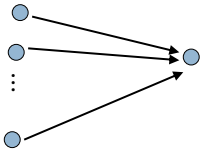

Neurons often have many, many connected input neurons

If a neuron is stimulated enough, then it also fires

How much stimulation is required is determined by its **threshold**

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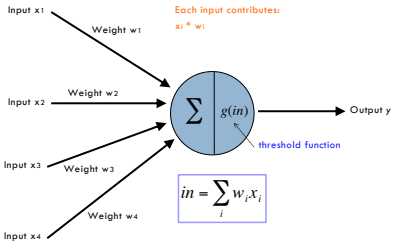
A Single Neuron/Perceptron



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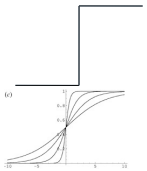
Activation functions

hard threshold:

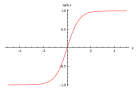
$$g(in) = \begin{cases} 1 & if\ in \geq T \\ 0 & otherwise \end{cases}$$



sigmoid

$$g(x) = \frac{1}{1+e^{-ax}}$$

tanh x



why other threshold functions?

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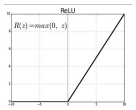
Many other activation functions

Rectified Linear Unit



Softmax (for probabilities)

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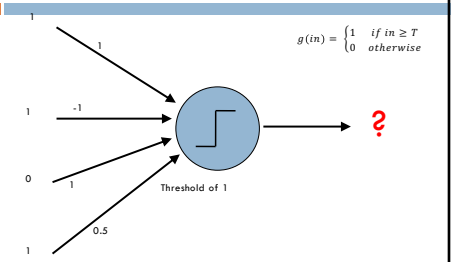
A Single Neuron/Perceptron



$$g(in) = \begin{cases} 1 & if\ in \geq T \\ 0 & otherwise \end{cases}$$

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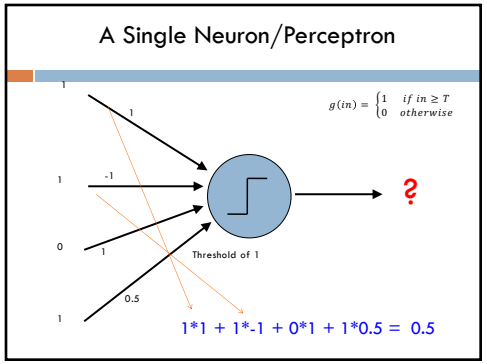
A Single Neuron/Perceptron
$g(in) = \begin{cases} 1 & if\ in \geq T \\ 0 & otherwise \end{cases}$
1
1
-1
1
0
1
0.5
1
Threshold of 1
?
1*1 + 1*-1 + 0*1 + 1*0.5 = 0.5

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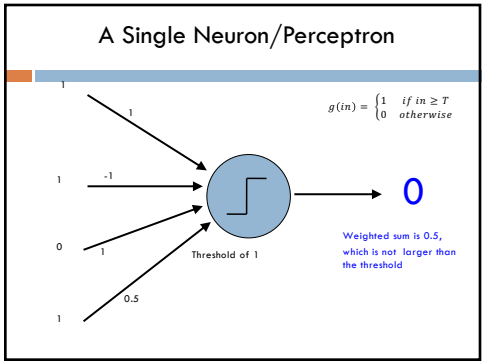
A Single Neuron/Perceptron
$g(in) = \begin{cases} 1 & if\ in \geq T \\ 0 & otherwise \end{cases}$
1
1
-1
1
0
1
0.5
1
Threshold of 1
0
Weighted sum is 0.5, which is not larger than the threshold

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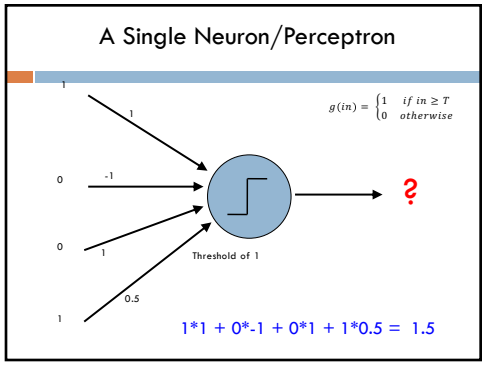
A Single Neuron/Perceptron
$g(in) = \begin{cases} 1 & if\ in \geq T \\ 0 & otherwise \end{cases}$
1
1
0
-1
0
1
0.5
1
Threshold of 1
?
1*1 + 0*-1 + 0*1 + 1*0.5 = 1.5

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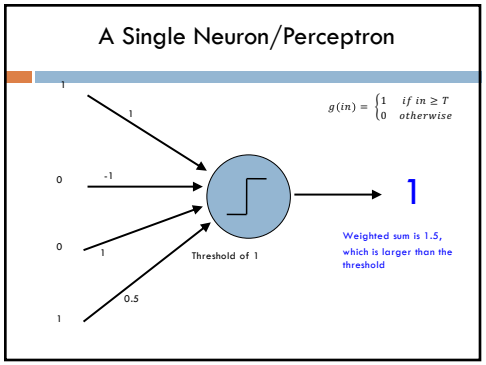
A Single Neuron/Perceptron
$g(in) = \begin{cases} 1 & if\ in \geq T \\ 0 & otherwise \end{cases}$
1
1
0
-1
0
1
0.5
1
Threshold of 1
1
Weighted sum is 1.5, which is larger than the threshold

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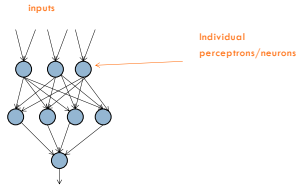
Neural network



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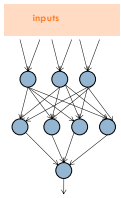
Neural network



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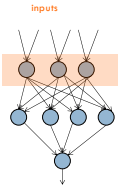
Neural network



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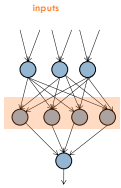
Neural network



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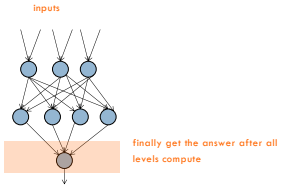
Neural network



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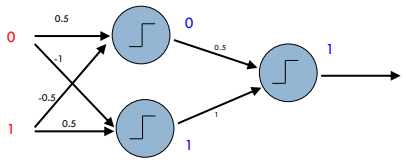
Computation (assume threshold 0)



$$g(in) = \begin{cases} 1 & if\ in \geq T \\ 0 & otherwise \end{cases}$$

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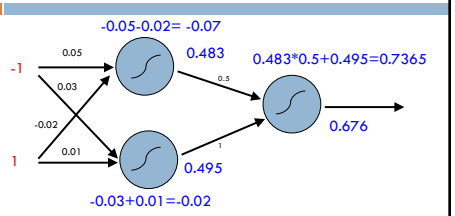
Computation



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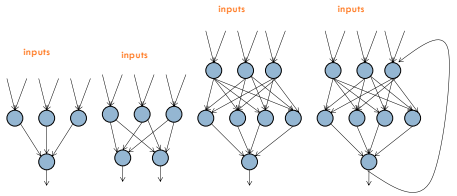
Neural networks

Different kinds/characteristics of networks



How are these different?

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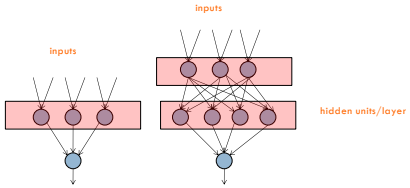
Hidden units/layers



Feed forward networks

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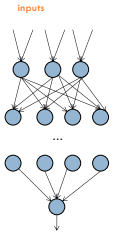
Hidden units/layers



Can have many layers of hidden units of differing sizes

To count the number of layers, you count all but the inputs

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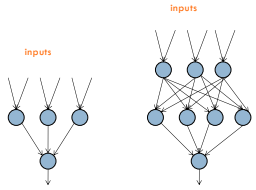
Hidden units/layers



2-layer network 3-layer network

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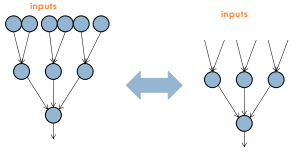
Alternate ways of visualizing

Sometimes the input layer will be drawn with nodes as well



2-layer network 2-layer network

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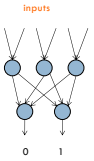
Multiple outputs



Can be used to model multiclass datasets or more interesting predictors, e.g. images

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Multiple outputs

input

output
(edge detection)

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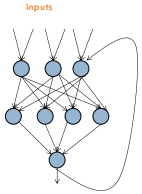
Neural networks



Recurrent network

Output is fed back to input

Can support memory!

Good for temporal data

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History of Neural Networks

McCulloch and Pitts (1943) – introduced model of artificial neurons and suggested they could learn

Hebb (1949) – Simple updating rule for learning

Rosenblatt (1962) - the *perceptron* model

Minsky and Papert (1969) – wrote *Perceptrons*

Bryson and Ho (1969, but largely ignored until 1980s--Rosenblatt) – invented back-propagation learning for multilayer networks

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Training the perceptron

First wave in neural networks in the 1960's

Single neuron

Trainable: its threshold and input weights can be modified

If the neuron doesn't give the desired output, then it has made a mistake

Input weights and threshold can be changed according to a learning algorithm

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Examples - Logical operators

AND – if all inputs are 1, return 1, otherwise return 0

OR – if at least one input is 1, return 1, otherwise return 0

NOT – return the opposite of the input

XOR – if exactly one input is 1, then return 1, otherwise return 0

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AND

x_1	x_2	x_1 **and** x_2
0	0	0
0	1	0
1	0	0
1	1	1

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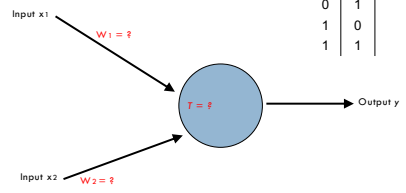
AND

x_1	x_2	x_1 **and** x_2
0	0	0
0	1	0
1	0	0
1	1	1



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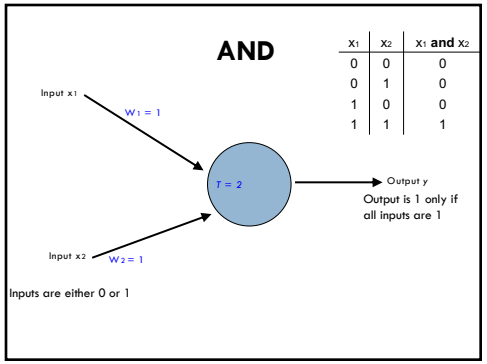
AND
x1 x2 x1 and x2
0 0 0
0 1 0
1 0 0
1 1 1
Input x1
W1 = 1
T = 2
Output y
Output is 1 only if all inputs are 1
Input x2
W2 = 1
Inputs are either 0 or 1

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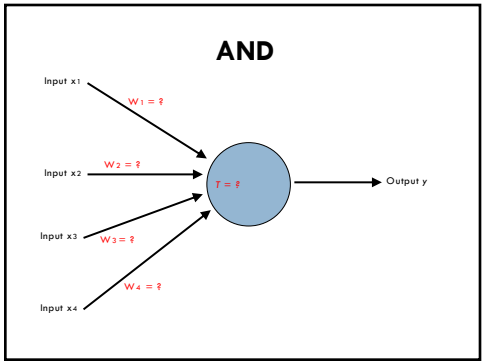
AND
Input x1
W1 = ?
Input x2
W2 = ?
T = ?
Output y
Input x3
W3 = ?
W4 = ?
Input x4

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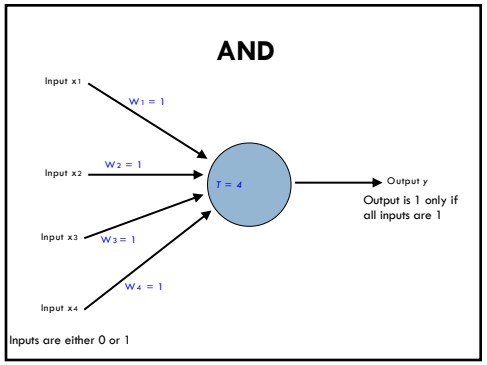
AND
Input x1
W1 = 1
Input x2
W2 = 1
T = 4
Output y
Output is 1 only if all inputs are 1
Input x3
W3 = 1
W4 = 1
Input x4
Inputs are either 0 or 1

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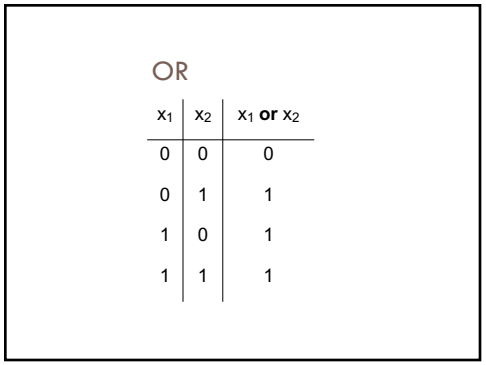
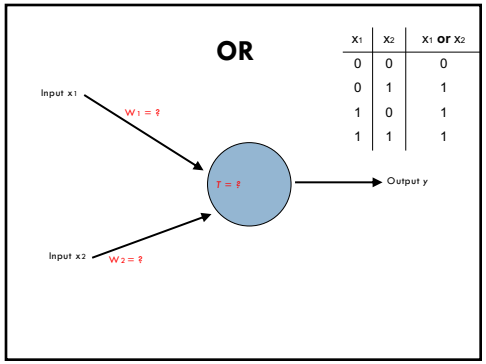

OR
x1 x2 x1 or x2
0 0 0
0 1 1
1 0 1
1 1 1

40


OR
Input x1
W1 = ?
Input x2
W2 = ?
T = ?
Output y
x1 x2 x1 or x2
0 0 0
0 1 1
1 0 1
1 1 1

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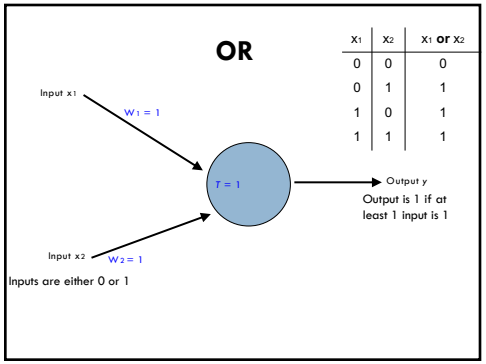
OR
Input x1
W1 = 1
Input x2
W2 = 1
T = 1
Output y
Output is 1 if at least 1 input is 1
Inputs are either 0 or 1
x1 x2 x1 or x2
0 0 0
0 1 1
1 0 1
1 1 1

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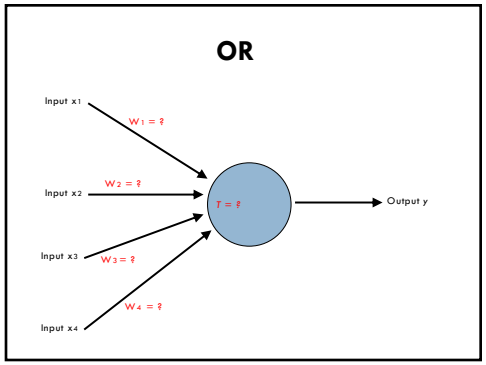
OR
Input x1
W1 = ?
Input x2
W2 = ?
Input x3
W3 = ?
Input x4
W4 = ?
T = ?
Output y

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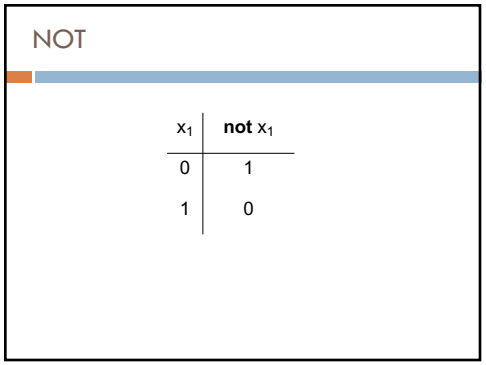
NOT
x1 not x1
0 1
1 0

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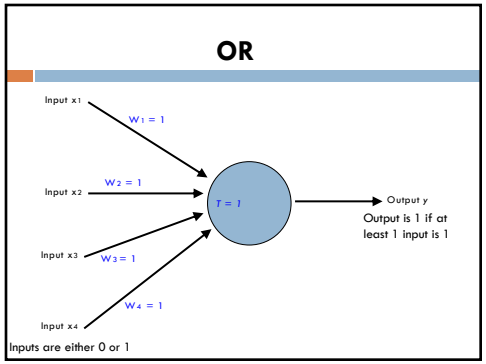
OR
Input x1
W1 = 1
Input x2
W2 = 1
T = 1
Output y
Output is 1 if at least 1 input is 1
Input x3
W3 = 1
W4 = 1
Input x4
Inputs are either 0 or 1

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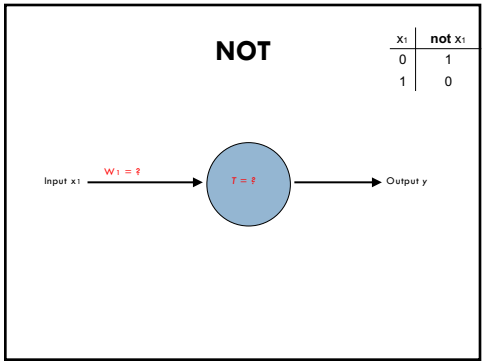
NOT
x1 | not x1
0 | 1
1 | 0
Input x1
W1 = ?
T = ?
Output y

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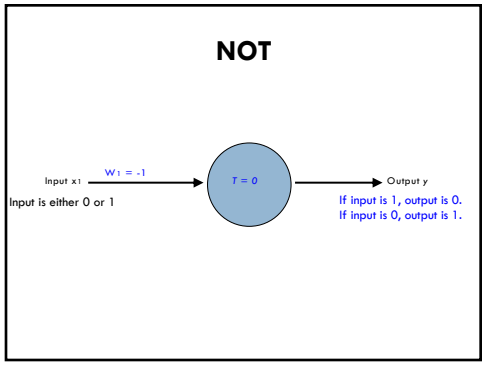
NOT
Input x1
W1 = -1
T = 0
Output y
Input is either 0 or 1
If input is 1, output is 0.
If input is 0, output is 1.

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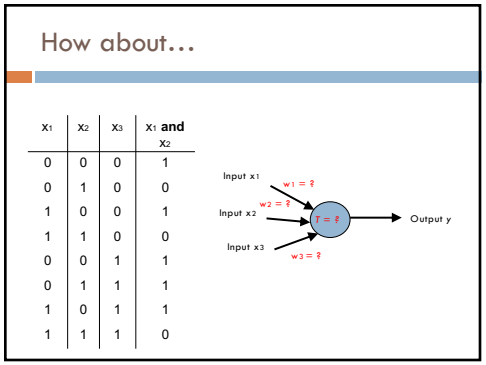
How about…
x1 | x2 | x3 | x1 and x2
0 | 0 | 0 | 1
0 | 1 | 0 | 0
1 | 0 | 0 | 1
1 | 1 | 0 | 0
0 | 0 | 1 | 1
0 | 1 | 1 | 1
1 | 0 | 1 | 1
1 | 1 | 1 | 0
Input x1
w1 = ?
Input x2
w2 = ?
T = ?
Output y
Input x3
w3 = ?

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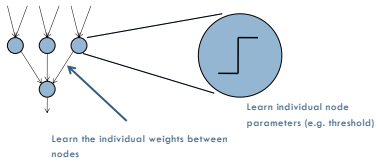
Training neural networks



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Positive or negative?

NEGATIVE

50

Positive or negative?

NEGATIVE

51

Positive or negative?

POSITIVE

52

Positive or negative?

NEGATIVE

53

Positive or negative?

POSITIVE

54

Positive or negative?

POSITIVE

55

Positive or negative?

NEGATIVE

56

Positive or negative?

POSITIVE

57

A method to the madness

blue = positive

yellow triangles = positive

all others negative

How did you figure this out (or some of it)?

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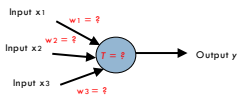
Training a neuron (perceptron)

x_1	x_2	x_3	x_1 and x_2
0	0	0	1
0	1	0	0
1	0	0	1
1	1	0	0
0	0	1	1
0	1	1	1
1	0	1	1
1	1	1	0



1. start with some initial weights and thresholds
2. show examples repeatedly to NN
3. update weights/thresholds by comparing NN output to actual output

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Perceptron learning algorithm

repeat until you get all examples right:

- for each "training" example:
  - calculate current prediction on example
  - if *wrong*:
    - update weights and threshold towards getting this example correct

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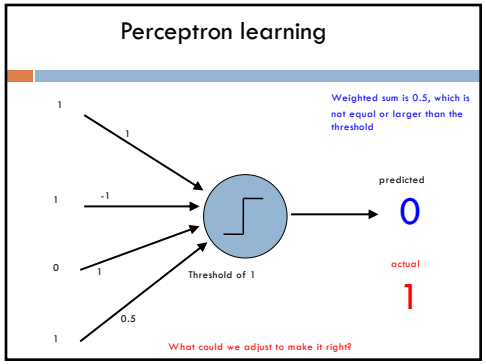
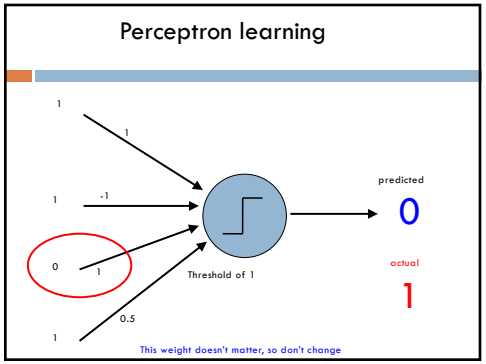
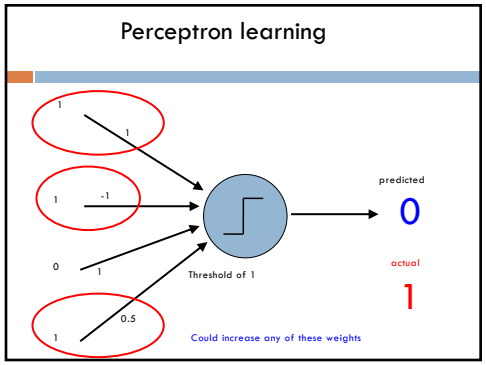

Perceptron learning
Weighted sum is 0.5, which is not equal or larger than the threshold
1
1
1
-1
0
1
1
0.5
Threshold of 1
predicted
0
actual
1
What could we adjust to make it right?

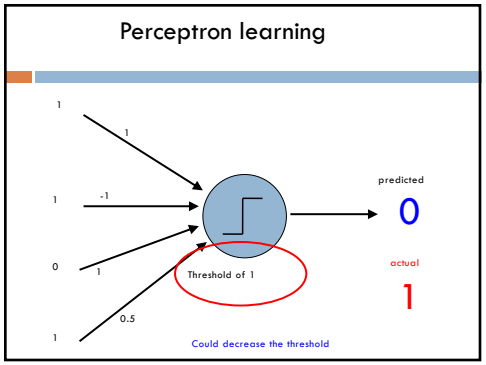
61


Perceptron learning
1
1
1
-1
0
1
1
0.5
Threshold of 1
predicted
0
actual
1
This weight doesn't matter, so don't change

62


Perceptron learning
1
1
1
-1
0
1
1
0.5
Threshold of 1
predicted
0
actual
1
Could increase any of these weights

63


Perceptron learning
1
1
1
-1
0
1
1
0.5
Threshold of 1
predicted
0
actual
1
Could decrease the threshold

64

Perceptron learning

A few missing details, but not much more than this

Keeps adjusting weights as long as it makes mistakes

Run through the training data multiple times until convergence, some number of iterations, or until weights don't change (much)

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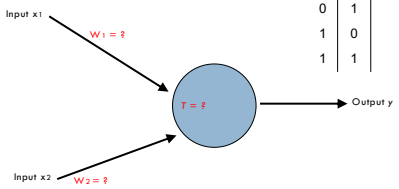
XOR

x_1	x_2	x_1 **or** x_2
0	0	0
0	1	1
1	0	1
1	1	0

66

XOR

x_1	x_2	x_1 **xor** x_2
0	0	0
0	1	1
1	0	1
1	1	0



67

Perceptron learning

A few missing details, but not much more than this

Keeps adjusting weights as long as it makes mistakes

Run through the training data multiple times until convergence, some number of iterations, or until weights don't change (much)

If the training data is linearly separable the perceptron learning algorithm is guaranteed to converge to the "correct" solution (where it gets all examples right)

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Linearly Separable

x_1	x_2	x_1 and x_2
0	0	0
0	1	0
1	0	0
1	1	1

x_1	x_2	x_1 or x_2
0	0	0
0	1	1
1	0	1
1	1	1

x_1	x_2	x_1 xor x_2
0	0	0
0	1	1
1	0	1
1	1	0

A data set is linearly separable if you can separate one example type from the other with a line (plane)

Which of these are linearly separable?

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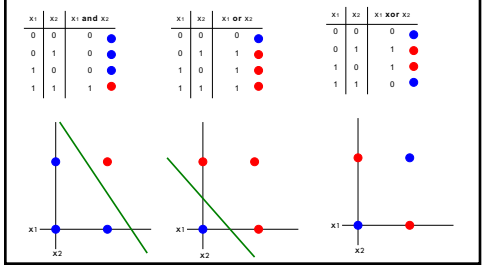
Which of these are linearly separable?



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Perceptrons

1969 book by Marvin Minsky and Seymour Papert

The problem is that they can only work for classification problems that are linearly separable

Insufficiently expressive

"Important research problem" to investigate multilayer networks although they were pessimistic about their value

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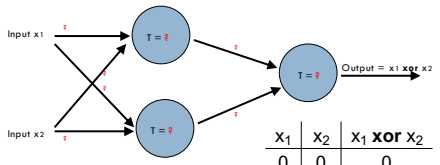
XOR



x_1	x_2	x_1 **xor** x_2
0	0	0
0	1	1
1	0	1
1	1	0

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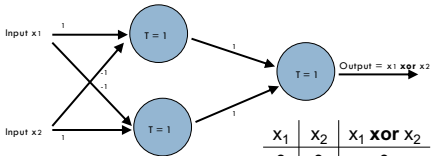
XOR



x_1	x_2	x_1 **xor** x_2
0	0	0
0	1	1
1	0	1
1	1	0

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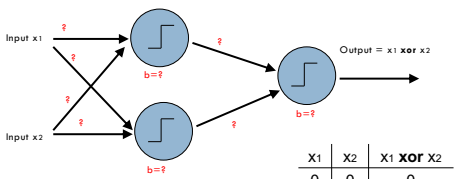
Training



How do we learn the weights?

x_1	x_2	x_1 **xor** x_2
0	0	0
0	1	1
1	0	1
1	1	0

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Training multilayer networks

perceptron learning: if the perceptron's output is different than the expected output, update the weights

gradient descent: compare output to label and adjust based on loss function

Any other problem with these for general NNs?

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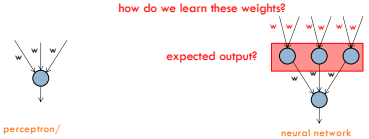
Learning in multilayer networks

Challenge: for multilayer networks, we don't know what the expected output/error is for the internal nodes!



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Backpropagation: intuition

Gradient descent method for learning weights by optimizing a loss function

1. calculate output of all nodes
2. calculate the weights for the output layer based on the error
3. "backpropagate" errors through hidden layers

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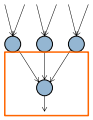
Backpropagation: intuition



We can calculate the actual error here

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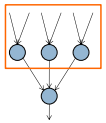
Backpropagation: intuition



Key idea: propagate the error back to this layer

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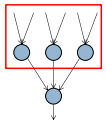
Backpropagation: intuition



"backpropagate" the error:

Assume all of these nodes were responsible for some of the error

How can we figure out how much they were responsible for?

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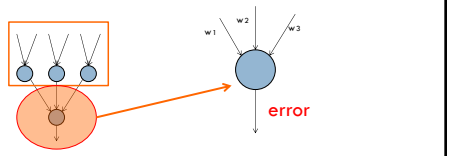
Backpropagation: intuition



error for node is ~ w_i * error

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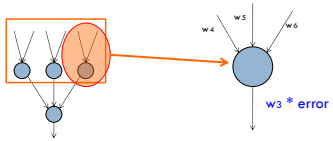
Backpropagation: intuition



Calculate as normal using this as the error

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